

deflection, then

$$W(\text{work stored in the spring}) = \int_0^y Ky = \frac{K}{2} y^2$$

where  $y$  = the limiting deflection of the spring. Thus, if we re-arrange the equation

$$f = \frac{PL^3}{3EI}$$

to the form

$$\frac{3EI}{L^3} = \frac{P}{\delta} = K = \frac{3\pi E d^4}{32 L^3}$$

we find that

$$K = \frac{3\pi (26 \times 10^6 \text{ psi}) (1/4)^4}{32 (2)^3} = 117500 \text{ lb/in.}$$

and if the spring is compressed by a deflection of 0.00924" it will be

$$\frac{1}{2} (117500 \text{ lb/in.}) (0.00924)^2 = 5.08 \text{ in.-lbs.}$$

$$\frac{5.08 \text{ in.-lbs.}}{1/2 \text{ in.}} = 10.16 \text{ lb.}$$

if spring. This would double the weight of the hammer

$$10.16 = \frac{W}{2(32)}$$

$$\left[ \frac{2(10.16)}{32} \right]^{1/2} = 0.79 \text{ sec.} = 1.56 \text{ rad./sec.}$$

now, the spring is not free to move. It would mean that the task of the hammer would be to produce the desired frequency of 150.8 rads. per sec. The hammer would stop after which the hammer would take part of the force of the spring and move slowly to a full stop.

Assuming the use of a 1/8" diameter hammer head and assuming a new spring. Before Spring #2 is properly positioned for black and-white camera, the hammer is placed to the right of the second positioning assembly.



The velocity of the Drive #2 assembly at the end of the above mentioned 120° travel can be determined by applying the formula:  $v = at$  the specified motor to the computed required motor, to the acceleration on which the computed motor is based. Since the computed required motor would raise the speed of the Drive Assembly from zero to 150 ft/sec in 60 sec, or an acceleration of:

$$150 \text{ ft} = \frac{1}{2} a (60)^2$$
$$\frac{150 \text{ ft}}{900} = \frac{1}{2} a$$
$$a = 5.03 \text{ ft/sec}^2$$

Using a 150 ft motor in the place of the 0.125 computed requirement, we may find:

$$\left( \frac{150 \text{ ft}}{0.125 \text{ ft}} \right) [5.03 \text{ ft/sec}^2] = 5.78 \text{ ft/sec}^2$$

With the motor at 150 ft, the required motor would supply the 120° arc of travel in 57.1 sec.

$$\frac{120}{57.1} (2\pi) = \frac{4}{3} \pi \text{ radians}$$

The required angular acceleration of 5.78 ft/sec<sup>2</sup> would be applied to the assembly with a 2 in. of 10.4 ft.  $\pi$  in. with the rotating of the Drive Assembly. The 2 in. is involved, meaning that the acceleration of 10.4 ft.  $\pi$  in. (assuming the same motor output) is required.

$$65 (5.78) = 376.7 \text{ ft/sec}^2$$

By

$$s = \frac{1}{2} at^2$$

$$\frac{4}{3} \pi = \frac{1}{2} (11.96) (t^2)$$

$$t = \sqrt{\frac{\frac{4}{3} \pi \times 2}{11.96}} = 0.511 \text{ sec}$$

Therefore, the motor should be able to handle the 120° arc of travel in 0.511 sec.

$$\frac{1}{2} at^2 = \frac{1}{2} (11.96) (0.511)^2 = 1.54 \text{ ft/sec}^2$$

Would be the same velocity at the conclusion of the arc of travel. The fact that the motor is able to handle the 120° arc of travel in 0.511 sec with respect to Drive #2 may be dropped. The two curves given



of the two functions which the latch serves: - (1) firstly, it serves to stop and position Drum #2 with respect to Drum #1, when black-and-white viewing is intended; and (2) it is the means by Drum #1 is motivated along with Drum #2 in color-viewing. In stopping Drum #2 after Drum #1 has already been positioned, it must absorb the flywheel energy of Drum #2. This would mean, since  $\Sigma m r^2$  for each Drum has been taken at 50.5 lb.-ft<sup>2</sup>, that

$$\frac{(50.5 \text{ lb.-ft}^2)}{(32 \frac{\text{ft}}{\text{sec}^2})} (3.5 \text{ rad/sec}) = 0.382 \text{ ft-lb.}$$

of energy absorbed here to be absorbed. By reference to the previous calculations concerning the two wheel functions Drum #1, it is clear that a member with a rotational inertia equal to a 1/2 lb. would absorb more than sufficient for the purpose, if it were rotating at the same angular velocity. This is a reasonable assumption for the design of the latch member, it would be sufficient to absorb the energy to transmit a torque equal to

$$\frac{(10.1 \text{ lb.-ft}^2)}{(32 \frac{\text{ft}}{\text{sec}^2})} (5 \text{ rad/sec}) = 0.771 \text{ ft-lb.}$$

$$(10.1 \text{ ft-lb}) (12 \frac{\text{in}}{\text{ft}}) = 121.45 \text{ in.-lb.}$$

absorbed by the latch. Assuming this is later to be taken on about a 15° radius from the axis of rotation, the torque indicated above implies a load of

$$\frac{121.45 \text{ in.-lb.}}{19 \text{ in.}} = 6.39 \text{ lb.}$$

applied at the end of the latch. Now the latch is 2" long, this would mean the loading for bending load of

$$(6.39 \text{ lb.}) (2) = 12.78 \text{ in.-lb.}$$

which is a fairly insignificant amount, and worthy of no further computations.

Summing up the function of the shifting key when the Drums are motivated. One consideration of the loader involved, it is practical from a superficial observation, to look in terms of a cantilever supporting moment of the Drums from one end as per the figure below:-



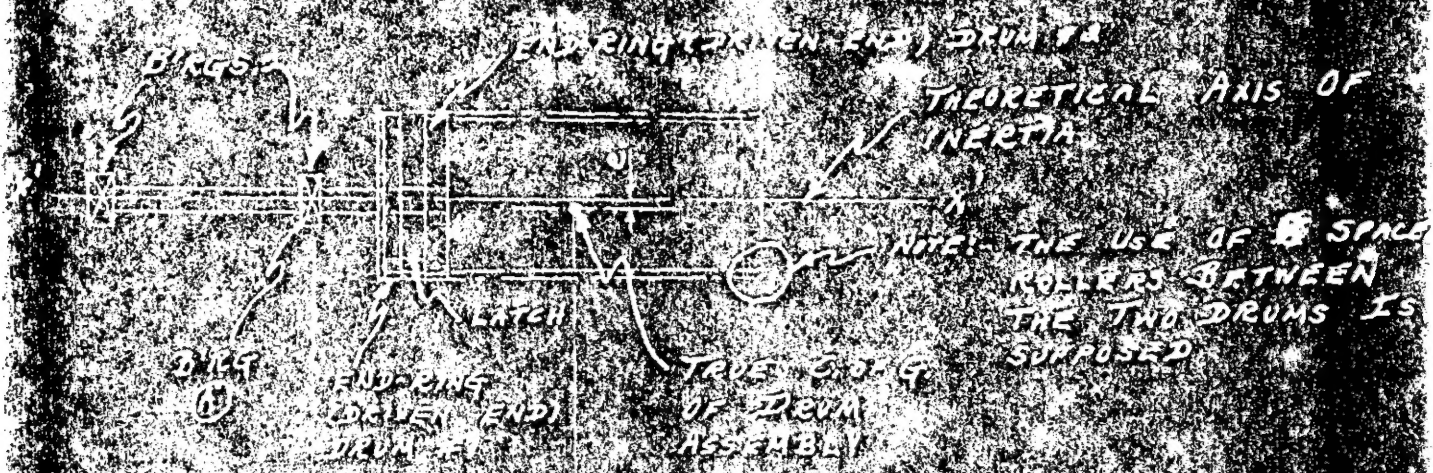


FIG. 9

The path of the center of the double drum assembly is considered as a single curve. The end of a shaft is parallel to the length of the shaft being taken as parallel to the axis between Fig. 9 and the true center of gravity of the combined drum assembly. The use of space rollers as indicated contributes towards the stability of the assembly.

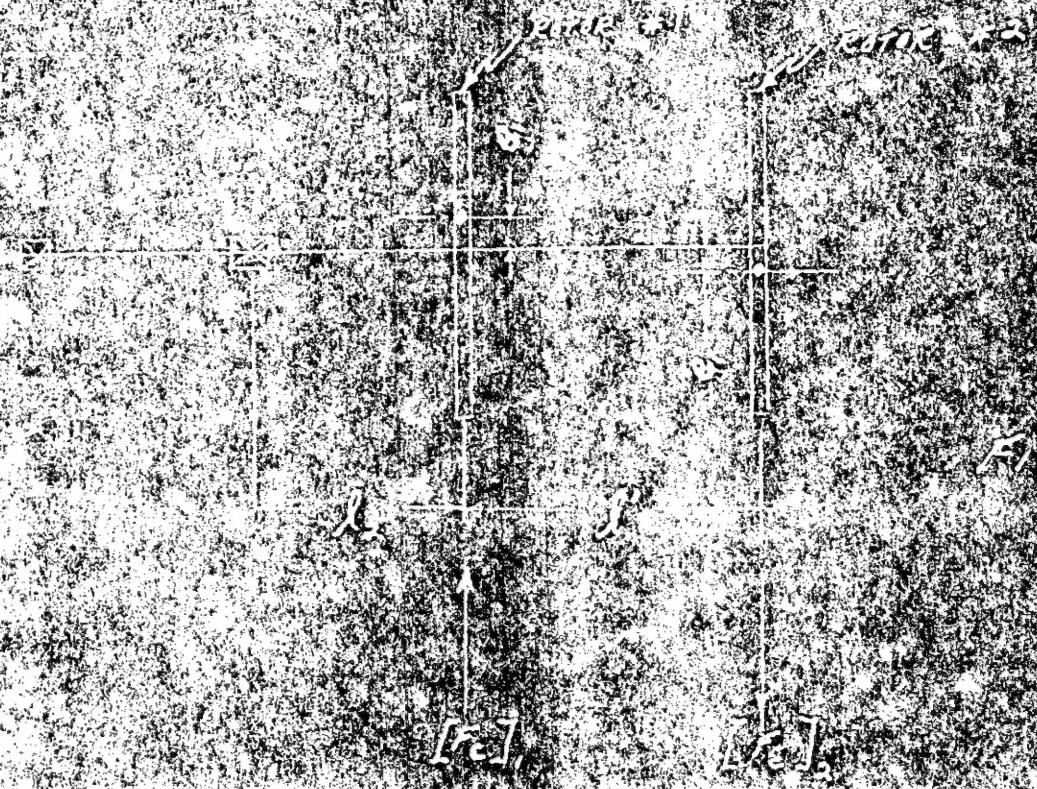


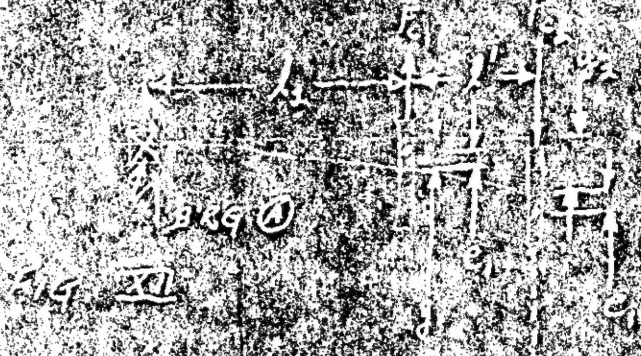
FIG. 10







departure of different from the previous energy transfer of different magnitude at  $x = l_1$  and  $x = l_2$ . Since the different magnitude would alter the relative magnitude of  $(F_1)$  and  $(F_2)$  the graph would be destroyed; and the particular process would not then be as previously below:-



as the energy is transferred in which the force  $(F_1)$  and  $(F_2)$  can be related according to the

$$\frac{(F_1)(l_1 + l_2) - (F_2)l_1}{(K_1 + 1)} = F_2$$

with a constant force  $(F_2)$  acting at a distance  $(l_1 + l_2)$  from the origin. The mass acting in any section of the beam would then be given by:-

$$m = F_2 (l_1 + l_2) = \frac{F_2}{g} \frac{u^2}{a^2}$$

where after performing the integration we obtain the formula

$$I = \frac{F_2}{EI} \left( \frac{(l_1 + l_2)^2}{2} - \frac{l_1^2}{2} \right)$$

Therefore the slope at the origin depending on  $K$  value

$$K = \frac{EI}{\left( \frac{(l_1 + l_2)^2}{2} - \frac{l_1^2}{2} \right)}$$

Thus by using the formula that

$$F_2 = \frac{W}{g} (1 - e^{-Kx})$$



and

$$F_2 = \frac{W}{g} (g_2 + e_1) \omega^2$$

Similarly also

$$F_1 + F_2 = K y_2$$

we may write

$$\frac{W}{g} (g_1 - e_1) \omega^2 + \frac{W}{g} (g_2 + e_1) \omega^2 = K y_2$$

we will solve for

$$\omega^2 (g_1 + g_2) = \frac{K}{W} y_2$$

$$\frac{\omega^2 y_2}{K} = \frac{y_2}{W} = \frac{1}{\frac{K}{W}} = 1$$

The significance of the final question is -

1) as  $\omega$  approaches  $(\frac{K}{W})^{1/2}$  in value,  $y_2$  would attain extremely large values becoming infinite when  $\omega^2 = \frac{K}{W}$   
2) the shaft would fail

and

3) since  $y_1$  is expressed in terms of  $y_2$  with  $[\frac{K}{W} - 1]^{-1}$  as a multiplier of  $y_2$ , it is clear that when  $\omega^2 = (\frac{K}{W})$  but approach the latter is infinitesimal, i.e. the portion of the shaft between Rotor #1 and the critical section, while, when  $\omega^2 = [\frac{K}{W}]$ , the force that rotor become

$$y_2 = \frac{y_1}{1 - \frac{K}{W}}$$

means that the action of the shaft above Rotor #1 become the critical portion

The critical portion of shaft is equally susceptible of resonance, but while we are all susceptible of resonance, should be considered as two independent systems. One with the load just below the engine, another load would be placed at the other end of the shaft supporting the two rotors. When the two rotors are at the ends of the shaft, the shaft connecting the two rotors is the shaft between the two rotors and is called the dynamic relationship.



$$E = +C - 2ABC + Dg = 0 + 0.04 - 0 + 0 = 0.04$$



$$k = \frac{1}{2} \sqrt{40 - 10} = \frac{1}{2} \sqrt{30} = 0.143$$

$$l = \frac{1}{2} \left[ \sqrt{h + (h^2 + k^2)^{1/2}} + \sqrt{h - (h^2 + k^2)^{1/2}} \right] =$$

$$= \frac{1}{2} \left[ \sqrt{0.04 + (0.0016 + 0.0029)^{1/2}} + \sqrt{0.04 - (0.0016 + 0.0029)^{1/2}} \right] =$$

$$= \frac{1}{2} \left[ \sqrt{0.04 + 0.164} + \sqrt{0.04 - 0.164} \right] =$$

$$0.102 + 0.071 = 0.176$$

$$u = g + l = 0 + 0.176 = 0.176$$

$$v = h + k = 0 + 0.176 = 0.176$$

$$w = h + u + 5k - 12gl = 4(0.176) + 3(0.143) - 12(0) =$$

$$= 1.031 + 0.429 = 0.127 + 0.429 = 0.556$$

Using the same method we get:

$$d_1 = -h + u \sqrt{2} + (v + w \sqrt{2})^{1/2}$$

$$d_2 = -h + u \sqrt{2} + (v - w \sqrt{2})^{1/2}$$

$$d_3 = -h + u \sqrt{2} - (v + w \sqrt{2})^{1/2}$$

$$d_4 = -h + u \sqrt{2} - (v - w \sqrt{2})^{1/2}$$

$$d_1 = -0 + 0.176 \sqrt{2} + (0.176 + 0.556 \sqrt{2})^{1/2} = 0.42 + (0.176 + 0.782)^{1/2}$$

$$= 0.42 + 1.934^{1/2} = 0.42 + 1.966 = 0.386$$

By inspection, the four other roots would lie in the realm of imaginary or irrational values. Checking:

$$d_2 = 0 + d = 0.13 = 0$$

~~same method~~

$$1.576 - 0.7(1.356) = 0.45 = 0$$

$$3.64 - 1.038 = 0.43 = 0$$

and the same value is correct. Taking (2) as follows:-

$$l = \frac{1}{2} \left[ \sqrt{h + (h^2 + k^2)^{1/2}} + \sqrt{h - (h^2 + k^2)^{1/2}} \right] =$$

$$= \frac{1}{2} \left[ \sqrt{0.04 + 0.164} + \sqrt{0.04 - 0.164} \right] =$$



$$= \frac{1}{2} [0.204 - \frac{1}{2}(0.124)] = [0.204 - 0.062] / 2 =$$

$$= \frac{1}{2} [0.142] = 0.071$$

$$u = 0.071$$

$$v = 0.071$$

$$w = 4(0.071)^2 + 0.43 = 4(0.005) + 0.43 =$$

$$0.02 + 0.43 = 0.45$$

$$d_1 = 0.071^{1/2} + (0.071 + 0.45)^{1/2} = 0.276 + (0.071 + 0.45)^{1/2}$$

$$= 0.276 + 0.741^{1/2} = 0.276 + 0.86 = 1.136"$$

Check

$$d_1^2 - 0.86 - 0.43 = 0$$

$$1.06 - 0.86(1.136) = 0.43 = 0$$

$$1.06 - 0.9088 = 0.43 = 0$$

Again, taking

$$1 = \frac{1}{2} [h + (h^2 + k^2)^{1/2}] + \frac{1}{2} [h - (h^2 + k^2)^{1/2}] =$$

$$\frac{1}{2} [0.204] + \frac{1}{2} [-0.124] = 0.102 - 0.062 = 0.04$$

$$u = 0.04$$

$$v = 0.04$$

$$w = 4(0.04)^2 + 0.43 = 4(0.0016) + 0.43 =$$

$$0.0056 + 0.43 = 0.4356$$

$$d_1 = 0.04^{1/2} + (0.04 + 0.4356)^{1/2} =$$

$$0.2 + (0.04 + 0.4356)^{1/2} = 0.2 + 0.7^{1/2} =$$

$$0.2 + 0.835 = 1.035"$$

Check

$$d_1^2 - 0.86 - 0.43 = 0$$

$$1.07 - 0.86(1.035) = 0.43 = 0$$

$$1.07 - 0.8908 = 0.43 = 0$$

The answer may be taken to be within the limits of slide-rule accuracy; and we would not need a call & shift, if all other design factors check, as the normal standard.



We previously found the torque accelerating the drum to be of the order of 22.75 in.-lbs. Taking the "shock-torque" to be 1.5 times the value, according to Eq. 56 of "Shifting From A Dynamic Vibration",

$$22.7 \left[ \frac{1.5}{4} \right]^{1/5} = 22.7 \left[ \frac{22.75(1.5)}{12(10^6)} \right]^{1/5} =$$

$$0.227 \left[ \frac{33.675}{12} \right]^{1/5} = 0.227(1.415) = 0.321 \text{ in.}$$

shaft stress is required to yield not more than a 10/20 diameter of shifting shaft. Finally, we find, by Eq. 58 of "Shifting From A Dynamic Vibration",

$$\frac{32 M_e}{\pi d^3} = S_s$$

where  $M_e = 10$  in.-lbs. torque and  $d = 1.125$  in. (as previously suggested)

$$\frac{10(1.5)(10^3)}{\pi(1.125)^3} = \frac{12.1(10^3)}{\pi(1.42)} = 121 \text{ psi}$$

which gives the shear stress due to torque. The combined stress due to torque and bending would then be:

$$\left[ 15,000 + 121 \right]^{1/2} = \left[ 2.25(10^4) + 147(10^4) \right]^{1/2} =$$

$$15,410 \text{ psi}$$

and hence the 1 1/2 diameter shaft satisfies the principle design condition. It is necessary check the value of resonance speed which we should expect. The resonance speed is given by  $\left[ \frac{k_g}{W} \right]^{1/2}$  according to Eq. (2) of "Shifting From A Dynamic Vibration". Since

$$k = \frac{3EI}{L} = \frac{3(30 \times 10^6)(\pi)(1.125)^4}{64(14)} =$$

$$\frac{14(10^6)(\pi)(1.125)}{64(2720)} = 2210 \text{ lb/in.}$$

then

$$\left[ \frac{k_g}{W} \right]^{1/2} = \left[ \frac{2210(3841)}{10.17} \right]^{1/2} = [83500]^{1/2} = 914 \text{ cycles per } 2\pi \text{ sec.}$$



Ry

$$g = \frac{e}{\frac{w_i}{w_o} - 1}$$

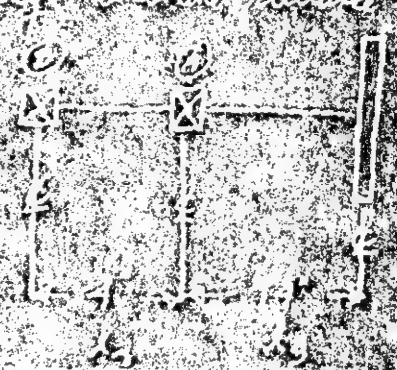
as per Eq. (8) of Vibration from a Dynamic Vibration,

$$\frac{e}{\left(\frac{w_i}{w_o}\right) - 1} = \frac{e}{36.1 - 1} = \frac{e}{35.1}$$

and from Eq. (9) of ibid.

$$\frac{2.57}{35.1} = 0.0732$$

The  $g$  is the  $g$  factor of the bearing, and  $g$  is  $g$  factor - assume a  $g$  factor of 1.0. The distance between the two main bearings



The required spring requirement, at a distance of 1.55 ft. The moment which must be resisted at the given point should be

$$M = S L = 3.14 \times 1.55 = 4.87 \text{ ft-lb}$$

$$\frac{15,000(1.55)}{32} = \frac{15,000(1.55)}{32} = 726.56 \text{ ft-lb}$$

Spring moment at (A)

$$\frac{M}{L} = \frac{4.87}{1.55} = 3.14 \text{ ft-lb} = \text{load on brg. (A)}$$

Spring moment at (B)

$$\frac{M}{L} = \frac{4.87}{1.55} = 3.14 \text{ ft-lb} = \text{load on brg. (B)}$$

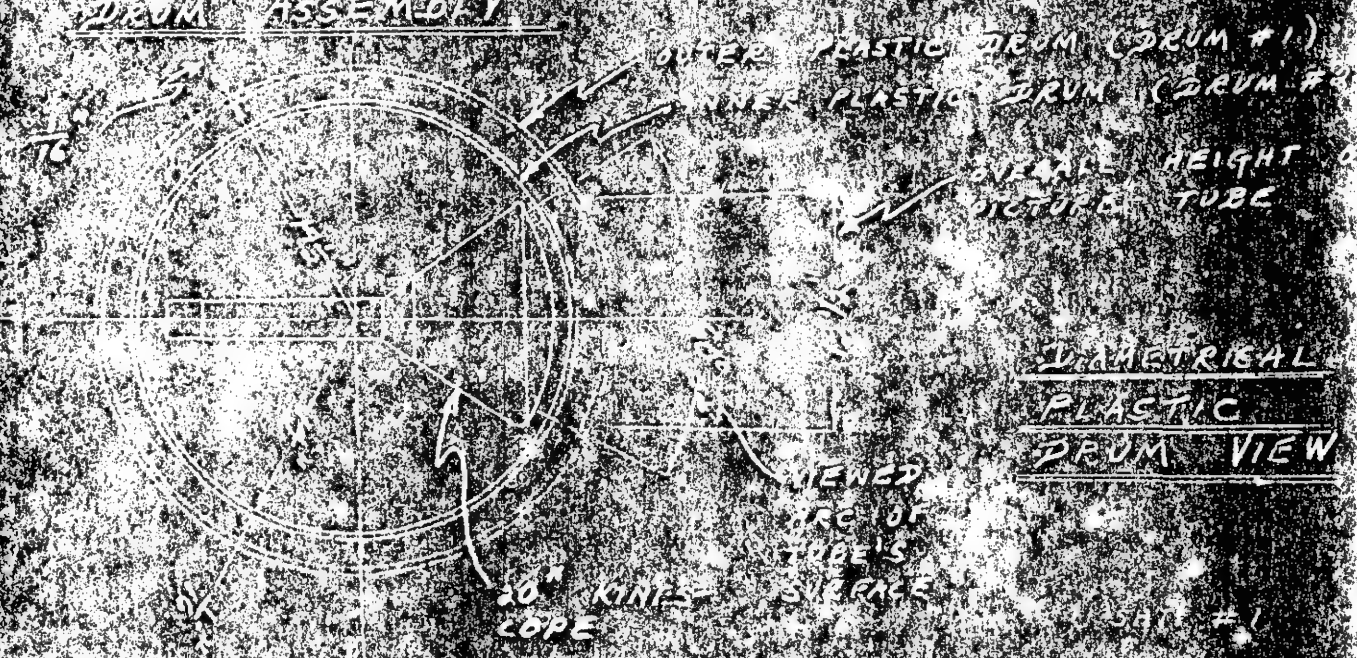
The moment at the principal completion point other as will be required will follow as part of the design computations.



# LAYOUT SKETCHES FOR 20" TUBE



SCHEMATIC SHOWING ARRANGEMENT  
OF FILTER SECTORS ON DOUBLE  
DRUM ASSEMBLY





FILTER SECTION "A"

GRIND JOINING EDGES OF LUCITE SHEETS TO INDICATED BEVEL XS; LEAVE GRD EDGES ROUGH AND FILL IN WITH DENTAL POLY-METHACRYLATE POLYMER PASTE

FILTER SECTION "B"

PREPARATION OF LONGITUDINAL SEAMS BETWEEN FILTER SECTIONS - BOTH DRUMS

GRIND BUFF & POLISH PERIPHERAL SURFACE OF WHEEL

6- EQUIDISTANT 1/2" R2, #2 MACH. SCREWS PER SECTOR TO DRIVEN END RING

6- LUCITE BRG DRIVERS

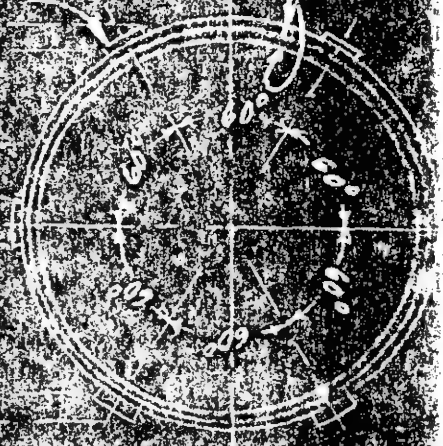
LUCITE END R2 1/8" THK 2 1/2" LG. WEL TO DRUM INST

DRIVEN END

FILTER SECTION

FILTER SECTION

FILTER SECTION



18 1/2" 14 1/8" 6.2"

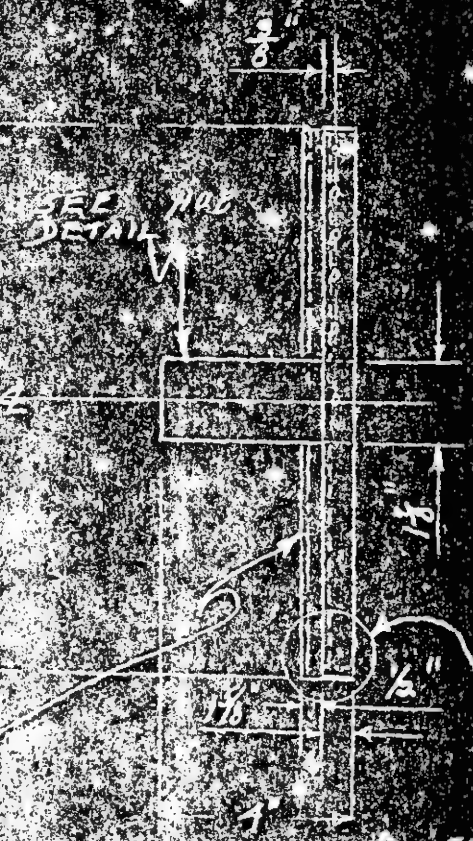
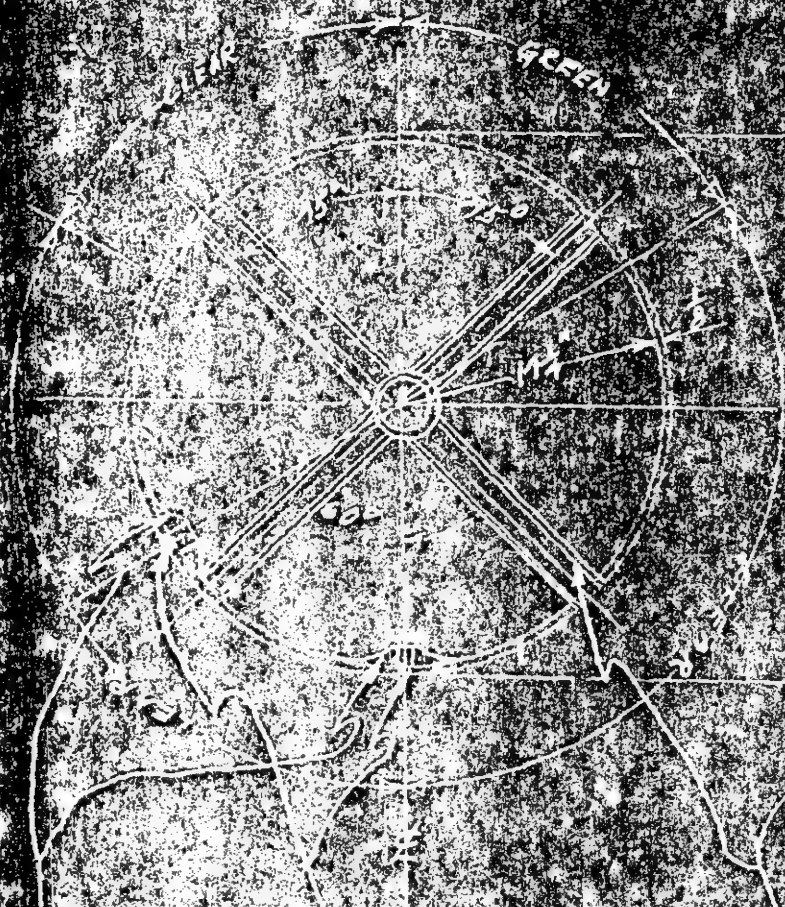
EXTERNAL PROJECTED HEIGHT OF FILTER SECTION

18 1/2"

DRUM #2 1 SIDE ELEVATION & R.H. END VIEWS

SEP 1947



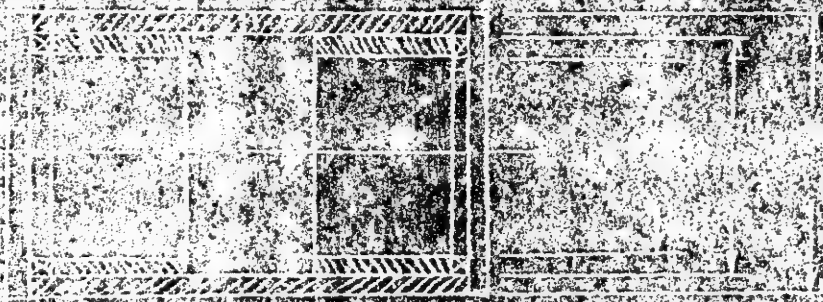


PAUL-GRAB  
DEVICE-SEE  
DETAILS

1/4" DEPTH x 1/4" RISE  
1/8" 0. NEEDED TO  
R.H. 1/4"

1/4" DOWELS  
SEE PAUL-GRAB  
DEVICE DETAIL

SEE  
DETAIL  
1/4"

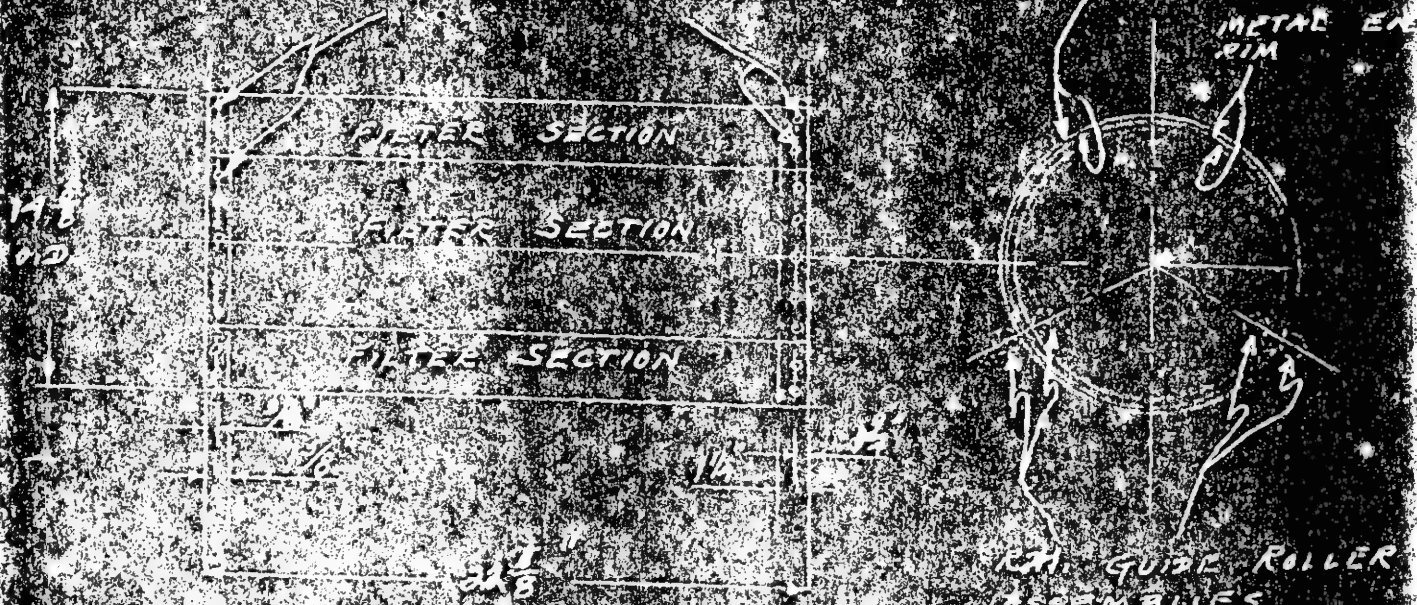




6 EQU-SPACED 3/8" ID  
 1/2" DIA. SCREENS PER  
 60° SECTOR TO END-RINGS

PLASTIC DRUM

METAL END RIM



R.H. GUIDE ROLLER ASSEMBLIES

DRUM #1 (SIDE ELEVATION & R.H. END VIEWS)



DRILL & TAP CIRC-  
 FERENCE  
 FOR 1/8" SCREWS  
 PER SH

BORE HUB  
 FOR 1/8" SHAFT

1/4" DIA. 8  
 1/8" NEEDED  
 TO ADD 4 RIM

WHEEL ROLLER  
 MECHANISM

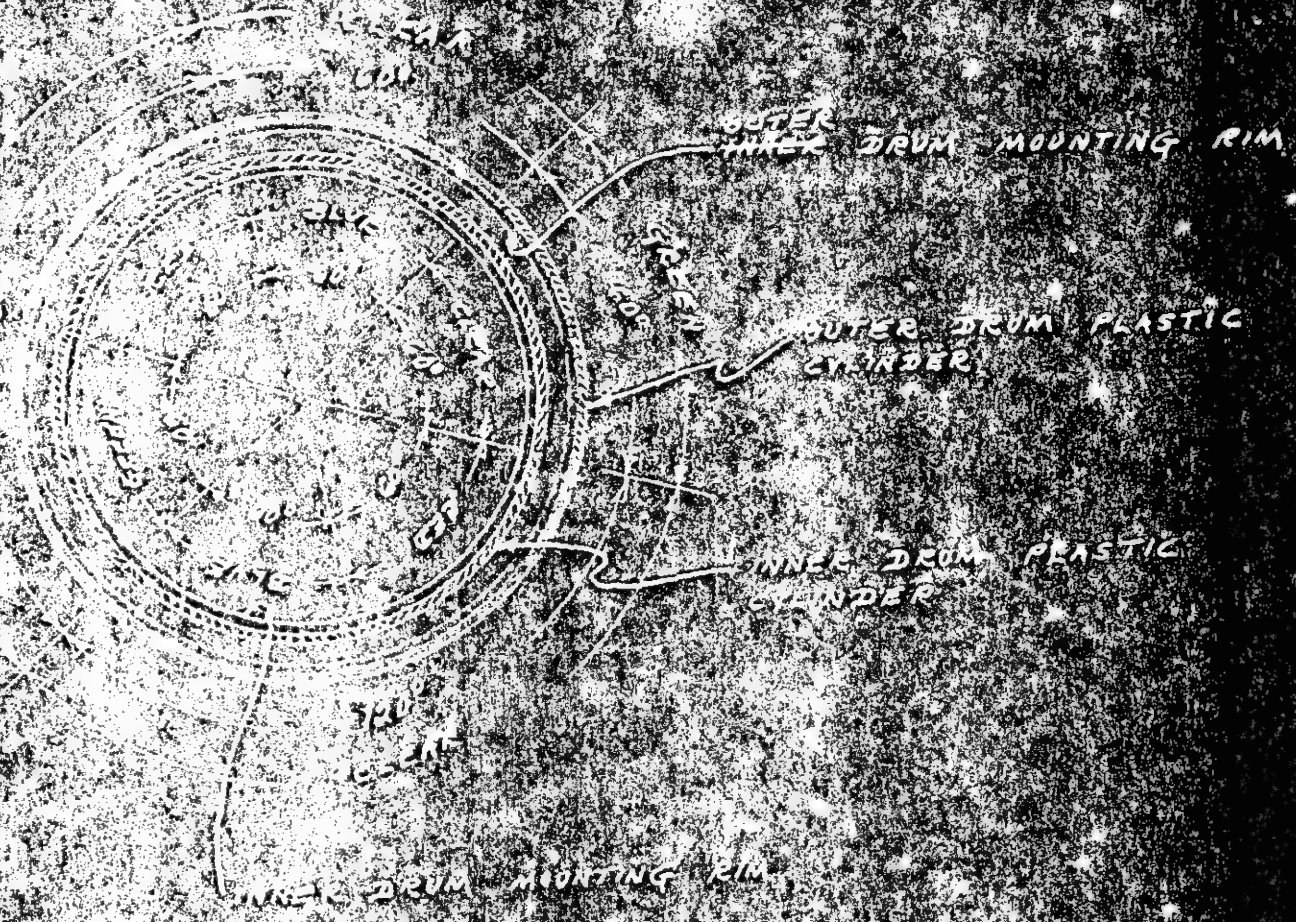
WHEEL ROLLER MECHANISM

DRUM #2 DRIVEN

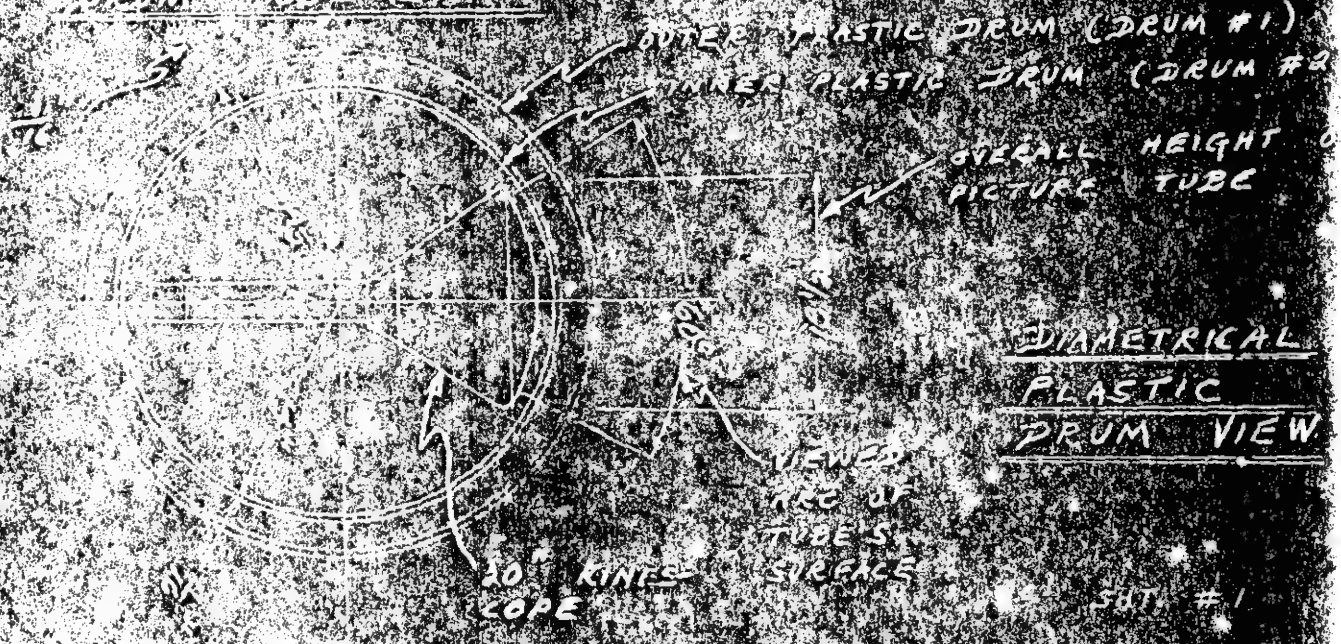
END RING



# SKETCHES FOR 30" TUBE



## SHOWING ARRANGEMENT OF FILTER SECTORS ON DOUBLE DRUM ASSEMBLY





FILTER SECTION "A"

GRIND ADJOINING EDGES OF LUCITE SHEETS TO INDICATED BEVEL 45; LEAVE GRD EDGES ROUGH AND FILL IN WITH DENTAL POLY-METHACRYLATE POLYMER PASTE

FILTER SECTION "B"

PREPARATION OF LONGITUDINAL SEAMS BETWEEN FILTER SECTIONS BOTH DRUMS

GRIND BUFF & POLISH PERIPHERAL SURFACE OF WHEEL

6 LUCITE BRG BLOCKS

LUCITE END RS. 1/8" THK 3/4" LG. WELD TO DRUM INS

6 EQUISPACED 3/8" RD. HD. MACH. SCREWS PER SECTOR DRIVEN END RING

DRIVEN END

FILTER SECTION

FILTER SECTION

FILTER SECTION



28 1/2" 14 1/8" 0.2"

EXTERNAL PROJECTED HEIGHT OF CHAMFER FILTER SECTION

18 1/2"

DRUM #2 (SIDE ELEVATION & R.H. END VIEWS)

DRUM #2



6-EQUI-SPACED 8 R. H.  
H2 MACH. SCREWS PER  
60° SECTOR TO END RINGS

PLASTIC J

MET  
RING

1/4" x 3/8"  
1/2"

FILTER SECTION

FILTER SECTION

FILTER SECTION

1/4"  
1/8"

1/4"  
1/8"

1/4"  
1/8"

R.H. GUIDE R  
ASSEMBLIES

DRUM #1 (SIDE ELEVATION & R.H.  
END VIEWS)

BLK

3/8"

3/4" x 3/8"  
WELDED  
HUB & RIM

200#  
FOR  
SHAFT

3/4"

1/4" x 3/8"  
WELDED  
HUB & RIM

1/8"

3/4"

1/4" x 3/8"  
WELDED  
HUB & RIM

DRUM #2 DR  
END-RING



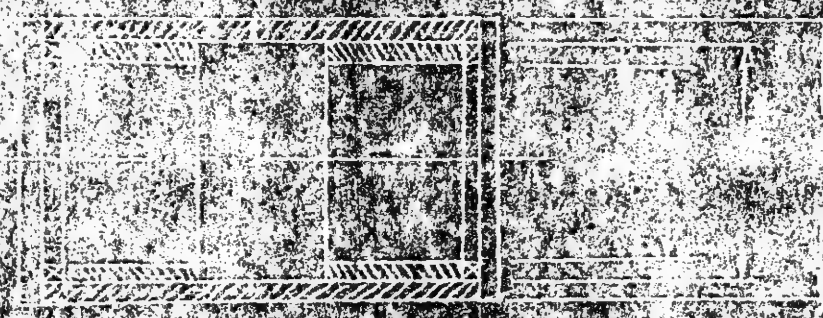


24-9-10  
DRILLS (SEE  
DETAIL)

1/2" DEPTH 1/2" TIGE  
X 6" WELDED TO  
PIN & HUB

1/4" DRILLS  
(SEE PIN & HUB  
DETAIL)

SEE  
DETAIL  
1/4"





To Joe F

Re "Ketchikan" Job

Go on daily the enclosed papers

Photostat sent on previous returning photo

MAIL IMMEDIATELY signals to PORT JENIS,  
marked passed, att. NORMAN

But photostat copy to SIXES LIOZ, only  
If he's gone on vacation or is going on vacation  
I wait work on same until he comes back, then  
my own man going come to him. But I will  
ask him to put, if possible, sufficient time in, in order  
the get started

Ask NORMAN to get Patent work started on this



To Joe F

Re Projector Job

Comm. Only the enclosed papers.

PHOTOSTAT SAME on premises, retaining photos

Mail IMMEDIATELY original to Port Jervis,

marked personal, att. NORMAN

See photostat copy to SIDNEY LIOZ, only

If he's gone on vacation or is going on vacation

I wait work on same until he comes back, then

re-sure we give some to him. But I don't

like him to put off possible, sufficient time in, or on

the photostat

Put NORMAN to get stat work started on this



BULKY EXHIBIT

Date received 6/30/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained Warden E. E. Thompson

Address Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Ultimate disposition to be made of exhibit Retained

Estimated date of disposition - To be decided at conclusion of case

List of contents:

125. Two letters addressed to

OSCAR THALER,  
45 Crosby Street  
New York City

73

100-95068-1B  
SEARCHED INDEXED  
SERIALIZED FILED  
JUL 1 1951  
FBI - NEW YORK  
JUL 1 1951  
JUL 1 1951



10

10

19

1000 7/11/46

1000 013450

1000 12, 11/4



## TELEVISION AND RADIO

### Liquidation Sale Satisfies Pathe

CHICAGO, June 24.—"Complete satisfaction" with results of the liquidation sale of 2 million dollars worth of Pathe and Freed-Eisemann television sets and radios was expressed today by Sidney Joffe, Pathe Television Corp., president.

"I'd bring what's left of the stock to the music show, but I don't expect to have much left," Mr. Joffe declared.

### Majestic Offers Special TV Deal To Retailers

Firm Giving Promotional Allowance on 17-Inch Sets

CHICAGO, June 21.—A new television buy was offered dealers this week by the Majestic Radio & Television division of the Wilcox-Gay Corp. Included in the special deal are a 17 inch leatherette table model and a 17 inch mahogany console set, both 1951 models. According to Leonard Ashtach, Majestic president, who would not quote list prices of the sets, the dealers pay "regular prices" for the sets but receive a promotional allowance.

Mr. Ashtach reported that 2,000 units of the table model have been sold since the deal was offered Monday and "almost as many" units of the console.

The special offer will continue until 5,000 units of each set have been sold.

Lacy's, Washington, D. C., was one of the first takers of the field and Hudson-Ross, Chicago, also bought the sets. Quantities sold to these retailers could not be learned.

### Meck Adds 14-Inch Model at \$139.95

CHICAGO, June 18.—John Meck Industries has added a 14-inch picture tube television receiver to retail at \$139.95, which was said by John S. Meck, president, to be \$20 under the nearest competitive set in the industry.

The new set has a leatherette table-top cabinet similar to the company's earlier model 616T, 16-inch table set, and has a standard chassis with continuous tuner. The model, identified as MM-614-TL, is in production for immediate delivery.

"We are adding this low cost unit as a 'sales starter' for both distributors and retailers," Mr. Meck said.

#### TOP EXECUTIVE

GENERAL MANAGEMENT, SALES

With only two companies during last 20 years. Very successful. Advancing from bottom in plant to General Sales Manager, and Vice President, multi-million dollar companies. Now, at 48, interested in another challenge with independent, product, organization, or other aid to improve its profit standing. Wharton graduate. Well acquainted with key government, industry and finance executives. Negotiated numerous prime and sub-contracts. Team builder and cooperator. Confidential inquiry invited.

Z 7568 Times

#### HOW TO BUILD A SALES FORCE WITH THE MAN

WHO BUILT ONE OF THE COUNTRY'S BEST

Sales Executive with over 23 years' experience in every phase of both industrial and consumer sales development for one of America's largest companies. Exceptionally well qualified for management and direction of existing sales force, or for building new sales organization where selection and training of men are vital to success. Also ideal for company sales representative contracting large buyers and negotiating big contracts. About 50, single, willing to work or travel anywhere. Salary secondary to interesting and challenging opportunity.

Z 7602 TIMES

cooperation for my wife, young son, and management team or as assistant to top executive. Married; no children. Z 7595 Times.

Joseph H. H. Daroff

phila, other lines already close to a down.

Despite the has brought spring levels that any mind do so, because cost of wool.

Other, more nounce specially planned for that "any standing in it that divers for prices.

win 2 to MEXICO

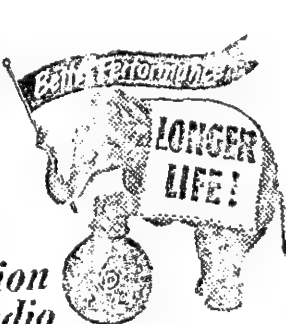
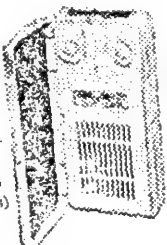
with all expenses paid!

That's what Pan-American and Emerson are offering Emerson dealers for the best Pan-American Portable window displays. Get your entry blank and window material from your Emerson distributor now!

3-Way Pocket Portable Model 584, \$39.95 (INCLUDING BATTERIES)

Pocket Portable Model 640, \$24.95 (INCLUDING BATTERIES)

**TESTED** Television and Radio  
NEW YORK 11, N. Y.



11  
 (NORMAN, S. 1102) - Norm. ARTIE - Labeled "CBS - Chamber,  
 25, ... about the year" in Retailing 6/27/51 - Paragraph 4  
 I find this problem very SIMPLE. It's been a golden  
 but's just to have immediately the working samples models  
 (L. L. R. J. K. H. K. H. K.) - Note Article labeled "C. B. C.  
 June. Products 25, or order sets this year" in Retailing  
 from Paragraph 46, first sentence. They say "No  
 Sales," but the firm will ask distributors "Kindly  
 line produced by the manufacturer."

(Rec. 11 only)  
 NORMAN, S. 1102 - I can't imagine you're in  
 for being quiet like color television products  
 I want only the engineers who are work-  
 ing to be told by others. I'll be sure about  
 know. I'll be sure to know the competitors  
 NORMAN & S. 1102. The fact that it has  
 kept quiet (Daddy shutting his mouth off) he  
 himself looks so well & so caused some  
 be upset. However, everyone will refer to the  
 project as the "projection" job.

How many of the air conditioning units  
 will be in the project? Some will be partly? I  
 get the idea from H. H. When does Starratt go  
 to work? When the project, for men? Women.  
 Is NORMAN SHIPPIER & AIR Conditioning units for  
 UNIT TEST with MORCANTON? Does L. Chiving? Bud-  
 ook? Keeping Brester, Mort. at bay? File of Brester  
 How is AARON MACH. business?



→ MAKE SURE... I will not try to sell you  
P.2 - 61

F.A. - Confirming previous note, please come on SAT.  
afternoon (leaving at 1400 - 1500) MUCH Trouble for  
I know you'll be able to get in. Tell things  
only if you are questioned; that you can't make  
the week.

(come in with Him).  
J.F. - Please Have Spickard see me as soon as you  
/ Mrs S.E.A's sentence been reduced to 9 mo. & 17 days  
to 8 mo. (8 mo. sentence = 8 Mo. minus 40 DAY  
while 9 Mo, 17 DAY sentence = same minus 1 Mo. & 17 DAY  
a flat 8 mo. - If the former he would get on  
on July 3<sup>rd</sup>, if latter on Aug. 11<sup>th</sup>. Of course, if  
gets back the 15 days soon enough, he would get  
out in either case 15 days earlier.) - What's  
on Designation V.A. L.K.? Did you get a message for  
N.A.M. on same? - C.F. - to come on an  
other day, but TUES. - L.T. LYNN is on the TUES.  
- Met the "devil". I am bristled in table. was  
delivered to (Name & address given to N.A.M.) - (see  
bottom Page 2 memo - 6/16/51 - I specified in  
P.L. if you see cons. No Bill unless & until  
say so. Also said deliver air antennae, he  
would install himself. They are arranged a set  
at your convenience. - What's the latest on  
the drawing, Army less at Somerville, & Tele. by  
Note that 14985. Circumstances unit advertised  
1/14 is over 1/2 H.P. & a piece of junk. - you can  
arrange installation & service for customer. ASK NORI.

To JEF:

Re: "Crosby" Job

GUARD Only the enclosed papers.

PHOTOGRAPH same on previous retaining photostat

MAIL IMMEDIATELY original to PORT Jervis,

marked personal; att. NORMAN

Give photostat copy to SIDNEY LIOZ, only.

If he's gone on vacation or is going on vacation  
I won't work on same until he comes back, then  
no sense in even giving same to him. But I won't  
like him to put it off, sufficient time in, in order  
this get started.

Push NORMAN to get Patent work started on this.



# DRUM TYPE COLOR WHEEL FOR BLACK- & WHITE & COLOR TV

Let us consider a drum composed of 6-slats (2 series of the prism) and let us assume that this drum will be used for a 20" as we will assume

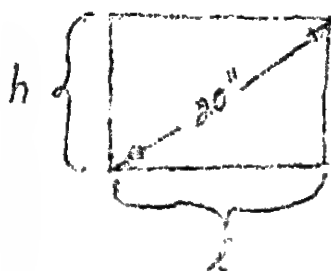


FIG. I

$$1.25h = l$$

then

$$(1.25h)^2 + h^2 = 20^2$$

$$h^2 = \frac{400}{2.56} = 156.2$$

$$h = 12.5"$$

$$l = 1.25(12.5) = 15.6"$$

would be the dimensions of the tube. For each slat to "cover" the prism would be necessary that

$$\frac{12.5}{\frac{2}{\sin 60}} = \frac{6.25}{2} = 12.5" =$$

of the Drum.

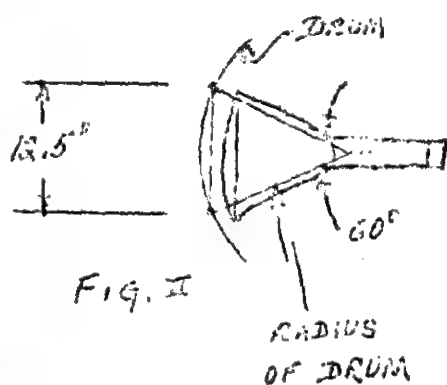


FIG. II

Let us now suppose the drum is formed a section shown in Fig. 3, in which the slat curved members "fitting" into a retainer rim. These slats are to consist of  $\frac{1}{16}$ " thick. of steel sheet, and their length were to be 17", then each would have a volume of

$$2\pi R l \left[ \frac{60}{360} \right] t = \frac{2\pi (12.5)(17)(60)}{360} \frac{1}{16}$$

$$13.9 \text{ in.}^3$$

and a specific gravity of 1.18, then

$$\frac{62.5 \frac{\text{lb}}{\text{ft.}^3}}{1728 \frac{\text{in.}^3}{\text{ft.}^3}} \cdot 1.18 \cdot 13.9 \text{ in.}^3 = 0.58 \text{ lb.}$$

would be the weight of each slat, where:-

62.5  $\frac{\text{lb}}{\text{ft.}^3}$  is taken as the density of steel

In the standard CBS color disc, 9 discs (3 series of the primary three) are at 1440 rpm. This would set a period of

$$\frac{9}{6}(1440) = 2160 \text{ rpm for the 6-slat drum}$$

This would mean an angular velocity of

$$\frac{1770 \frac{\text{rev.}}{\text{min.}} (2\pi \frac{\text{rad.}}{\text{rev.}})}{60 \frac{\text{sec.}}{\text{min.}}} = 150.8 \frac{\text{rads.}}{\text{sec.}}$$

The centrifugal force acting on each slot would then be:-

$$F_c = \frac{W}{g} \omega^2 r$$

$$= \frac{0.594 \text{ lb.}}{32 \frac{\text{ft.}}{\text{sec.}^2}} \cdot \left[ 150.8 \frac{\text{rad.}}{\text{sec.}} \right]^2 \frac{12.5 \text{ in.}}{12 \frac{\text{in.}}{\text{ft.}}}$$

$$= 440 \#$$

and both retainer rings would therefore be said to act under a load

$$440 \frac{\#}{\text{slot}} (6 \text{ slots}) = 2640 \#$$

together, and

$$\frac{2640 \#}{2 \text{ retainer rings}} = 1320 \frac{\#}{\text{ring}}$$

To hold the kinetic stress in each ring to  $\frac{1}{5}$  of an screened value  
value of 76,000 #/in.<sup>2</sup> with a  $\frac{5}{8}$ " wide ring would require a

$$\frac{1320 \#}{0.75 \text{ in.} (1)} = 17,600 \frac{\#}{\text{in.}^2}$$

$$\frac{1320 \#}{0.75 \text{ in.} (17,600 \frac{\#}{\text{in.}^2})} = 0.1258" = t$$

and the slot must also be reviewed as a uniformly loaded beam with a simply supported end and end:-

$$W = wL$$

$$M = \frac{wx}{2} (L-x) = EI \left( \frac{d^2 y}{dx^2} \right)$$

$$\frac{w}{2} (L-x^2) = EI \left( \frac{d^2 y}{dx^2} \right)$$

$$\frac{w}{2EI} \left( \frac{Lx^2}{2} - \frac{x^3}{3} \right) + C_1 = \frac{dy}{dx}$$

But  $\frac{dy}{dx} = 0$ , when  $x = \frac{L}{2}$ , and so:-

$$\frac{w}{2EI} \left( \frac{L^3}{8} - \frac{L^3}{24} \right) + C_1 = 0$$

$$C_1 = - \frac{w}{2EI} \left( \frac{L^3}{24} \right) = - \frac{wL^3}{24EI}$$

$$\frac{dy}{dx} = \frac{w}{2EI} \left( \frac{Lx^2}{2} - \frac{x^3}{3} \right) - \frac{wL^3}{24EI}$$

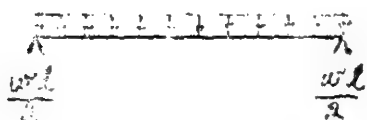


Fig. II



$$y = \frac{w}{2EI} \left( \frac{Lx^3}{6} - \frac{x^4}{12} \right) - \frac{wL^3x}{24EI} + C_2$$

But, since  $y = 0$  when  $x = 0$ , then

$$C_2 = 0$$

and

$$y = \frac{w}{2EI} \left( \frac{Lx^3}{6} - \frac{x^4}{12} - \frac{L^3x}{12} \right)$$

At  $x = \frac{L}{2}$ , it is clear that  $(y)$  would have its maximum value,  $(y)_{max}$  would be given by:-

$$y_{max} = \frac{w}{2EI} \left( \frac{L^4}{48} - \frac{L^4}{192} - \frac{L^4}{24} \right)$$

$$= -\frac{5wL^4}{384EI} = -\frac{5WL^3}{384EI}$$

This gives us a form for computing the deflection, and the stresses, in the plates when the rotor has up to full design speed. It is now necessary to find the value of  $(I)$  for the plates.



Fig. II

It is clear that the mean radius  $r = 12 \frac{1}{2}$ " and  $r_{mean} = 12 \frac{9}{16}$ " (which is  $12 \frac{17}{32}$ ") would be the radius of gyration of the plate indicated in Fig. II with respect to the axis  $X'X'$ . Since the cross-sectional area of the plate is approximately

$$\frac{(2\pi r_{mean}) \cdot 48}{360} =$$

$$\frac{\frac{1}{16} (2\pi) (12 \frac{17}{32}) (60)}{360} = 0.822$$

the  $(I)$  with respect to the  $X'X'$  would be

$$Ah^2 = 0.822 (12 \frac{17}{32})^2 = 129 \text{ in.}^4$$

The center of gravity of the plate would be given by:-

$$y_0 = \frac{r_{mean} \sin \theta}{\text{rad. } \theta} = \frac{(12 \frac{17}{32}) (\sin 30^\circ)}{\text{rad. } 30^\circ} = \frac{12 \frac{17}{32} (0.5)}{0.5236} = 1.2$$

If  $(I_0)$  is the moment of inertia of the plate section about its own c.g., then

$$I_{xx'} = I_0 + A y_c^2$$

and so

$$129 \text{ in.}^4 = I_0 + 0.823 (11.95)^2$$

$$129 - 0.823 (142.5) = 129 - 117.5 = 11.5 \text{ in.}^4$$

From this, it follows that

$$y_{\max} = -\frac{5WL^3}{384EI} = -\frac{5(740)(17)^3}{384(2)(10^6)(11.5)} = 0.00122 \text{ in.}$$

which is acceptable if it does not involve an excessive stress.

$$y_{\max} = \frac{5WL^3}{384EI}$$

and

$$M_{\max} = \frac{wL^2}{8} = \frac{WL}{8}$$

Therefore

$$y_{\max} = \frac{WL}{8} \cdot \frac{5L^2}{48EI} = \frac{5ML^2}{48EI}$$

But

$$M = SZ$$

where

$M$  = Moment induced in the beam — in-lb.

$Z$  = Sectional modulus of the beam — in.<sup>3</sup>

$S$  = stress induced in the beam — #/in.<sup>2</sup>

and

$$\frac{I}{c} = Z$$

where

$c$  = distance of the extreme fibre from the neutral axis of the beam

and hence

$$y_{\max} = \frac{5(S)(\frac{I}{c})L^2}{48EI} = \frac{5SL^2}{48Ec}$$

By this equation,

$$0.00122 \text{ in.} = \frac{5(12 \frac{3}{4} - 11.5)(17^2)S}{48(2)(10^6)} = \frac{5(1.25)(17^2)S}{96(10^6)(1.1)}$$

$$\frac{0.00122(96)(10^6)}{5(1.25)(289)} = S = \frac{8.36}{1.25} \text{ #/in.}^2$$



### 4.4 FILEVER SHAFT

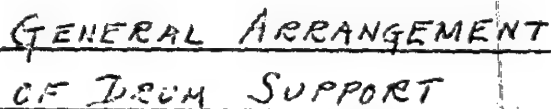


FIG. VI



FIG. VIII

To approximate the combined weights of the Drums, let us proceed  
 follows:

12 rings - 17" dia.,

$$\frac{2\pi r 60}{960} = \frac{2\pi (12.5)(60)}{360} = 13.1" \text{ wide}$$

and  $\frac{1}{8}"$  thick

would weigh

$$\frac{12(17)(13.1)(0.0625)(62.5)(1.18)}{172.8} = 7.17 \#$$

and, if we estimate each end-ring at 3#, then the drums  
 rings would weigh 12# in total, to give a total weight  
 approximately 20#. This could be said to have a radius of  
 gyration of approximately 13", giving the Drum a  $I_{mr}$  of:

$$I_{mr} = 20 \left( \frac{13}{12} \right)^2 = 23.5 \text{ ft.-lb.}^2$$

For drum is given to attain a velocity of  $150.8 \frac{\text{rads.}}{\text{sec.}}$ ,

$$\frac{23.5}{2(32)} (150.8)^2 = \frac{15,700}{2} \text{ ft.-lb.} = 8,350 \text{ ft.-lb.}$$

of energy is required in the form of physical energy. But it is evidently,  
 we need a large motor, and it would be desirable to reduce this figure  
 the value of the indicated figure. Let us therefore reduce the weight of  
 rings, and particularly the weight at the indicated radius of gyration,  
 to 3# limit for the 14-end-rings in total. In that case,

$$\frac{10.17}{2} (150.8)^2 = \frac{22,400}{2} \text{ ft.-lb.} = 11,200 \text{ ft.-lb.}$$

and if this were supplied in  
 a

$$\frac{11,200 \text{ ft.-lb.}}{(60 \text{ sec.})(550 \frac{\text{ft.-lb.}}{\text{sec.}})} = 0.218 \text{ HP}$$

motor would be required.

In bringing the Drum around to a stop, let us assume  $I_{mr}$   
 is calculated. Then the negative acceleration of

$$\frac{a}{r} = \frac{2(150.8 - 0)}{60} = 5.03 \frac{\text{rads.}}{\text{sec.}}$$

is calculated, and the Torque-rating of the brake would have to be

$$\frac{10.17}{32} (5.03) = 1.595 \text{ ft.-lb.}$$



Here this to be applied via a mechanical brake, this would mean, applied on a 13" radius, a

$$\frac{15,975 \text{ ft-lb.} \left(12 \frac{\text{in.}}{\text{ft.}}\right)}{(13 \text{ in.})} = 14,777 \#$$

braking-force. If an eddy-current brake were to be used, it would be one in which a

$$\frac{36.20}{72.40 \text{ (ft-lb.)}} = \frac{60.3}{291.3 \frac{\text{ft-lb.}}{\text{sec.}}}$$

energy consumption is planned. The theoretical electrical rating of the motor would then have to be:-

$$\frac{60.3}{291.3 \frac{\text{ft-lb.}}{\text{sec.}}} \left(0.746 \frac{\text{H.P.}}{\text{ft-lb./sec.}}\right) = 0.0825 \text{ H.P.} = 0.329 \text{ KW}$$

but because eddy current brakes are quite inefficient, the actual brake rating would have to be substantially larger. A mechanical input applied to the output shaft of the driving motor also discloses considerable

The question arises of applying the braking force until a minimum speed is obtained, and then leaving it to the positive pin to bring the drum to a full-stop. The combined positive and displacement of the drum from drum #2. Assume the use of a  $\frac{1}{4}$ " diameter round pin with a cantilever length of 2". By formula (for cantilever beam)

$$M = PL^2 = 52 = 5 \frac{I}{E}$$

$$f = \frac{PL^3}{3EI}$$

or in other words

$$f = \frac{SL^2}{9Ec}$$

Using this formula, we see that for a stress limit which is 75% of the elastic limit, and taking the elastic limit to be 50,000 psi, then for a material for which  $E = 2.6(10^6)$

$$f = \frac{0.75(30,000 \frac{\text{lb.}}{\text{in.}^2})(2 \text{ in.})^2}{3(2.6 \times 10^6 \frac{\text{lb.}}{\text{in.}^2})\left(\frac{1}{2} \text{ in.}\right)} = 0.00924 \text{ in.}$$

Quite obviously, the pin would be working as a spring storing up energy, and so, if  $P(K)$  represents the force  $P$  and  $K$  the spring per inch

deflection, then

$$W (\text{work stored in the spring}) = \int_{y=0}^{y=y} Ky = \frac{K}{2} y^2$$

where  $y$  = the limiting deflection of the spring. Thus, if we re-arrange equation

$$f = \frac{P \ell^3}{3EI}$$

to the form

$$\frac{3EI}{\ell^3} = \frac{P}{f} = K = \frac{3\pi E d^4}{\ell^3}$$

we find that

$$K = \frac{3\pi (26 \times 10^6 \text{ #/in.}^2) (\frac{1}{4})^4}{2^3} = 119,500 \text{ #/in.}$$

and, by this, the work stored by a deflection of 0.00924" would be

$$\frac{1}{2} (119,500 \text{ #/in.}) (0.00924)^2 = 5.08 \text{ in.-lbs.}$$

or

$$\frac{5.08 \text{ in.-lbs.}}{12 \frac{\text{in.}}{\text{ft.}}} = 0.423 \text{ ft.-lbs.}$$

energy. This would limit the velocity of the drum to

$$0.423 = \frac{10.17}{2(32)} \omega^2$$

$$\left[ \frac{2(32)}{10.17} \right]^{1/2} \omega = [2.75]^{1/2} = 1.66 \text{ rads./sec.}$$

When the positioning pin is sent "home", this would mean that the  $\omega$  of the drum would be reduced to zero. The drum speed from 150.8 rev./min. to 0 rev./min., after which the pin would take care of the drum stopping. The drum turning to a full stop.

During the use of a  $\frac{1}{2}$  horsepower motor drive and assuming that before Drum #2 is properly positioned for black-and-white recording, we now proceed to the design of the second positioning drum.



The velocity of the Drum #2 assembly at the end of the above-mentioned 120° can be derived by applying the ratio of: - the specified motor, the computed required motor, to the acceleration on which the computer is based. Thus, the computed required motor would raise the speed of the Drum Assembly from zero to 156.8 radians/sec. in 60 sec., or acceleration of

$$156.8 = \frac{1}{2} a (60)$$

$$\frac{3(156.8)}{66} = 5.63 \text{ rads./sec.}^2$$

Using a 0.125 HP motor in the place of the 0.115 HP computed requirement may take

$$\frac{(0.125 \text{ HP})}{(0.115 \text{ HP})} [5.63 \text{ rads./sec.}^2] = 5.98 \text{ rads./sec.}^2$$

is the acceleration which the specified motor would apply. The of travel constitutes a travel of

$$\frac{120}{360} (2\pi) = \frac{2}{3} \pi \text{ radians}$$

The above-given acceleration of 5.98 rads./sec.<sup>2</sup> would be applied to an assembly with a  $\Sigma m r^2$  of 10.17 lb.-ft.<sup>2</sup>, while in the motor of 0.125 HP alone roughly one-half of this  $\Sigma m r^2$  is involved; thus the acceleration of the #2 Drum (assuming the same motor as before) would be

$$2(5.98) = 11.96 \text{ rads./sec.}^2$$

$$s = \frac{1}{2} at^2$$

$$\frac{2}{3} \pi = \frac{1}{2} (11.96) (t^2)$$

$$t = \left[ \frac{\frac{2}{3} (2\pi)}{1(11.96)} \right]^{1/2} = 0.35^{1/2} = 0.592 \text{ sec}$$

Thus, the Drum #2 would move through the mentioned arc; and

$$s = \frac{1}{2} at^2 = \frac{1}{2} (11.96) (0.592)^2 = 3.54 \text{ rads./sec.}$$

Thus, the Drum #2 would move through the arc of travel. The position of the Drum #2 at the end of the arc of travel is indicated by the position of the Drum #2 at the end of the arc of travel. Thus, the Drum #2 would move through the arc of travel.

of the two functions which the latch serves: - (1) firstly, it serves to stop and position Drum #2 with respect to Drum #1 when black-and-white viewing is intended; and (2) it is the means by which Drum #1 is motivated along with Drum #2 in color-viewing. In stopping Drum #2 after ~~it~~ has Drum #1 has already been positioned, it must absorb the flywheel energy of Drum #2. This would mean, since  $E_{max}$  for each Drum has been taken at 5.085 ft.-lb., that

$$\frac{(5.085 \text{ ft.-lb.})}{(2)(9.2 \frac{\text{ft.}}{\text{sec.}})} (3.54 \text{ rads./sec.}) = 0.382 \text{ ft.-lbs.}$$

of energy would have to be absorbed. By reference to the previous calculation concerning the pin which positions Drum #1, it is clear that a member with a section modulus equal to a  $\frac{1}{4}$ " round would more than suffice for this service, if it were no longer than the aforementioned pin. According to the second criterion for the design of the latch member, it would be required at a maximum to transmit a torque equal to

$$\frac{(10.17 \text{ ft.-lb.})}{(3.2 \frac{\text{ft.}}{\text{sec.}})} (5.85 \text{ rads./sec.}) = 18.71 \text{ ft.-lb.}$$

or

$$(18.71 \text{ ft.-lb.}) (12 \frac{\text{in.}}{\text{ft.}}) = 22.45 \text{ in.-lb.}$$

~~At a design stress limit of~~ Since the latch is located on about a 15" radius from the axis of rotation, the torque indicated above implies a load of

$$\frac{22.45 \text{ in.-lb.}}{15 \text{ in.}} = 1.728 \text{ lb.}$$

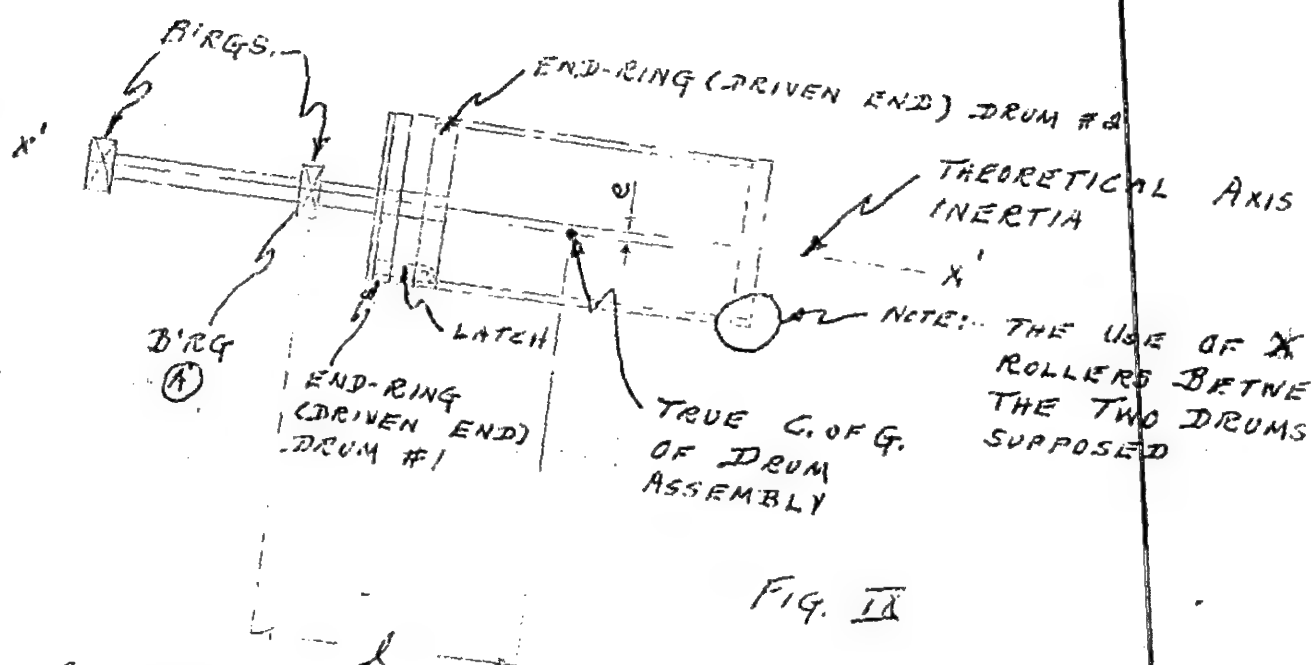
applied to the end of the latch. Were the latch 2" lg., this would mean the inducing of a bending load of

$$1.728 (2) = 3.456 \text{ in.-lb.}$$

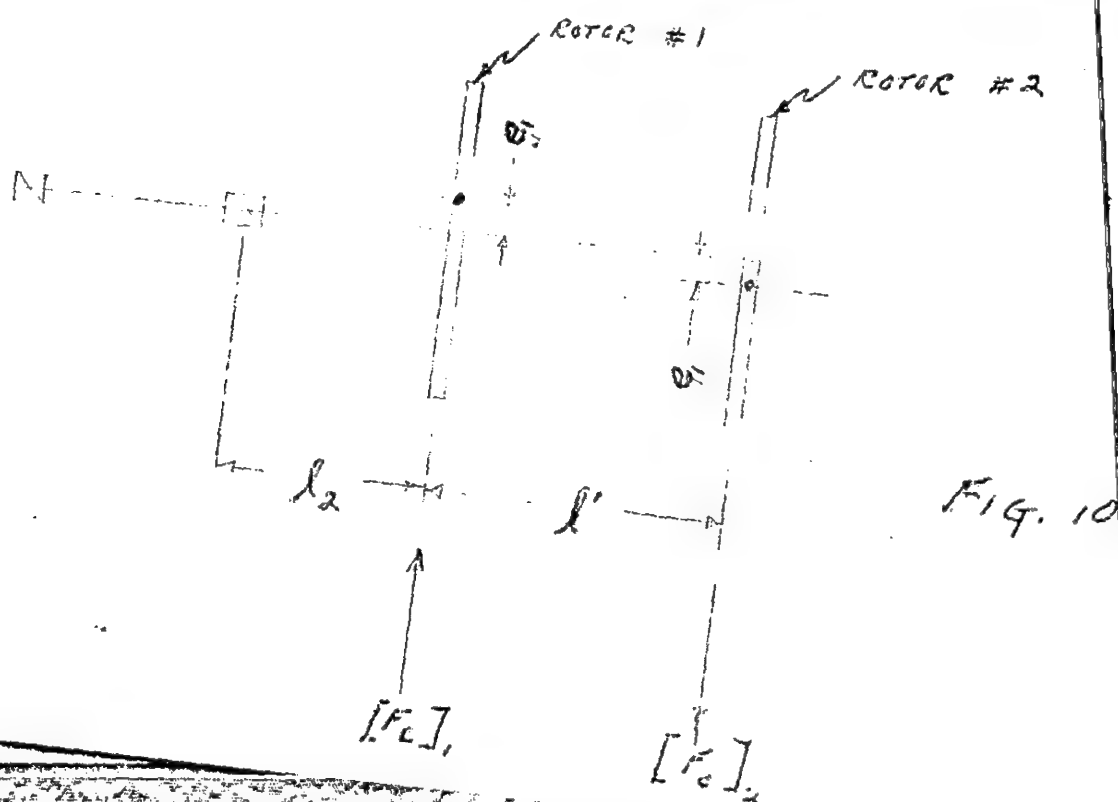
which is, in fact, insignificant, and worthy of no further computations.

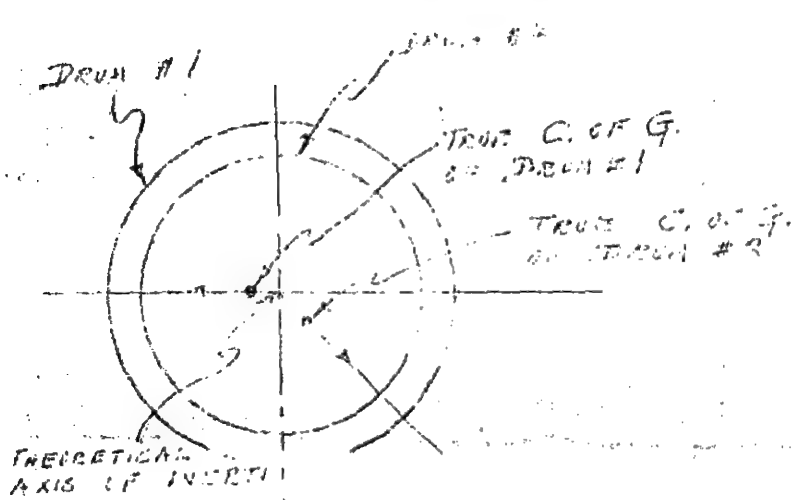
This brings us to the question of the shafting by which the Drums are motivated. On reconsideration of the loads involved, it is practical, from a superficial observation, to think in terms of a cantilever shafting mounting of the Drums from one end as per the figure below:-





As portrayed above, the double-drum assembly is considered as a single concentrated load on a cantilever shaft, with the length of the shaft being taken as equal to the <sup>horizontal</sup> span between Brg. (A) and the true center of gravity of the combined drum assembly. The use of spacer-rollers as indicated contributes towards the validity of this viewpoint.





SCHEMATIC END VIEW  
OF ASSEMBLY (DRUMS)

FIG. XI

The analysis taken above is, fundamentally, a simplified and idealized one. It is in operation to the vector in the shaft, to carry the distinct concentrated loads. Assuming the shaft that carrying two distinct concentrated loads, this is more or less, but possible (assuming that each drum has been fabricated to identical tolerances as to balance). The possibilities are illustrated in Figs. 10

1. The situation in which the action of identical weights act in identically opposite vibration action that are mounted on the same shaft;

and  
2. The situation in which the action of identical weights have their identical vibration acting in different axial planes.

Analyzing the situation presented by Fig. 1, it is observed since the eccentricities of the drums are identical, each drum will begin with a static centrifugal force on the shaft, as given by:-

But as is  $(r_1)$  and  $(r_2)$  are identical, the centrifugal forces, as shown, are identical, opposite in direction, they are a balanced or balanced moment (or balanced couple) of magnitude

$$\frac{W}{g} r \omega^2$$

For as long as the balanced couple exists, the drums will not rotate and will continue of the shaft to the balance position. If the left of  $(r_2 + \delta/2)$  to an upward rotation, and every rotation to the right of  $(r_2 + \delta/2)$  to a downward rotation. But obviously the mentioned position of the drum would present different reactions to the couple, and would consequently result in



directions of different beam the neutral axis of inertia of different cross section  $x = x_2 + l'$ , where the difference in magnitude would be the moment of  $(x_2)$  or  $(F_{c_2})$ , the couple would be directly proportional to the distance between the plot shown pictorially below:

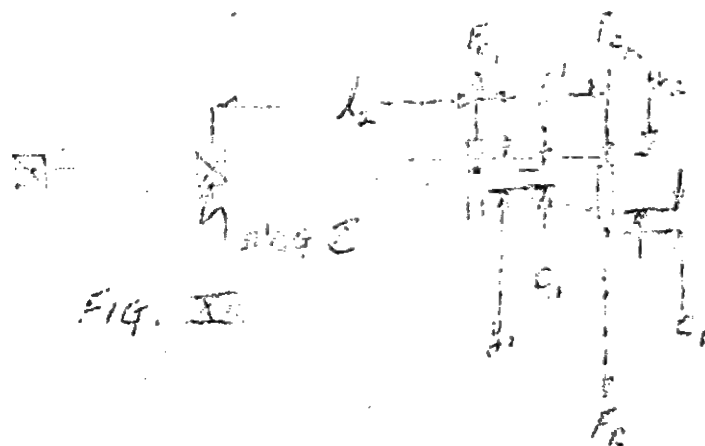


Fig. 10

Thus we have a situation in which the forces  $(F_{c_1})$  and  $(F_{c_2})$  can be considered as acting at

$$\frac{(F_{c_2})(l' + l_2) - (F_{c_1})l_2}{(F_{c_2} + F_{c_1})} = F_R$$

and the total force  $(F_R)$  acting at a distance from  $(l_2 + l')$  from the left edge. The moment acting on any section of the beam would be

$$M(x) = (F_R)(l_2 + l' - x) = EI \frac{d^2 y}{dx^2}$$

the deflection curve, would take the form

$$y = -\frac{F_R}{EI} \left( \frac{(l_2 + l')x^2}{2} - \frac{x^3}{6} \right)$$

By applying the boundary conditions, a K-value

$$K = \frac{EI}{(l_2 + l')^2} \left( \frac{(l_2 + l')^2}{2} - \frac{(l_2 + l')^3}{6} \right)$$

can be determined from

$$K = \frac{EI}{(l_2 + l')^2} \left( \frac{(l_2 + l')^2}{2} - \frac{(l_2 + l')^3}{6} \right)$$





(10) (11) in fact of the at down by the normal static  
 relationship. It contains the value for the dynamic  
 relationship between (9) and (10) at which point any attempt to open  
 it up is quite then the first dynamic speed. and, in fact, there is  
 open to some extent as the first dynamic speed. I  
 in fact, the first dynamic speed is the first dynamic speed.  
 as the first dynamic speed is the first dynamic speed.  
 "single speed" or "fixed" speed.

P. 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106, 107, 108, 109, 110, 111, 112, 113, 114, 115, 116, 117, 118, 119, 120, 121, 122, 123, 124, 125, 126, 127, 128, 129, 130, 131, 132, 133, 134, 135, 136, 137, 138, 139, 140, 141, 142, 143, 144, 145, 146, 147, 148, 149, 150, 151, 152, 153, 154, 155, 156, 157, 158, 159, 160, 161, 162, 163, 164, 165, 166, 167, 168, 169, 170, 171, 172, 173, 174, 175, 176, 177, 178, 179, 180, 181, 182, 183, 184, 185, 186, 187, 188, 189, 190, 191, 192, 193, 194, 195, 196, 197, 198, 199, 200, 201, 202, 203, 204, 205, 206, 207, 208, 209, 210, 211, 212, 213, 214, 215, 216, 217, 218, 219, 220, 221, 222, 223, 224, 225, 226, 227, 228, 229, 230, 231, 232, 233, 234, 235, 236, 237, 238, 239, 240, 241, 242, 243, 244, 245, 246, 247, 248, 249, 250, 251, 252, 253, 254, 255, 256, 257, 258, 259, 260, 261, 262, 263, 264, 265, 266, 267, 268, 269, 270, 271, 272, 273, 274, 275, 276, 277, 278, 279, 280, 281, 282, 283, 284, 285, 286, 287, 288, 289, 290, 291, 292, 293, 294, 295, 296, 297, 298, 299, 300, 301, 302, 303, 304, 305, 306, 307, 308, 309, 310, 311, 312, 313, 314, 315, 316, 317, 318, 319, 320, 321, 322, 323, 324, 325, 326, 327, 328, 329, 330, 331, 332, 333, 334, 335, 336, 337, 338, 339, 340, 341, 342, 343, 344, 345, 346, 347, 348, 349, 350, 351, 352, 353, 354, 355, 356, 357, 358, 359, 360, 361, 362, 363, 364, 365, 366, 367, 368, 369, 370, 371, 372, 373, 374, 375, 376, 377, 378, 379, 380, 381, 382, 383, 384, 385, 386, 387, 388, 389, 390, 391, 392, 393, 394, 395, 396, 397, 398, 399, 400, 401, 402, 403, 404, 405, 406, 407, 408, 409, 410, 411, 412, 413, 414, 415, 416, 417, 418, 419, 420, 421, 422, 423, 424, 425, 426, 427, 428, 429, 430, 431, 432, 433, 434, 435, 436, 437, 438, 439, 440, 441, 442, 443, 444, 445, 446, 447, 448, 449, 450, 451, 452, 453, 454, 455, 456, 457, 458, 459, 460, 461, 462, 463, 464, 465, 466, 467, 468, 469, 470, 471, 472, 473, 474, 475, 476, 477, 478, 479, 480, 481, 482, 483, 484, 485, 486, 487, 488, 489, 490, 491, 492, 493, 494, 495, 496, 497, 498, 499, 500, 501, 502, 503, 504, 505, 506, 507, 508, 509, 510, 511, 512, 513, 514, 515, 516, 517, 518, 519, 520, 521, 522, 523, 524, 525, 526, 527, 528, 529, 530, 531, 532, 533, 534, 535, 536, 537, 538, 539, 540, 541, 542, 543, 544, 545, 546, 547, 548, 549, 550, 551, 552, 553, 554, 555, 556, 557, 558, 559, 560, 561, 562, 563, 564, 565, 566, 567, 568, 569, 570, 571, 572, 573, 574, 575, 576, 577, 578, 579, 580, 581, 582, 583, 584, 585, 586, 587, 588, 589, 590, 591, 592, 593, 594, 595, 596, 597, 598, 599, 600, 601, 602, 603, 604, 605, 606, 607, 608, 609, 610, 611, 612, 613, 614, 615, 616, 617, 618, 619, 620, 621, 622, 623, 624, 625, 626, 627, 628, 629, 630, 631, 632, 633, 634, 635, 636, 637, 638, 639, 640, 641, 642, 643, 644, 645, 646, 647, 648, 649, 650, 651, 652, 653, 654, 655, 656, 657, 658, 659, 660, 661, 662, 663, 664, 665, 666, 667, 668, 669, 670, 671, 672, 673, 674, 675, 676, 677, 678, 679, 680, 681, 682, 683, 684, 685, 686, 687, 688, 689, 690, 691, 692, 693, 694, 695, 696, 697, 698, 699, 700, 701, 702, 703, 704, 705, 706, 707, 708, 709, 710, 711, 712, 713, 714, 715, 716, 717, 718, 719, 720, 721, 722, 723, 724, 725, 726, 727, 728, 729, 730, 731, 732, 733, 734, 735, 736, 737, 738, 739, 740, 741, 742, 743, 744, 745, 746, 747, 748, 749, 750, 751, 752, 753, 754, 755, 756, 757, 758, 759, 760, 761, 762, 763, 764, 765, 766, 767, 768, 769, 770, 771, 772, 773, 774, 775, 776, 777, 778, 779, 780, 781, 782, 783, 784, 785, 786, 787, 788, 789, 790, 791, 792, 793, 794, 795, 796, 797, 798, 799, 800, 801, 802, 803, 804, 805, 806, 807, 808, 809, 810, 811, 812, 813, 814, 815, 816, 817, 818, 819, 820, 821, 822, 823, 824, 825, 826, 827, 828, 829, 830, 831, 832, 833, 834, 835, 836, 837, 838, 839, 840, 841, 842, 843, 844, 845, 846, 847, 848, 849, 850, 851, 852, 853, 854, 855, 856, 857, 858, 859, 860, 861, 862, 863, 864, 865, 866, 867, 868, 869, 870, 871, 872, 873, 874, 875, 876, 877, 878, 879, 880, 881, 882, 883, 884, 885, 886, 887, 888, 889, 890, 891, 892, 893, 894, 895, 896, 897, 898, 899, 900, 901, 902, 903, 904, 905, 906, 907, 908, 909, 910, 911, 912, 913, 914, 915, 916, 917, 918, 919, 920, 921, 922, 923, 924, 925, 926, 927, 928, 929, 930, 931, 932, 933, 934, 935, 936, 937, 938, 939, 940, 941, 942, 943, 944, 945, 946, 947, 948, 949, 950, 951, 952, 953, 954, 955, 956, 957, 958, 959, 960, 961, 962, 963, 964, 965, 966, 967, 968, 969, 970, 971, 972, 973, 974, 975, 976, 977, 978, 979, 980, 981, 982, 983, 984, 985, 986, 987, 988, 989, 990, 991, 992, 993, 994, 995, 996, 997, 998, 999, 1000.

$$W = 11.17 \text{ ft}$$

$$L = 14 \text{ ft}$$

$$S = 15.11 \text{ ft/sec}$$

$$C = 15.8 \text{ ft/sec}$$

$$E = \frac{1}{2} \pi r^2 \text{ (area of circle)} = \frac{1}{2} \pi (14)^2 = 153.8 \text{ ft}^2$$

$$g = \left[ 3.14 \frac{\text{ft}}{\text{sec}^2} \right] \left[ \frac{14 \text{ ft}}{\text{sec}^2} \right] = 38.4 \text{ ft/sec}^2$$

$$E_1 = 25(10) \text{ ft/sec}^2$$

$$E_2 = 25(10) \text{ ft/sec}^2$$

$$\frac{E_1}{E_2} = \frac{E_1}{E_2} = \frac{25(10)}{25(10)} = 1$$

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$$E_1 = 25(10) \text{ ft/sec}^2$$

$$E_2 = 25(10) \text{ ft/sec}^2$$

$$h = \frac{1}{3} AC - e^2 - \frac{1}{3} C = 0 - 0 + \frac{0.73}{3} = 0.143$$

$$g = \frac{1}{3} \left[ h + (h^2 + e^2)^{1/2} \right] + \frac{1}{3} \left[ - (h^2 + e^2)^{1/2} \right] =$$

$$\frac{1}{3} \left[ 0.143 + (0.021 + 0.009)^{1/2} \right] + \frac{1}{3} \left[ 0.074 - (0.021 + 0.009)^{1/2} \right] =$$

$$\frac{1}{3} [0.074 + 0.107] + \frac{1}{3} [0.074 - 0.107] =$$

$$0.102 + 0.077 = 0.176$$

$$u = \frac{g}{3} = 0 + 0.176 = 0.176$$

$$v = 2g + e = 0 + 0.176 = 0.176$$

$$W = 4u^2 + 3v - 12gl = 4(0.176)^2 + 3(0.143) - 12(0) =$$

$$= 4(0.031) + 0.429 = 0.124 + 0.429 = 0.573$$

Now, the four roots would be:-

$$d_1 = -A + u^{1/2} + (v + w^{1/2})^{1/2}$$

$$d_2 = -A - u^{1/2} + (v - w^{1/2})^{1/2}$$

$$d_3 = -A + u^{1/2} - (v + w^{1/2})^{1/2}$$

$$d_4 = -A - u^{1/2} - (v - w^{1/2})^{1/2}$$

Now, using

$$d_1 = -0 + 0.176^{1/2} + (0.176 + 0.573)^{1/2} = 0.42 + (0.176 + 0.573)^{1/2}$$

$$= 0.42 + 0.845 = 1.265$$

Now, the four roots would be in the region of imaginary - imaginary values. Using

$$d_1 = 0.42 - 0.845 = -0.425$$

$$d_2 = 0.42 + 0.845 = 1.265$$

$$d_3 = 0.42 - 0.845 = -0.425$$

$$d_4 = 0.42 + 0.845 = 1.265$$

Now, the four roots would be in the region of imaginary - imaginary values. Using (4) as follows

$$d_1 = \frac{1}{3} \left[ h + (h^2 + e^2)^{1/2} \right] + \frac{1}{3} \left[ - (h^2 + e^2)^{1/2} \right] =$$

$$\frac{1}{3} [0.074 + 0.107] + \frac{1}{3} [0.074 - 0.107] =$$



$$= \frac{1}{2} [0.009 - \frac{1}{2} (0.121)] = [0.009 - 0.0605]^{1/2} =$$

$$\frac{1}{2} [0.42] = 0.071$$

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1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100. 101. 102. 103. 104. 105. 106. 107. 108. 109. 110. 111. 112. 113. 114. 115. 116. 117. 118. 119. 120. 121. 122. 123. 124. 125. 126. 127. 128. 129. 130. 131. 132. 133. 134. 135. 136. 137. 138. 139. 140. 141. 142. 143. 144. 145. 146. 147. 148. 149. 150. 151. 152. 153. 154. 155. 156. 157. 158. 159. 160. 161. 162. 163. 164. 165. 166. 167. 168. 169. 170. 171. 172. 173. 174. 175. 176. 177. 178. 179. 180. 181. 182. 183. 184. 185. 186. 187. 188. 189. 190. 191. 192. 193. 194. 195. 196. 197. 198. 199. 200. 201. 202. 203. 204. 205. 206. 207. 208. 209. 210. 211. 212. 213. 214. 215. 216. 217. 218. 219. 220. 221. 222. 223. 224. 225. 226. 227. 228. 229. 230. 231. 232. 233. 234. 235. 236. 237. 238. 239. 240. 241. 242. 243. 244. 245. 246. 247. 248. 249. 250. 251. 252. 253. 254. 255. 256. 257. 258. 259. 260. 261. 262. 263. 264. 265. 266. 267. 268. 269. 270. 271. 272. 273. 274. 275. 276. 277. 278. 279. 280. 281. 282. 283. 284. 285. 286. 287. 288. 289. 290. 291. 292. 293. 294. 295. 296. 297. 298. 299. 300. 301. 302. 303. 304. 305. 306. 307. 308. 309. 310. 311. 312. 313. 314. 315. 316. 317. 318. 319. 320. 321. 322. 323. 324. 325. 326. 327. 328. 329. 330. 331. 332. 333. 334. 335. 336. 337. 338. 339. 340. 341. 342. 343. 344. 345. 346. 347. 348. 349. 350. 351. 352. 353. 354. 355. 356. 357. 358. 359. 360. 361. 362. 363. 364. 365. 366. 367. 368. 369. 370. 371. 372. 373. 374. 375. 376. 377. 378. 379. 380. 381. 382. 383. 384. 385. 386. 387. 388. 389. 390. 391. 392. 393. 394. 395. 396. 397. 398. 399. 400. 401. 402. 403. 404. 405. 406. 407. 408. 409. 410. 411. 412. 413. 414. 415. 416. 417. 418. 419. 420. 421. 422. 423. 424. 425. 426. 427. 428. 429. 430. 431. 432. 433. 434. 435. 436. 437. 438. 439. 440. 441. 442. 443. 444. 445. 446. 447. 448. 449. 450. 451. 452. 453. 454. 455. 456. 457. 458. 459. 460. 461. 462. 463. 464. 465. 466. 467. 468. 469. 470. 471. 472. 473. 474. 475. 476. 477. 478. 479. 480. 481. 482. 483. 484. 485. 486. 487. 488. 489. 490. 491. 492. 493. 494. 495. 496. 497. 498. 499. 500. 501. 502. 503. 504. 505. 506. 507. 508. 509. 510. 511. 512. 513. 514. 515. 516. 517. 518. 519. 520. 521. 522. 523. 524. 525. 526. 527. 528. 529. 530. 531. 532. 533. 534. 535. 536. 537. 538. 539. 540. 541. 542. 543. 544. 545. 546. 547. 548. 549. 550. 551. 552. 553. 554. 555. 556. 557. 558. 559. 560. 561. 562. 563. 564. 565. 566. 567. 568. 569. 570. 571. 572. 573. 574. 575. 576. 577. 578. 579. 580. 581. 582. 583. 584. 585. 586. 587. 588. 589. 590. 591. 592. 593. 594. 595. 596. 597. 598. 599. 600. 601. 602. 603. 604. 605. 606. 607. 608. 609. 610. 611. 612. 613. 614. 615. 616. 617. 618. 619. 620. 621. 622. 623. 624. 625. 626. 627. 628. 629. 630. 631. 632. 633. 634. 635. 636. 637. 638. 639. 640. 641. 642. 643. 644. 645. 646. 647. 648. 649. 650. 651. 652. 653. 654. 655. 656. 657. 658. 659. 660. 661. 662. 663. 664. 665. 666. 667. 668. 669. 670. 671. 672. 673. 674. 675. 676. 677. 678. 679. 680. 681. 682. 683. 684. 685. 686. 687. 688. 689. 690. 691. 692. 693. 694. 695. 696. 697. 698. 699. 700. 701. 702. 703. 704. 705. 706. 707. 708. 709. 710. 711. 712. 713. 714. 715. 716. 717. 718. 719. 720. 721. 722. 723. 724. 725. 726. 727. 728. 729. 730. 731. 732. 733. 734. 735. 736. 737. 738. 739. 740. 741. 742. 743. 744. 745. 746. 747. 748. 749. 750. 751. 752. 753. 754. 755. 756. 757. 758. 759. 760. 761. 762. 763. 764. 765. 766. 767. 768. 769. 770. 771. 772. 773. 774. 775. 776. 777. 778. 779. 780. 781. 782. 783. 784. 785. 786. 787. 788. 789. 790. 791. 792. 793. 794. 795. 796. 797. 798. 799. 800. 801. 802. 803. 804. 805. 806. 807. 808. 809. 810. 811. 812. 813. 814. 815. 816. 817. 818. 819. 820. 821. 822. 823. 824. 825. 826. 827. 828. 829. 830. 831. 832. 833. 834. 835. 836. 837. 838. 839. 840. 84

$$P = (0.07)^2 + 0.43 = 0.049 + 0.43 = 0.479$$

$$x_1 = 0.071^{1/2} + (0.071 + 0.10^{1/2})^{1/2} = 0.276 + (0.071 + 0.10)^{1/2}$$

$$= 0.276 + 0.171^{1/2} = 0.276 + 0.414 = 0.690$$

2000

$$1^4 - 6 \cdot 1^2 + 0 \cdot 13 = 0$$

$$1.66 - 0.8(1.136) = 0.73$$

100-09088-043 \* 0

again, asking

$$x = \frac{1}{2} \left[ h + (h^2 + k^3)^{1/3} \right] + \frac{1}{2} \left[ h - (h^2 + k^3)^{1/3} \right] =$$

$$[0.204] + \frac{1}{2} [-0.124] = 0.102 - 0.062 = 0.04$$

$\mu = 0.07$

$$r = 0.04$$

$$= 7(0.0016)^2 + 0.43 = 7(0.0016) + 0.43 = 0.0056 + 0.43 = 0.4356$$

$$I_1 = 0.0047 \times (0.07 + 0.006)^{1/2}$$

$$0.2 + (0.04 + 0.01)^{1/2} = 0.2 + 0.1^{1/2} =$$

$$0.2 + 0.835 = 1.035''$$

6. 2. 1. 1.

$$-0.13 - 0.40 = 0$$

$$1.17 - 0.8(1.035) - 0.12 = 0$$

111-6981-2, 3, 4

[illegible]

is probably from the torque in accelerating the drum to  
 1000 rpm of 22.5 in-lb. Torque to "shock torque" to 6  
 1.5 times this value, according to eq. 58 of "Shifting From A  
 Dynamic Standpoint",

$$M = \left[ \frac{W}{g} \right]^{1/3} = 22.5 \left[ \frac{22.5 \cdot 15(1.5)}{32.2} \right]^{1/3} =$$

$$0.227 \left[ \frac{23.625}{12} \right]^{1/3} = 0.227(1.415) = 0.321 \text{ in.}$$

shaft would be required to yield not more than a 1/20 in.  
 of deflection. This shaft, in fact, is of eq. 58 of "Shifting From  
 A Dynamic Standpoint",

$$\frac{16 M_c}{\pi d^3} = 55$$

if again we set  $M_c = 22.5$  "shock torque" and  $d = 1.125$  (as  
 previously suggested)

$$\frac{16(1.5)(22.5)}{\pi (1.125)^3} = \frac{2.4(22.5)}{\pi (1.42)} = 12.1 \text{ #/in.}^2$$

would equal the shear stress due to torsion. The combined  
 stress due to torsion and bending would then be:-

$$\left[ 15000^2 + 12.1^2 \right]^{1/2} = \left[ 2.25(10^8) + 141(10^4) \right]^{1/2} =$$

$$15000 \text{ #/in.}^2$$

and since, a 1 1/2" diameter shaft satisfies the principle of  
 similarity, the required diameter of a shaft of any given speed is  
 proportional to the cube root of the torque. Thus by  $\left[ \frac{K_2}{K_1} \right]^{1/3}$  acco  
 to eq. 11) of "Shifting From A Dynamic Standpoint", since

$$K = \frac{GEJ}{L} = \frac{(12 \cdot 10^6)(\pi)(1.125)^4}{64(2700)} =$$

$$\frac{7.6(10^6)(\pi)(1.5^4)}{64(2700)}, \quad 0.2212 \text{ in.}$$

then,

$$\left[ \frac{1.5}{1.125} \right]^{1/3} = \left[ \frac{2.25(10^8)}{12.1} \right]^{1/3} = \left[ 3500 \right]^{1/3} = 9.14 \text{ rev.}$$

$$y = \frac{2}{\frac{2}{1.035} - 1}$$

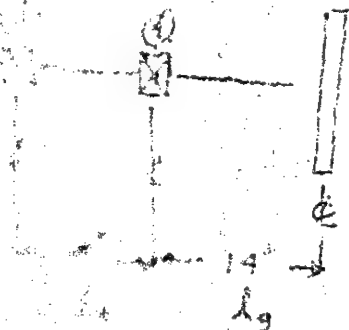
in for Eq. (15) of "Shifting from C to D" in report,

$$y = \frac{2}{\left(\frac{2}{1.035}\right) - 1} = \frac{2}{2.58 - 1} = \frac{2}{1.58}$$

where  $e = 0.12$ , then

$$y = \frac{2.02}{1.58} = 1.0371"$$

in turn we get the fraction of the bearings and spring spacings - assume  
 (centerline distance) between the two main bearings:



The computed shifting requirement at  
 15,000 psi, was 1.035". The  
 value which a shift would withstand a  
 given value would be:-

$$N = 52 = \frac{5\pi \cdot 1^2}{32} = \frac{(15,000 - 1.035)^2}{32} = \frac{15000(\pi)(1.12)}{32}$$

1150 in.-lbs.

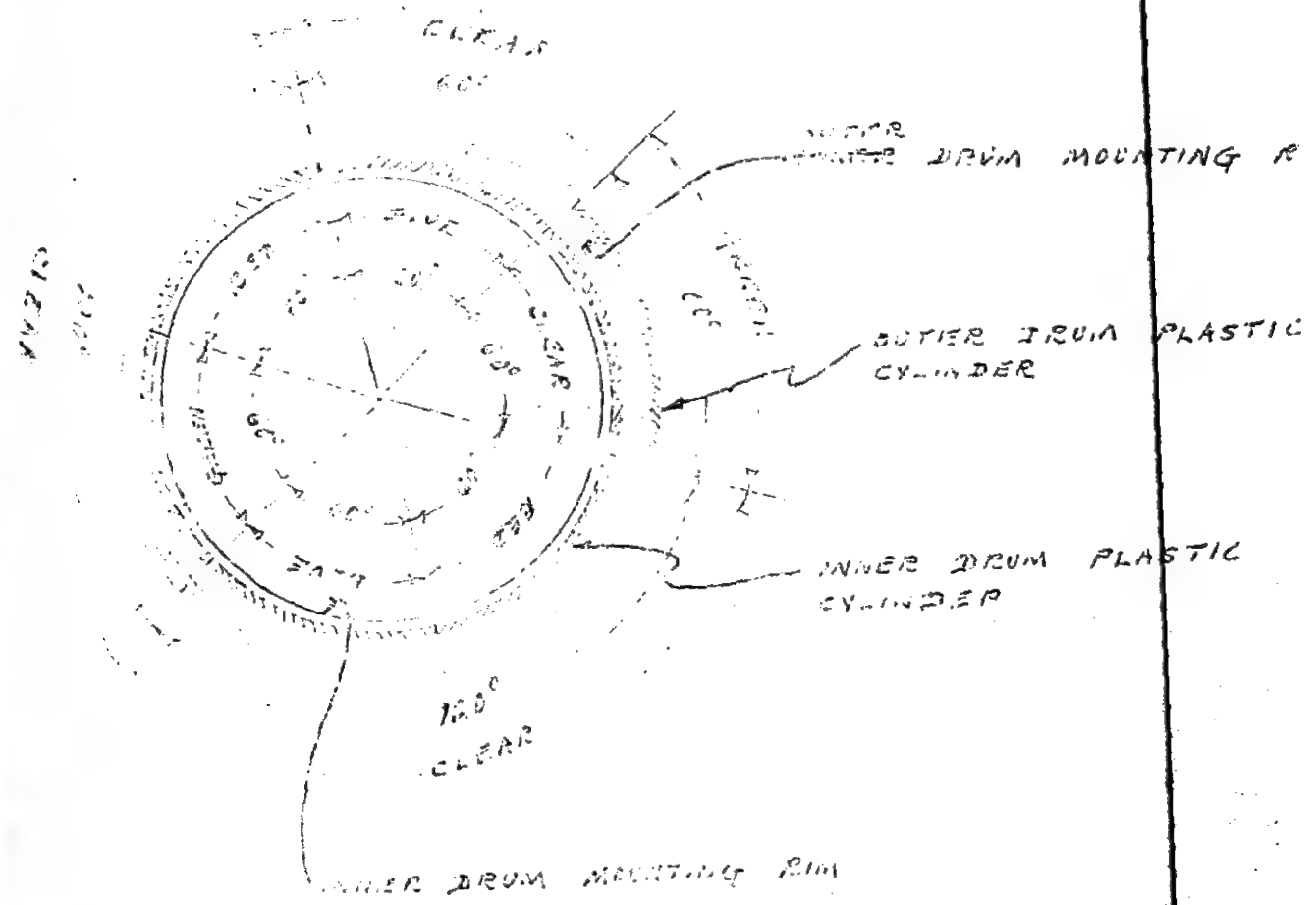
1150 in.-lbs. = 1000 in. Brg. (B)

1150 in.-lbs. = 1000 in. Brg. (A)

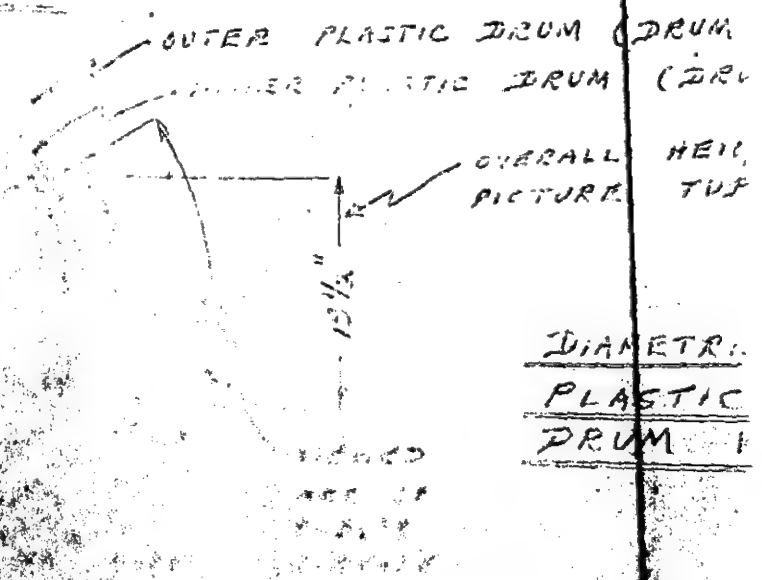
These values would be  
 the largest computations.



DOUBLE DRUM SET-UP FOR 20" TUBE



SCHEMATIC SHOWING ARRANGEMENT  
OF SECTORS ON DOUBLE-  
DRUM ASSEMBLY



DIAMETER  
PLASTIC  
DRUM

SAT. #

FILTER SECTION "A"

GRIND ADJOINING EDGES OF SHEETS TO INDICATED BEVEL  
LEAVE GRIND EDGES ROUGH, &  
FILL UP WITH DENTAL POLY-  
METHACRYLATE POLYMER PASTE



FILTER SECTION "B"

PREPARATION OF LONGI  
SEAMS BETWEEN FILTE  
SECTIONS BOTH DRUMS

6-LUCITE 1/4"  
BLOCKS

LUCITE  
RG. 1/4"  
3/4" LG.  
TO 2R

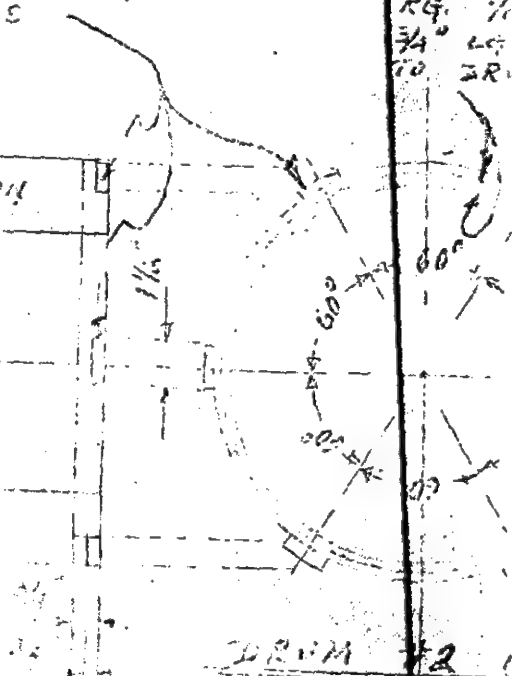
DRIVEN END

FILTER SECTION

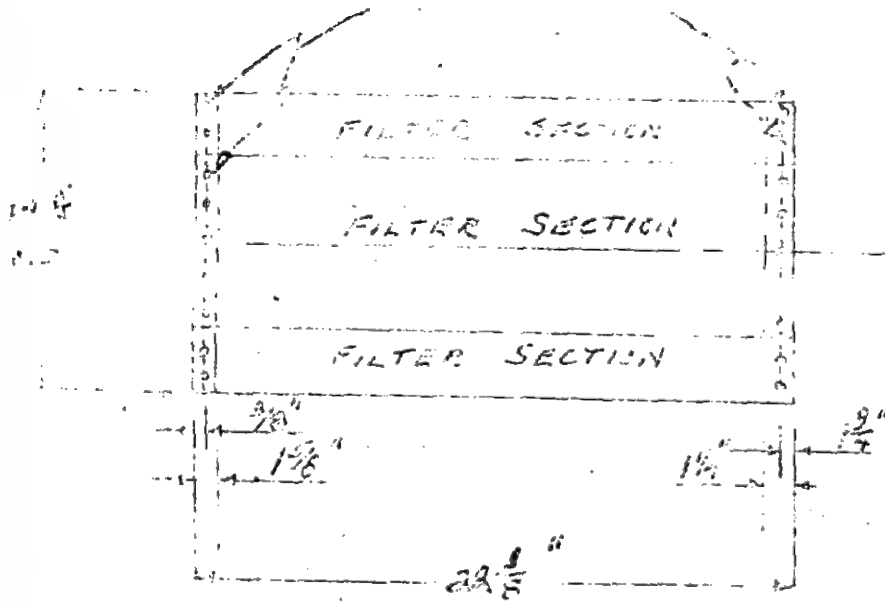
FILTER SECTION

FILTER SECTION

DRUM #2  
ELEVATION  
A.H. END



6. EQU-SPACED  $\frac{1}{8}$ " & 32.  
 RE. MACH. SCREWS PER  
 90° SECTOR TO END-RINGS

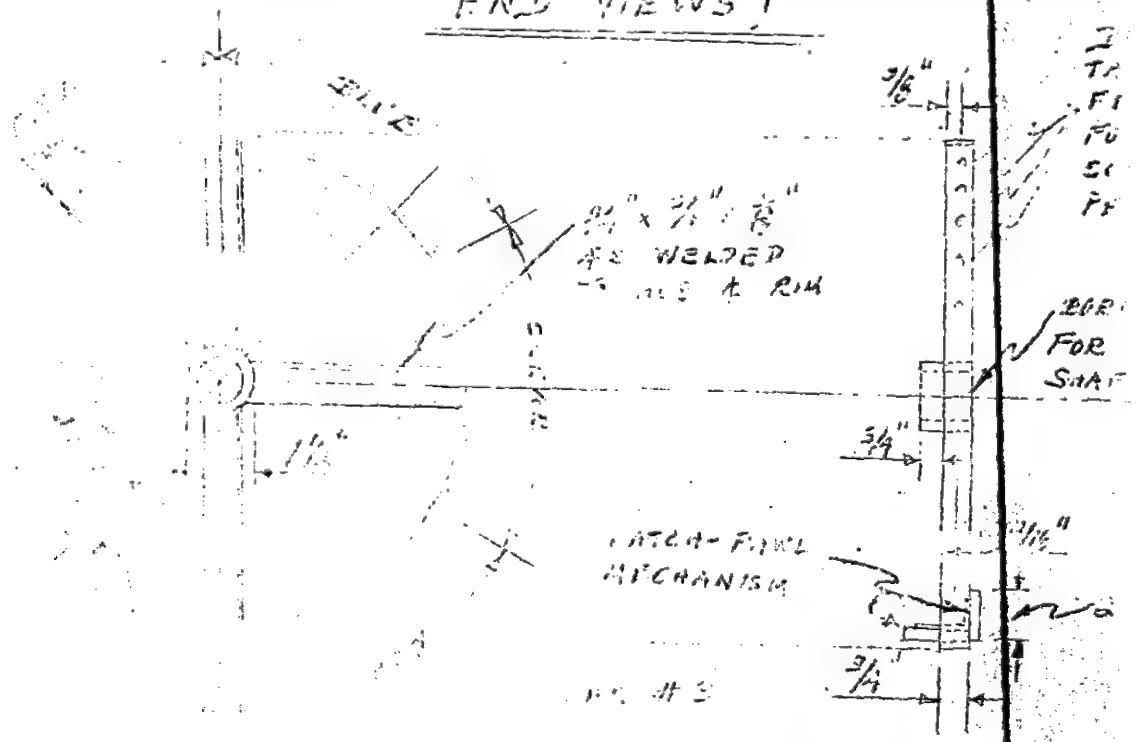


FLASTIC DR

MET RIM

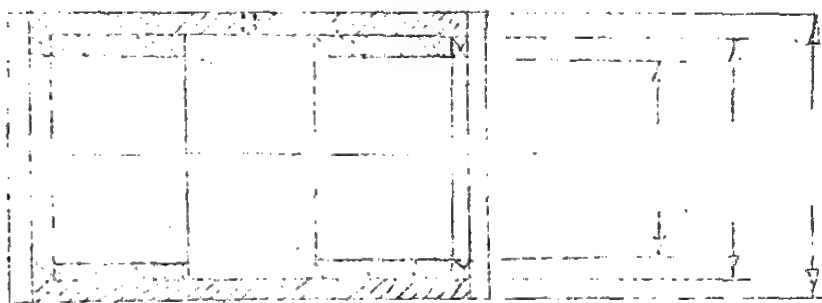
R.H. GUIDE R.  
 ASSEMBLIES

DRUM #1 (SIDE ELEVATION & R.H.  
END VIEWS)



DRUM #2 DRI  
END-RING





BULKY EXHIBIT

Date received 7/9/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Ultimate disposition to be made of exhibit Retained

Estimated date of disposition-To be decided at conclusion of case.

List of contents:

128. Two photostatic copies of thesis dated 7/6/51 together with two photostatic copies of drawing entitled "Switching Circuit for Double-drum Arrangement".

74  
100-95068-1B

INDEXED  
FILED  
JUL 11 1951  
FBI - NEW YORK

812

Carbon Caps:-

Shots (1) thru (4)

and computer shots replace the material  
previously set and is directly explained. Mt. (17)  
in the relay circuit for the automatic switching and diagram  
arrangement. Full explanation follows. Monthly

A



1954

1891. I am glad to hear  
you are happy. Love to  
all the family.

- Compare the 2nd  
after report of R. tubes;  
small White Black &  
the one C.P. Tube;

- The nature be objective  
and having the go to  
subject

stayed "what what" is  
"what" must be  
the consideration,  
material things and  
the thought that the  
person who it will

There (10) looks to the  
"pencil" (11) the form  
by an "hooking" is  
made to the fact that  
it should be written with

...the ... more than  
... the ... screen.]  
... illustrates  
... between the C.R.  
... It will be  
... to subside  
... the length of the color  
... distance  
... provide  
... supporting and  
... screen, it is  
... the length of the  
... distributed  
... the ... screen.  
... the color-  
... the drum  
... fundamental accom-  
... the same C.R.  
... the two shells is  
... the drum  
... occurring on the  
...  
... of 5 properly sequenced  
... of the same are.  
... of 5 equal  
... filter section,  
...  
... the drum complete the  
... by the drum filter-  
...



1) The first section is a very thin section of the rock, showing the texture of the rock. The second section is a thin section of the rock, showing the texture of the rock. The third section is a thin section of the rock, showing the texture of the rock. The fourth section is a thin section of the rock, showing the texture of the rock. The fifth section is a thin section of the rock, showing the texture of the rock. The sixth section is a thin section of the rock, showing the texture of the rock. The seventh section is a thin section of the rock, showing the texture of the rock. The eighth section is a thin section of the rock, showing the texture of the rock. The ninth section is a thin section of the rock, showing the texture of the rock. The tenth section is a thin section of the rock, showing the texture of the rock.

[illegible][illegible]

The following, along with portions of the same, -  
which will be referred to in the C. A. F. volume, -  
is the most complete list of the same.

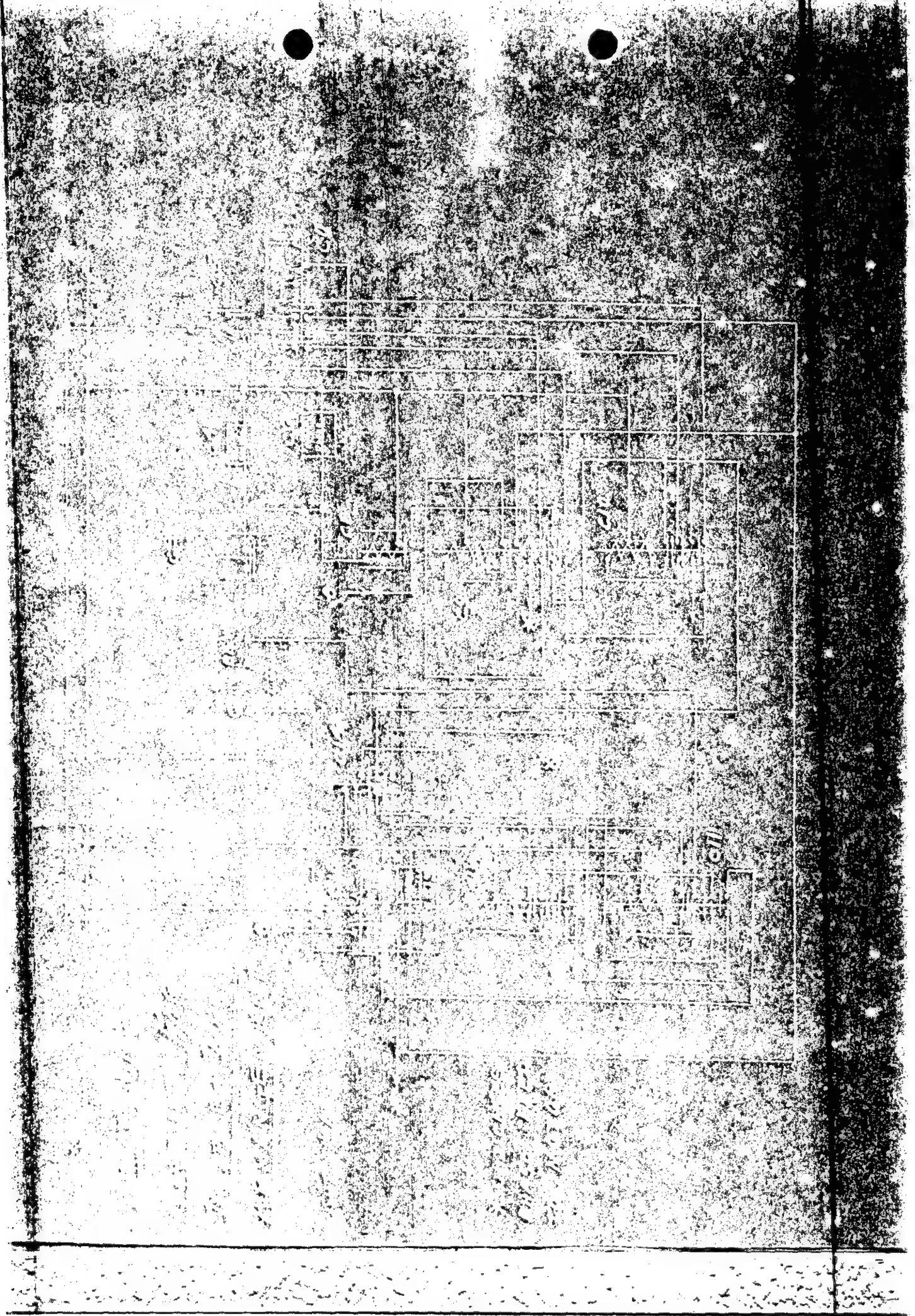
is a double drum, and the other is the  
single drum, and the double drum is the  
single drum.

2) The alignment of the two parallel members of the outer frame with the line of inner frame — stability frame is proper alignment of the two frame for shear and with weaving



... (all the [15] [16] [17] and [18])  
... (all the [15] and [16]) which is  
... (all the [15] and [16]) shown as 60°  
... (all the [15] and [16]) be ejected from the  
... (all the [15] and [16]) the action of the released-actuator plunger  
... (all the [15] and [16]) that all the released-actuator plunger and the  
... (all the [15] and [16]) it is rotated thru a 300°  
... (all the [15] and [16]) while the released-actuator plunger is held stationary by  
... (all the [15] and [16]) the released-actuator plunger, and that the  
... (all the [15] and [16]) the released-actuator plunger is engaged in  
... (all the [15] and [16]) the released-actuator plunger is engaged in  
... (all the [15] and [16]) the released-actuator plunger is engaged in

(to be continued)





Carbon Copies:-

Shots (3) thru (4)  
and computation shots replace the material  
previously sent and evidently misplaced. Lt. (17)  
is the key circuit for the automatic switching and diagram  
arrangement. Full explanation follow Monkey  
A



July 1931

OBJECTIVES:

The design projected on Sheet No. 1 (D. 111) is intended for some use in the "color wheel" component of the color system. In preparing objectives, have been kept in mind the laying down the preliminary design which this sketch was intended to convey -

- a) principally the drawing which has been to extend color reception in the larger type of C.R. tubes,
- b) meeting the goal has been to include both black & white and color reception on the same C.R. tube,
- and
- c) finally, another goal has been to produce the objective set down in D and to include having to go to uniformly appearing cabinet design.

FUNDAMENTAL PRINCIPLES OF THE PROJECTED DESIGN:

A guiding principle of the generally employed "color wheel" is that which holds that the diameter of the wheel must be the diameter of the given glass tube. The consideration, and the problem which it entails in both mechanical design and cabinet design, lies at the bottom of the thought that the "color wheel" is limited as to the size of screen which it will accommodate on a practical basis.

The design projected on Sheet No. 1 (D. 111) refers to the use of a "color drum" (or "color reflector"). The drum or reflector action, though in the present instance the "overlying" is indicated. By the overlying, reference is made to the fact that the conventional "color wheel" must revolve about a center which

...the screen is actually more than  
...the screen. ]  
...illustrates  
...between the C.R.  
...It will be  
...to subtend  
...The length of the color-  
...that minimum distance  
...and which provides  
...the practical supporting and  
...it is  
...the length of the  
...distributed  
...of the viewed screen  
...the color-  
...that the drum  
...The fundamental principle  
...the same C.R.  
...the two shells is  
...the double drum  
...the color viewing on the  
...of 5 properly sequenced  
...of the same are  
...in principle, of 5 equal  
...filter section,  
...the inner drum complete the  
...the inner drum filter-  
...section.



See the top view on the #1

(1) The two drums be capable of having their relative positions altered so that, for color-viewing, the one filter-section of the outer drum properly complements the color-sequence established by the 5 filter-sections of the inner drum, - while, for black and white viewing, the filter-section of the inner drum is complemented by any of the clear pictures of the outer drum.

Such an ability, the complementary positioning of the two drums for color-viewing involves the joint rotating of both drums, while the proper alignment of the two drums for black-and-white reception is based on both drums remaining stationary.

It thus appears in (a), (b), (c) and (d) above, together with the movement which follows (e), means that a positive means of aligning the 5 color-sections of the inner wheel with the 1 color-section of the outer wheel must be provided, means that the joint rotation of the properly-matched color-sections of both wheels must be insured when color viewing is desired, and means that, for black-and-white viewing, both the complementary positioning of the pictures and the color-sections should be secured. Clearly, in rotating and, in proper complementary positioning mechanism, is indicated. Therefore, the proposed device involves first, a rotating, aligning, and positioning mechanism.

The rotating, aligning, and positioning mechanism, - which shall be referred to as the C-P mechanism, - is built around the following features:

- (a) a central shaft or axle, - which is the axis of the inner drum, and the centrally located drum is the outer drum.
- (b) the alignment of the 5 color-sections of the outer drum with the 1 color-section of the inner drum - whereby, from a proper alignment of the two drums, can have black-and-white viewing.



ing-balls (see also [14], [15], [5], [7], and [4])  
 that the latch-pawl (shown in [5] and [15]) is  
 located in the grab (shown in [7] and [15]) shown as 60°  
 off the vertical centerline on [14] be ejected from the  
 grab-slot by the action of the solenoid-actuated plunger  
 (shown in [15]) that the latch-pawl and the  
 inner drum of which it is a member be rotated thru a 300°  
 arc of travel while the outer drum is held stationary by  
 the continuously-engaged solenoid-actuated plunger, and that the  
 latch-pawl member of the outer drum then be engaged in  
 the grab-slot of the grab shown on the vertical centerline of  
 [14].

(To be continued)

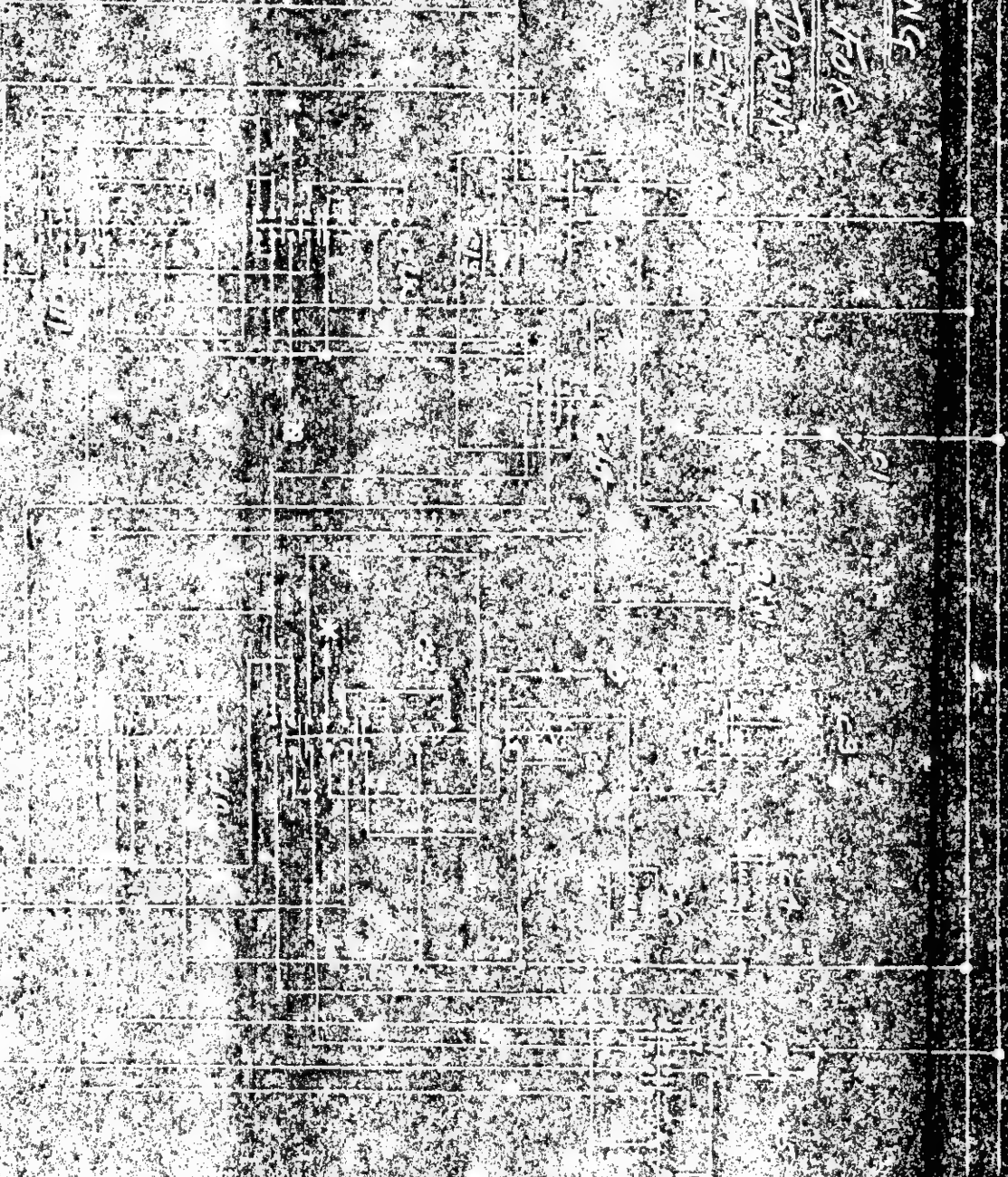
SWITCHING

MECHANICAL

MODEL - DRAW

EXPERIMENT

NO. 10786





BULKY EXHIBIT

Date received 7/27/51

AD RAUL M BROTHMAN

100-95068-1B  
(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained USA-SDNY

Address \_\_\_\_\_

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

127. Photostatic copy of decision of Circuit Court of appeals in case entitled US v BROTHMAN & MOSKOWITZ.

75  
100-95068-1B  
8  
G.M.



UNITED STATES COURT OF APPEALS

FOR THE SECOND CIRCUIT

No. 290—October Term, 1950.

(Argued June 14, 1951)

Decided July 26, 1951.)

Docket No. 22039

UNITED STATES OF AMERICA,

*Appellee.*

—v.—

ABRAHAM BROTHMAN and MIRIAM MOSKOWITZ,

*Appellants.*

Before:

SWAN, Chief Judge, AUGUSTUS N. HAND and L. HAND,

*Circuit Judges.*

Appeal from the United States District Court for the  
Southern District of New York.

From judgments of conviction and sentence after trial  
upon an indictment charging both defendants with con-  
spiracy to obstruct justice and defendant Brothman alone  
with the substantive offense, the defendants have appealed.  
Affirmed on conspiracy count; reversed on substantive count.

JOHN McKIM MINTON, Attorney for appellant  
Brothman; William E. McNulty, in counsel.

WILLIAM L. MESSING, Attorney for appellant  
Moskowitz.

IRVING H. SAYPOL, United States Attorney, for  
appellee; Bruno Schachner, Roy M. Cohn,  
John M. Foley and Stanley D. Robinson,  
Assistant United States Attorneys, of  
counsel.

SWAN, Chief Judge:

These are appeals from judgments of conviction and sentence upon an indictment which charged both appellants with the crime of conspiracy, 18 U. S. C. § 83 (1946 ed.), and Brothman alone with the substantive offense of endeavoring to persuade a witness to give false testimony before a federal grand jury, 18 U. S. C. § 241 (1946 ed.). Brothman was sentenced to consecutive terms of 2 and 5 years and fines of \$10,000 and \$5,000 on the respective counts. Moskowitz was sentenced to 2 years imprisonment and fined \$10,000. Brothman's appeal raises a single issue, namely, failure to prove venue of the substantive offense. The appeal of Moskowitz challenges the sufficiency of the evidence to prove her participation in the conspiracy, and asserts prejudicial error in the prosecution's summation.

We address ourselves first to the conspiracy count. In the summer of 1944 a federal grand jury in and for the southern district of New York was conducting an investigation of possible violations of the espionage laws. Brothman and one Gold were summoned to appear as witnesses before this grand jury. The conspiracy count charged that both



appellants together with Gold, who was named as a conspirator but not as a defendant, agreed that Brothman should give false testimony before the grand jury, should inform Gold thereof, and Gold should likewise give false testimony consonant with Brothman's. The case against the appellants was made largely by the testimony of Gold. Moskowitz does not question the sufficiency of the evidence to prove that such a conspiracy existed between Brothman and Gold, but contends that she was not shown to have been a party to it. An examination of the record convinces us beyond doubt that the contention is groundless. Without discussing the evidence in detail it will suffice to refer to a few incidents which indicate that she repeatedly assisted in making up the false stories of the two main actors. After Gold had been interviewed by agents of the Federal Bureau of Investigation, he recounted in the presence of Brothman and Moskowitz what he had told the agents, and Brothman remarked that he had made "a very fine choice of a story." The inference that the story was false must have been obvious to Moskowitz. She was also present when Gold refused to tell Brothman about his espionage activities because Brothman "was already deeply enough involved." When Brothman was considering testifying before the grand jury to a story different from that he had originally told the F. B. I. agents Moskowitz expressed concern and told Gold she was going to tell Brothman to try to stick to the original story; and she later told Gold that she and attorney Needleman persuaded Brothman to do so. Finally, on the night before Gold was to testify, Moskowitz said that she wished to go home early "so that Abe Brothman and I would have plenty of time to match our stories before my appearance before the grand jury the next morning."

The next contention of appellant Moskowitz is that she was prejudiced by repeated statements in the prosecutor's



summation that the defense had failed to contradict the government's testimony. It is conceded that as a general rule a reference to the testimony for the prosecution as uncontradicted is not an indirect comment on the defendant's failure to testify, but the appellant contends that an exception exists where the only persons who could contradict the testimony are the defendants themselves. Assuming *arguendo* that such an exception should be recognized, we do not think that the appellant's case falls within it. The prosecutor's comments were general and made without express reference to Moskowitz. It is possible to explain them as covering occurrences as to which contradiction could have come from others than this appellant. For example, the comment to which objection was first interposed was the following: "The truth of the testimony offered here by Miss Bentley, Gold and others is conclusively established by the failure of the defense to produce one solitary word contradicting any of this testimony." In overruling the objection the court stated: "I will deal with that later properly myself." And in his charge the judge instructed the jury that they may not "infer guilt nor even draw a single unfavorable inference against the defendants because they did not take the stand." We think this was all that was required.

We turn now to Brothman's appeal. The court's charge limited the substantive crime to endeavoring to influence Gold to give false testimony, and the jury was told that the Government did not have to prove the success of the

<sup>1</sup> See *London v. United States*, 3 Cir., 296 F. 101; *Barnes v. United States*, 8 Cir., 8 F. 2d 832.

<sup>2</sup> See *Leffkovits v. United States*, 2 Cir., 273 F. 684, 688, cert. den., 257 U. S. 637; *United States v. Shapiro*, 2 Cir., 103 F. 2d 775, 776; *United States v. Di Carlo*, 2 Cir., 34 F. 2d 15, 17; *United States v. De Vito*, 2 Cir., 52 F. 2d 26, 30, cert. den., 284 U. S. 678; *Boehm v. United States*, 8 Cir., 123 F. 2d 761, 810.

endeavor. Concededly all of Brothman's "endeavors" to influence Gold's testimony took place in the eastern district of New York, although Gold's testimony was given in the southern district. The contention on appeal is failure of proof of venue. At the close of the prosecutor's case, Brothman moved for a directed verdict on count 2 on the ground that the evidence was insufficient. This motion was renewed at the end of the entire case. The Government's only answer to the appellant's argument is that Brothman waived his constitutional privilege to be tried where the crime was committed by going to trial in the southern district without objection. Where the indictment discloses lack of venue, going to trial without objection to venue is a waiver. *United States v. Jones*, 2 Cir., 162 F. 2d 72, 73. There is a dictum in *United States v. Michelson*, 2 Cir., 165 F. 2d 732, 734, aff'd, 335 U.S. 469, that the same result may follow if the defendant is warned of the defect during the course of the trial. In the case at bar Brothman could not know that venue would not be proved until the prosecutor's evidence was closed; he then moved for a directed verdict. We may assume *arguendo* that he argued the motion and said nothing about failure to prove venue; he might be held to have waived the defect. But the motion was denied without argument being heard. In *United States v. Jones*, 7 Cir., 174 F. 2d 746, Judge Minton (now Mr. Justice Minton), speaking for the court, held that a motion for acquittal made at the conclusion of all the evidence properly raised the question of venue in the court below. Such a motion need not specify the grounds therefor. We agree with the Seventh Circuit decision. Accordingly Brothman's conviction on count 2 must be reversed. The conviction of both appellants on the conspiracy count is affirmed.



RECORD PRESS—12-16-18 William St.—New York 38, N. Y.—REctor 2-2638  
135—7-27-512 □ USA—2362

BULKY EXHIBIT

Date received 7/20/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

128. Photostatic copy of paper entitled "Drawing #1" together with envelope addressed to N. GABORLULT, Pres., Techniflex Corp, Port Jervis, NY
129. Photostatic copy of paper entitled "Drawing #2" together with envelope addressed to OSCAR THALER, 3107 Bedford Avenue, Brooklyn, NY.
130. Photostatic copy of drawing showing various views and positions of a color television tube.

76

100-95068-1B

|                |         |
|----------------|---------|
| SEARCHED       | INDEXED |
| SERIALIZED     | FILED   |
| AUG 22 1951    |         |
| FBI - NEW YORK |         |

*[Signature]*



11-5-40

RECEIVED

NOV 5 1940

U.S. DEPT. OF JUSTICE

BULKY EXHIBIT

Date received 7/30/51

ABRAHAM BROTHMAN

100-95063-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal House of Detention

Purpose for which acquired Investigation

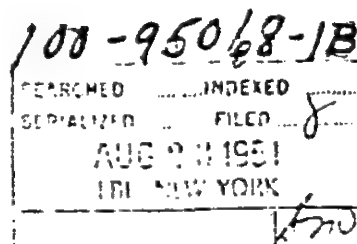
Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 131. Photostatic copy of paper entitled "Drawing #3."
- 132. Photostatic copy of paper entitled "Drawing #4."
- 133. Photostatic copy of paper entitled "Drawing #5."
- 134. Photostatic copy of paper entitled "The Mirascope for 20" Rectangular C R Tube.
- 135. Photostatic copy of envelope addressed to N. GABRIELT.



Dist. 1 - 1st book on the component of the  
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8. Contact wire formed from  $\frac{1}{8}$ " wire and  
insulated with 3 longitudinal layers to complete  
range. Contact wires  $\frac{3}{32}$ " apart.

9. 8. 86 Long Allen - Has not seen

*Peter Joseph Busch*

*M. Baskin, M.D., C. P. Thompson, D.P.M.*

mouth of horn (not thick as genuine) fit  
of shell of horn is to "10" get well before fit

*Handwritten:* 1/8 - 1/2 - 1/4 - 1/8 - 1/16 - 1/32 - 1/64 - 1/128 - 1/256 - 1/512 - 1/1024 - 1/2048 - 1/4096 - 1/8192 - 1/16384 - 1/32768 - 1/65536 - 1/131072 - 1/262144 - 1/524288 - 1/1048576 - 1/2097152 - 1/4194304 - 1/8388608 - 1/16777216 - 1/33554432 - 1/67108864 - 1/134217728 - 1/268435456 - 1/536870912 - 1/1073741824 - 1/2147483648 - 1/4294967296 - 1/8589934592 - 1/17179869184 - 1/34359738368 - 1/68719476736 - 1/137438953472 - 1/274877906944 - 1/549755813888 - 1/1099511627776 - 1/2199023255552 - 1/4398046511104 - 1/8796093022208 - 1/17592186044416 - 1/35184372088832 - 1/70368744177664 - 1/140737488355328 - 1/281474976710656 - 1/562949953421312 - 1/1125899906842624 - 1/2251799813685248 - 1/4503599627370496 - 1/9007199254740992 - 1/18014398509481984 - 1/36028797018963968 - 1/72057594037927936 - 1/144115188075855872 - 1/288230376151711744 - 1/576460752303423488 - 1/1152921504606846976 - 1/2305843009213693952 - 1/4611686018427387904 - 1/9223372036854775808 - 1/18446744073709551616 - 1/36893488147419103232 - 1/73786976294838206464 - 1/147573952589676412928 - 1/295147905179352825856 - 1/590295810358705651712 - 1/1180591620717411303424 - 1/2361183241434822606848 - 1/4722366482869645213696 - 1/9444732965739290427392 - 1/18889465931478580854784 - 1/37778931862957161709568 - 1/75557863725914323419136 - 1/151115727451828646838272 - 1/302231454903657293676544 - 1/604462909807314587353088 - 1/1208925819614629174706176 - 1/2417851639229258349412352 - 1/4835703278458516698824704 - 1/9671406556917033397649408 - 1/19342813113834066795298816 - 1/38685626227668133590597632 - 1/77371252455336267181195264 - 1/154742504910672534362390528 - 1/309485009821345068724781056 - 1/618970019642690137449562112 - 1/1237940039285380274899124224 - 1/2475880078570760549798248448 - 1/4951760157141521099596496896 - 1/9903520314283042199192993792 - 1/19807040628566084398385987584 - 1/39614081257132168796771975168 - 1/79228162514264337593543950336 - 1/158456325028528675187087900672 - 1/316912650057057350374175801344 - 1/633825300114114700748351602688 - 1/1267650600228229401496703205376 - 1/2535301200456458802993406410752 - 1/5070602400912917605986812821504 - 1/10141204801825835211973625643008 - 1/20282409603651670423947251286016 - 1/40564819207303340847894502572032 - 1/81129638414606681695789005144064 - 1/162259276829213363391578010288128 - 1/324518553658426726783156020576256 - 1/649037107316853453566312041152512 - 1/1298074214633706907132624082305024 - 1/2596148429267413814265248164610048 - 1/5192296858534827628530496329220096 - 1/10384593717069655257060992658440192 - 1/20769187434139310514121985316880384 - 1/41538374868278621028243970633760768 - 1/83076749736557242056487941267521536 - 1/166153499473114484112975882535043072 - 1/332306998946228968225951765070086144 - 1/664613997892457936451903530140172288 - 1/1329227995784915872903807060280344576 - 1/2658455991569831745807614120560689152 - 1/5316911983139663491615228241121378304 - 1/10633823966279326983230456482242756608 - 1/21267647932558653966460912964485513216 - 1/42535295865117307932921825928971026432 - 1/85070591730234615865843651857942052864 - 1/170141183460469231731687303715884105728 - 1/340282366920938463463374607431768211456 - 1/680564733841876926926749214863536422912 - 1/1361129467683753853853498429727072845824 - 1/2722258935367507707706996859454145691648 - 1/5444517870735015415413993718908291383296 - 1/10889035741470030830827987437816582766592 - 1/21778071482940061661655974875633165533184 - 1/43556142965880123323311949751266331066368 - 1/87112285931760246646623899502532662132736 - 1/174224571863520493293247799005065324265472 - 1/348449143727040986586495598010130648530944 - 1/696898287454081973172991196020261297061888 - 1/1393796574908163946345982392040522594123776 - 1/2787593149816327892691964784081045188247552 - 1/5575186299632655785383929568162090376495104 - 1/11150372599265311570767859136324180752990208 - 1/22300745198530623141535718272648361505980416 - 1/44601490397061246283071436545296723011960832 - 1/89202980794122492566142873090593446023921664 - 1/178405961588244985132285746181186892047843328 - 1/356811923176489970264571492362373784095686656 - 1/713623846352979940529142984724747568191373312 - 1/14272476927059598810582859694494951363827466

Re. Banking posts for country on the day

14. Full Page

*K. - 1980*

Mr. Charles French letter - may do the job by -

*The artist*

per 1/2" deflection standard steel

total length of the meridian  $\frac{3}{32}$

[illegible]

19 <sup>spiked</sup> ~~in depth~~ <sup>groove</sup> with  $\frac{1}{4}$ " <sup>radius</sup> ~~flat~~

Geo. Sturges, still attending to carbon work

*John Carter Smith*

23 wooden stake stock

End of the portion of hills in ~~###~~ #16

三、

*C. J. ...*





1. See Item "B"
2.  $\frac{3}{4}" \times \frac{3}{4}" \times \frac{1}{8}"$  aluminum angle spacers
3.  $\frac{1}{4}" \times \frac{1}{4}" \times \frac{1}{16}"$  aluminum angle rim
4. Indicates the position of the 6 equispaced Kennedy plates on the assembled unit.
5. Aluminum hull (machine from 4" o.d. x 18" l.s. tube stock, or from a 4" round stock piece)
6. 6 equispaced (on a 37" o.d.) holes, drilled and tapped for  $\frac{1}{8}"$  o. head machine screws  $\frac{1}{8}"$  lg.
7. 6 -  $\frac{1}{8}"$  o. head machine screws,  $\frac{1}{8}"$  lg.
8. 1000 Series,  $\frac{1}{4}"$  shaft size, ball bearing (packing fit into housing)
9. Aluminum cover plate (though indicated as a  $\frac{1}{4}"$  thick plate, a  $\frac{1}{16}"$  thick piece would more than suffice)
10. ditto (3)
11. 2 -  $\frac{1}{8}"$  diameter x  $\frac{5}{16}"$  lg. cap screws & nuts
12.  $\frac{1}{4}" \times \frac{1}{4}" \times \frac{1}{16}"$  aluminum angle end ring (R.H.) - ring to have 25  $\frac{1}{2}"$  o.d.
13. roller support member for R.H. end of inner drum; - 6 equispaced units, - see Item #1
14. Outer Drum End Ring (R.H. side)
15. Split Pulley Block (see Item #3)
16. Weld Steel anchor member for stationing shaft "second support" point (see Item #5)
17. S.A.E. 1020 machine steel tube stock stationing shaft machined as per Item #5
18. Hollow shaft component of C.R. Tube Support Assembly, - of same S.A.E. 1020 tube stock



19.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $1\frac{1}{2}$ " lg. by attaching anchor member (16) to hollow shaft (17)
20. Inguine member of anchor (see Dwg. # 3)
21.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{3}{4}$ " lg. cap screws and bolts - 2 ang.
22. From anchor plate to which (16) is tied (see Dwg. # 5)
23.  $1\frac{1}{2}$ " x  $1\frac{1}{2}$ " x  $\frac{1}{2}$ " angle iron to which (22) is welded (see Dwg. # 5)
24.  $\frac{3}{4}$ " x  $\frac{3}{4}$ " x  $\frac{1}{2}$ " angle iron leg of R.H. and A-Frame (see Dwg. # 5 for details and true relationship of A-frame members to one another and to drum)
25. Koston Riv. Works 3-2226-16 Plain Cylindrical Root-Boring bearings, one each end as indicated, machined to friction fit with interior of (17) and exterior of (26)
26. Outline of tube, indicating clearance of Outer Drive and - ring R.H. spoke from tube
27.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $1\frac{1}{2}$ " lg. by attaching bracket to hollow shaft member of C.R. Tube Support Assembly
28.  $2\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{3}{4}$ " lg. cap screws and bolts
29.  $\frac{1}{2}$ " mild steel plate, R-informed as indicated in Tube Support (Vet. Detail)
30.  $\frac{3}{4}$ " x  $\frac{3}{4}$ " x  $\frac{1}{2}$ " angle iron stiffener, welded down length of the underside of (29)
31.  $\frac{1}{2}$ " x  $\frac{3}{4}$ " x  $\frac{1}{2}$ " angle iron stiffener, running roughly half-way across the underside of support plate (29) at each of the two points of support by bracket
32.  $1\frac{1}{2}$ " x  $1\frac{1}{2}$ " x  $\frac{1}{2}$ " horizontal member of bracket
33. Bracket (see bracket detail)
34. Pressed Steel Clip to which Forming and Deflection Cords Bracket is attached

35.  $1\frac{1}{2} \times 1\frac{1}{2} \times \frac{1}{8}$  vertical member of bracket
36.  $\frac{3}{8} \times \frac{7}{8} \times \frac{1}{8}$  stiffener across width of underside of plate, welded to plate and to (30) as indicated in Front-End Elevation View of Tube Support Detail
37. In (31) and (35)
38. Angle of Tube Strap Member to Support Plate
39. Cover Area Tube Strap Member (See Front-End Elevation View of Tube Support Plate)
40. Hub of bracket, of  $2\frac{3}{4}$  O.D.  $\times 1\frac{1}{2}$  I.D. S.A.E. 1020 standard steel tube stock
41. Keyway for  $\frac{1}{2} \times \frac{1}{2} \times 1\frac{1}{2}$  key as per (27)
42.  $1 \times 1 \times \frac{1}{8}$  each arm of bracket
43.  $\frac{1}{8}$  thick stiffener plate welded to angle arms & hub
44. vulcanized neoprene rubber tubing forming soft shoulder for bottom side of C.R. Tube
45. Plywood has following contour of underside of tube
46. rubber lining to tube for (39)
47. flange of (31)
48. Nut for  $\frac{1}{2}$  diameter carriage bolt and wing-nut fastening between (39) and leg-member of strap



1. Shoulder bearing against inner race of ball bearing in Outer Drive R.H. End Ring Nut [NOTE: Shaft, at its reduced diameter, to be a running fit into inner race.]
2. Keyway for  $\frac{1}{2}$ " x  $\frac{3}{8}$ " key fixing Stationary Shaft against rotation in pillow block [NOTE: Keyway to extend for  $4\frac{1}{2}$ " in length from indicated R.H. end of shaft.]
3. Drill and Tap for  $\frac{3}{8}$ " set screw which threads into Stationary Shaft. Set of set screw into tapped hole to be "free fit". [NOTE: Lower  $\frac{1}{4}$ " of set screw to be machined down to  $\frac{1}{8}$ " and to fit snugly into corresponding hole in Hollow Shaft. Shoulder on set screw because of machined down end to seat tightly against inner Hollow Shaft.]
4. Keyway for  $\frac{1}{2}$ " x  $\frac{3}{8}$ " x  $1\frac{1}{2}$ " key between Stationary Shaft and Stationary Shaft Anchor.
5. Set screw, Allen Locks  $\frac{3}{8}$ " x  $\frac{1}{2}$ " of description in 3 rather than as indicated.
6. Keyway in Stationary Shaft Anchor matching 3.
7. End view of Anchor to have a snug fit into Stationary Shaft.
8. Square Shoulder Anchor.
9. Drill for  $\frac{1}{2}$ " hole passing thru.
10.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " drill for set screw going as indicated in Item # 3 above.
11. Keyway for  $\frac{1}{2}$ " x  $\frac{3}{8}$ " x  $1\frac{1}{2}$ " key between Bracket Nut and Hollow Shaft.
12. Drive Assembly.
13. Split Pillow Block support for R.H. End of Drive Assembly.
14.  $1\frac{1}{2}$ " x  $1\frac{1}{2}$ " x  $\frac{1}{2}$ " top member of A-frame (the studs "LB" and "LC")
15. ditto C.

16. Frame leg to weld (C) is weld.
17. 1" x 1" x 1/8" horizontal member to weld (D) is welded (see items "L3" and "L4")
18. Weld Plate (see item "L4") [NOTE: Actually <sup>each</sup> gusset plate will be 2 triangles as required by item "L3"] = 1/2" R
19. Weld Plate (see items "L4" and "L3") = 1/2" R
20. 1" x 1" x 1/8" horizontal member serving to stiffen and tie together beams of uprights, and as a base to which the counting down load detection element is attached
21. 1/4" x 1/4" x 1/8" back iron uprights
22. Weld Pad (see Detail "F")
23. T.V. Elements fastened to uprights by way of clips
24. Weld Plate (see item "L4")
25. Weld Plate (see item "L4")
26. 1/4" x 1/4" x 1/8" bolts



MR. N. GABORIAULT 7275

TECHNIFLEX CORP.

PORT JERVIS, NEW YORK

PERSONAL

BULKY EXHIBIT

Date received 8/3/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, N C

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 136. One photostatic copy of paper entitled "Drawing # 6.
- 137. One photostatic copy of paper entitled "Drawing #7.
- 138. One photostatic copy of drawing entitled "The Miriascope for a 20" Rectangular C R Tube Drawing #6.
- 139 One photostatic copy of drawing entitled " The Miriascope for a 20" Rectangular C R Tube Drawing #7.

100-95068-1B  
SEARCHED INDEXED  
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AUG 22 1951  
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1.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing (Bolt-Bridge) - [NOTE: See the "Bolt-Bridge Value", (E), which is an identical Thrust bearing as not shown in order that the bolted construction of the lower bar bearing be identical.]
2.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
3.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing
4.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
5.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
6.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
7.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
8.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
9.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
10.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
11.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
12.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
13.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
14.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
15.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
16.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
17.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support
18.  $\frac{1}{2}$  B. & S.  $\frac{1}{2}$  x  $\frac{1}{2}$  I. D. Thrust Bearing, welded as indicated to one leg of the support

19.  $\frac{1}{2}$ " R mild steel gusset, welded to inside of one leg of (3) and to baseplate. [NOTE: (3) should be similarly stiffened in the other direction as well.]
20. Keyway for  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $1\frac{1}{2}$ " lg. key between Main Drive Shaft and the hub of the Inner Drum Driven-End End Ring
21. Allen Headless Set Screw used to fix commutator holder into end of Main Drive Shaft. [NOTE: With the set screw engaged, the top of set screw is beneath the root of the indicated <sup>shaft</sup> threads. Threading of the shaft is to be done after the hole for the set screw has been drilled and tapped.]
22. 16 threads per inch, mach. thread, medium fit - to - locking-up nut. [NOTE: Locking-up nut to be driven with a lock-washer against the inner race of the  $1\frac{1}{2}$ " shaft-size bearing.]
23. Keyway for  $\frac{1}{2}$ " x  $\frac{1}{8}$ " x  $\frac{3}{8}$ " lg. key between gear (29) and Main Drive Shaft
24. Commutator & brush assembly for relay circuit
25.  $1\frac{1}{2}$ " shaft size ball bearing pillow block
26. Drive motor (further information, next communication)
27. Output shaft of drive motor, here taken to be  $\frac{1}{2}$ " x  $2\frac{1}{2}$ "
28. Helical Gear (specified on Dwg. #1) on output shaft of motor
29. " " " " " " " " Main Drive Shaft
30.  $1\frac{3}{4}$ " shaft size ball bearing pillow block
31.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{1}{2}$ " cap screw threaded into baseplate (43)
32.  ~~$\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{1}{2}$ " mild steel perpendicular~~ outboard bearing for output shaft of Motor Drive
33.  $1\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{1}{2}$ " cap screw and bolt to baseplate (42)
34. spoke of Outer Drum Driven-End End Ring



35. Spokes of Inner Drum Driven - End End Ring
36. Hub " " " " " " " "
37.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $1\frac{1}{2}$ " lg. key between Main Drive Shaft and Inner  
Drum Driven - End End Ring
38.  $1\frac{1}{2}$ " x  $1\frac{1}{2}$ " x  $\frac{1}{2}$ " structural steel, top horizontal member of L.H. A-frame
39.  $\frac{3}{4}$ " x  $\frac{3}{4}$ " x  $\frac{1}{2}$ " " " " & legs of L.H. A-frame
40. Horizontal member of A-frame knee - knee for baseplate (42)
41. steel " " " " " " " "
42.  $\frac{1}{2}$ " R mild steel baseplate for L.H. end assembly
43. Template for  $1\frac{1}{2}$ " shaft size pillow block
44. cap screw and bolt for connecting motor to baseplate (47) - 1 set
45.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{1}{2}$ " structural steel & stiffener for baseplate (47) - 2 set
46.  $\frac{1}{2}$ " R mild steel gusset tying (47) to baseplate (42)
47.  $\frac{1}{2}$ " R mild steel baseplate for Drive Motor
48.  $\frac{1}{2}$ " R cap screw threading into baseplate (47) to tie (48) to (43)
49.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{1}{2}$ " lg. cap screw and bolt tying baseplate (47) to knee  
base (48)





22.  $\frac{1}{8}$ " R mild steel baseplate for attachment of Brake Assembly (11)
23.  $\frac{1}{8}$ " R " " stiffener plates for (23)
24.  $1" \times 1" \times \frac{1}{8}"$  structural steel  $\frac{1}{8}$ " horizontal member of L. H. A-frame
25.  $\frac{1}{8}$ " R mild steel gusset - 2 req., running between (19) and (24)
26. foot plate - see details of R. H. A-frame
27.  $\frac{1}{8}$ " R mild steel gusset plate running between bottom plate of Positioner "3" fixture and one leg of (19)
28.  $\frac{1}{8}$ " R mild steel vertical baseplate of Positioner "3" fixture
29.  $\frac{1}{8}$ " R mild steel gusset between bottom plate and (28) of Positioner "3" assembly fixture
30. forward gusset plate, identical with (29)
- \* NOTE - The true shape of (27) and the <sup>true</sup> position of (29) with respect to the main axis of (19) are to be such as to satisfy the orientation axis indicated for the fixture in Item "FA"
31.  $\frac{1}{8}$ " R mild steel <sup>topside</sup> gusset running between (33) and one leg of (19)
32.  $\frac{1}{8}$ " R mild steel bottomside gusset running between (33) and the other leg of (19)
33. bottom plate member of Positioner "A" attachment fixture
34. forward gusset running between (33) and (35)
35. vertical baseplate of Positioner "A" attachment fixture
- \* NOTE - The true shapes of (31) and (32) are to be such as to satisfy the orientation axis indicated for the fixture in Item "FA"

BULKY EXHIBIT

Date received 7/30/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit Incabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

140. Two photostatic copies of drawing entitled "The Miriascope for a 20" Rectangular C.R. Tube, Drawings 4 & 5" together with photostatic copy addressed to N. GABORIAULT, Pres, Techniflex Corp, Port Jervis, NY

100-95068-1B

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| SEARCHED       | INDEXED |
| SERIALIZED     | FILED   |
| AUG 23 1951    |         |
| FBI - NEW YORK |         |

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BULKY EXHIBIT

Date received 8/13/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit retain

List of contents:

- 141. Two photostatic copies of letter dated 8/10/51 to J.F. & S.E.A.
- 142. Two photostatic copies of paper entitled "Errata, Addenda, & Comments.
- 143. Two photostatic copies of pages numbered 112-117.
- 144. Two photostatic copies of paper entitled Drawing #8 together with drawing.
- 145. Two photostatic copies of paper entitled Drawing #9 together with drawing.

100-95068-1B

SEARCHED INDEXED  
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AUG 14 1951  
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80

8/10/51

To: J.F.  
S.E.A.

Re: - Synchronizing Arrangements  
for C.B.S. color-TV

I note which I received from Name today indicated that perhaps my message relative to the construction of a special motor for C.B.S. color-wheel or color-driven units had been misinterpreted. I may have talked with Jack, he conveyed to me the thought that S.E.A. was thinking in terms of a special combination of a synchronous and an induction motor (a specially constructed motor) which would pick up the vertical scanning pulse via any of a number of mechanical linkages. In the message I gave Name, I expressed my opinion against such a project both from a technical and from a commercial point of view. I am inclined towards servo-type between the vertical pulse and the Drive Motor, but, as differentiator between the two I have seen that C.B.S. does, I believe that the driving or forcing section of the servo should operate something like a variable in its operating characteristics than a controllable reluctance. The thought on which I wanted a decision was whether to take the time now to design a servo of the type I have in mind, or whether I should leave this till later and proceed with Jack's orders with the design of a larger size (I think 3" motor-wheel - say a color-wheel for a 14" tube) or smaller. I believe that the servo which I have in mind, as would involve an eddy current (a very light eddy current) and against a standard motor would be especially suited to the device I have designed.

Please discuss this with S.E.A. and let me have your opinion. I was informed today that drawings 6, 7, 8, & 9 sent Friday of last week Wednesday of this week in two equal shipments have not arrived. I believe that the material contained in these drawings is most essential to the device in construction. Please see that the finished device conforms to these drawings and that the original drawings are contained on the



8/10/51

To: J. F.  
S. E. A.

RE: - Synchronizing Arrangement  
for C.B.S. color-TV

Today

A note which I received from Harrie today indicated that perhaps my message relative to the construction of a special motor for CBS color-wheel or color-drum which had been misconstrued. In my last talk with Jack, he conveyed to me the thought that S. E. was thinking in terms of a special combination of a synchronous and an induction motor (a specially constructed motor) which would "dead lock" to the vertical scanning pulse via any of a number of drive servo linkages. In the message I gave Harrie, I expressed my opinion against such a project both from a technical and from a commercial point-of-view. I am inclined towards servo-type link between the vertical pulse and the Drive Motor, but, as differentiated from the servo I have seen that CBS uses, I believe that the driving or guiding section of the servo should operate something a bit more stable in its operating characteristics than a saturable reactor. The thought on which I wanted a decision was whether I should take the time now to design a servo of the type I have in mind, or whether I should leave this till later and proceed according to Jack's orders with the design of a larger size (than 32" color-wheel - say a color-wheel for a 14" tube) immediately. I believe that the servo which I have in mind, and which would employ an eddy current (a very light eddy current) to operate against a standard motor would be especially suited to the device I have designed.

Please discuss this with S. E. and let me have your opinion. I was informed today that drawings 6, 7, 8, & 9 sent Friday of last week Wednesday of this week in two equal shipments have not arrived. Material contained on these drawings is most essential to the device in construction. Please see that the finished device accords these drawings. Important revisions of the original designs are contained on these.

sent out

# ERRATA, ADDENDA, & COMMENTS

RE: PAGES 101-111.

## IMPORTANT

[NOTE: Check relay C9 on Dwg. #9. The set of contacts in C9 delivering phase supply to the Drive Motor should be a normally-closed set. If Dwg. #9 indicates otherwise, it should be revised in this regard.]

## DIFFERENCES BETWEEN THE ORIGINALLY-SUBMITTED CONTROL CIRCUIT & THE ONE GIVEN ON DWG. #9

A proposed control circuit for the microscope was submitted as Sheet #19 of the original group of sketches, and, the originally-submitted control circuit was the basis of the document, pages 101-111, entitled "Description of the Drive Alignment Control Circuit" since the microscope control circuit, as submitted on Dwg. #9 differs in some respects from that given on Sheet #19, the descriptive material given on pages 101-111 will not correspond exactly to the facts of the latterly-submitted circuit. Therefore, the document is submitted to amend and correct page 101-111 wherever this is required.

The microscope control circuit, as given on Dwg. #9 differs from that given on the above-mentioned sheet #19 in the following principal respects:-

- a) <sup>on Dwg. #9</sup> The signal from the downstream side of the normally-open set of load contacts in the Inductor Relay C3 is passed to the timing relay C8 and to the <sup>56</sup>coils of



Positioner "A" via a normally-closed set of load contacts in the mechanically-held relay C16; while, on Alt. #19, the same signal is passed directly from the mentioned set of load contacts in C3 to C8 and C6 without any interposed relay effects;

b) on Diag. #9, C15 is indicated as a mechanically-held relay, while on Alt. #19 it appears as a conventional relay;

c) on Diag. #9, the mechanically-held relay C9 appears as a 3 N.O. - 1 N.C. unit, the mechanically-held relay C10 as a 2 N.O. - 1 N.C. unit, and the mechanically-held relay C7 as a 2 N.O. - 1 N.C. unit. On Alt. #19, C9 appears as a 2 N.O. - 2 N.C. unit, C10 as a 2 N.O. unit, and C7 as 1 N.O. - 1 N.C. unit;

and,

d) in accordance to the above-mentioned equipment changes, certain details of the functional patterns have been altered.

The addition of C16 to the circuit as per (c) has been for the purpose of providing for the disengagement of C6 and C8 after the re-alignment of the Drums for "black-and-white" viewing has been achieved. By so doing, any A.C. chatter associated with the continued engagement of C6 [the solenoid member of Positioner "A"] and C8 [the on-delay timing relay] is eliminated, and, further, any disturbing effects due to the a continued feeding of these equipment elements is eliminated.

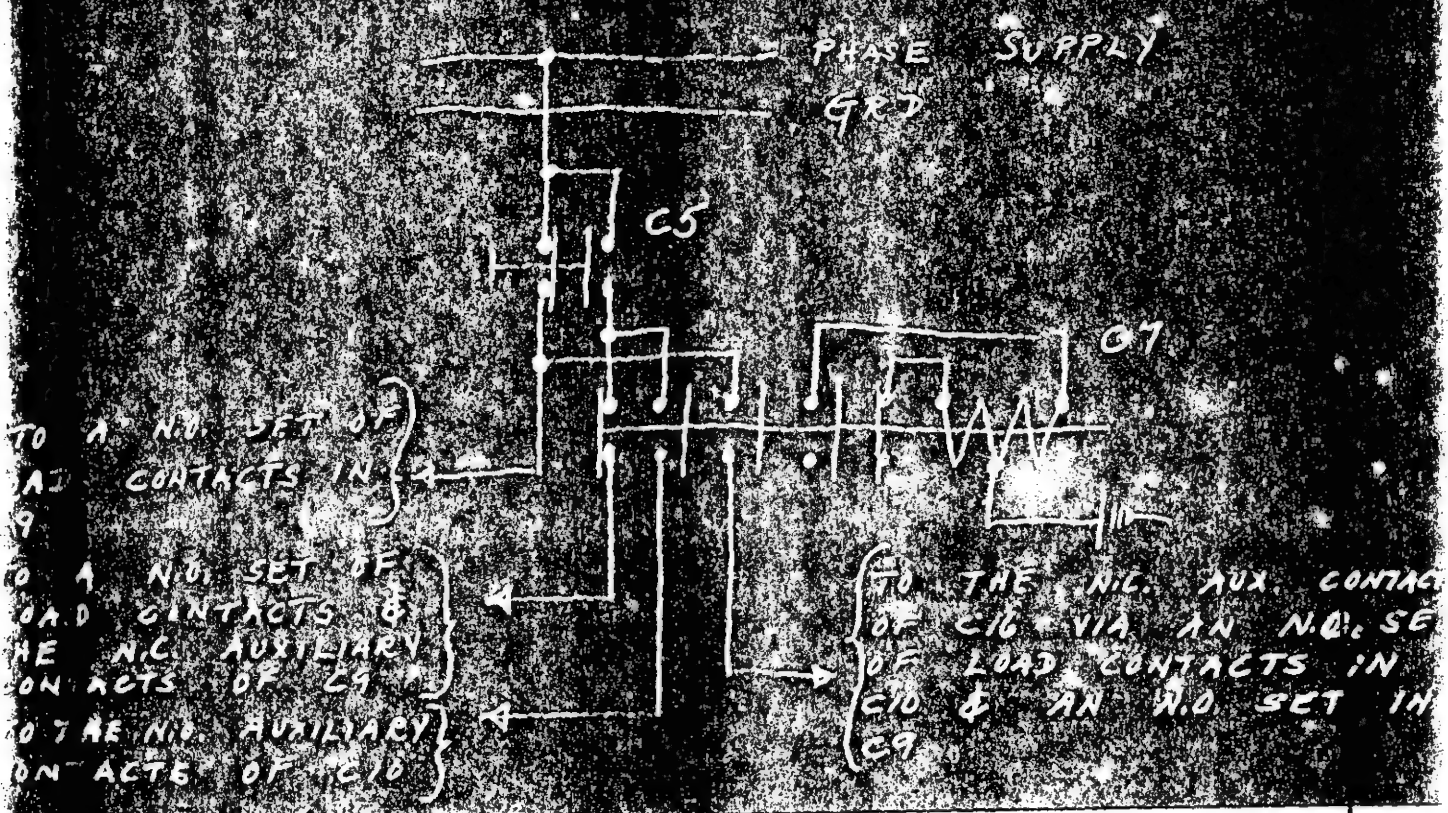
Associated with the addition of C16 to the "black-and-white" alignment section of the control circuit are the above-noted changes in the specifications for C10 and C7 and, in part, the changes in the specifications for C9. From a reading of pages 101-111, it will be observed that -

- A. when the arresting of the Drum Assembly and the disengagement of the latch-pawl from Knob "A" is accomplished as the first step in the re-alignment of the two drums for black-and-white viewing, C9 is ~~then~~ engaged;
- B. after C9 is engaged following the event mentioned in (A), C10 is engaged;
- and,
- C. after C10 is engaged as a consequence of the engagement of C9 and after the drawing motion of Drum #2 above results in the return of the latch-pawl to a position where it no longer trips the actuator of the Permit Limit Switch, C7 is engaged.

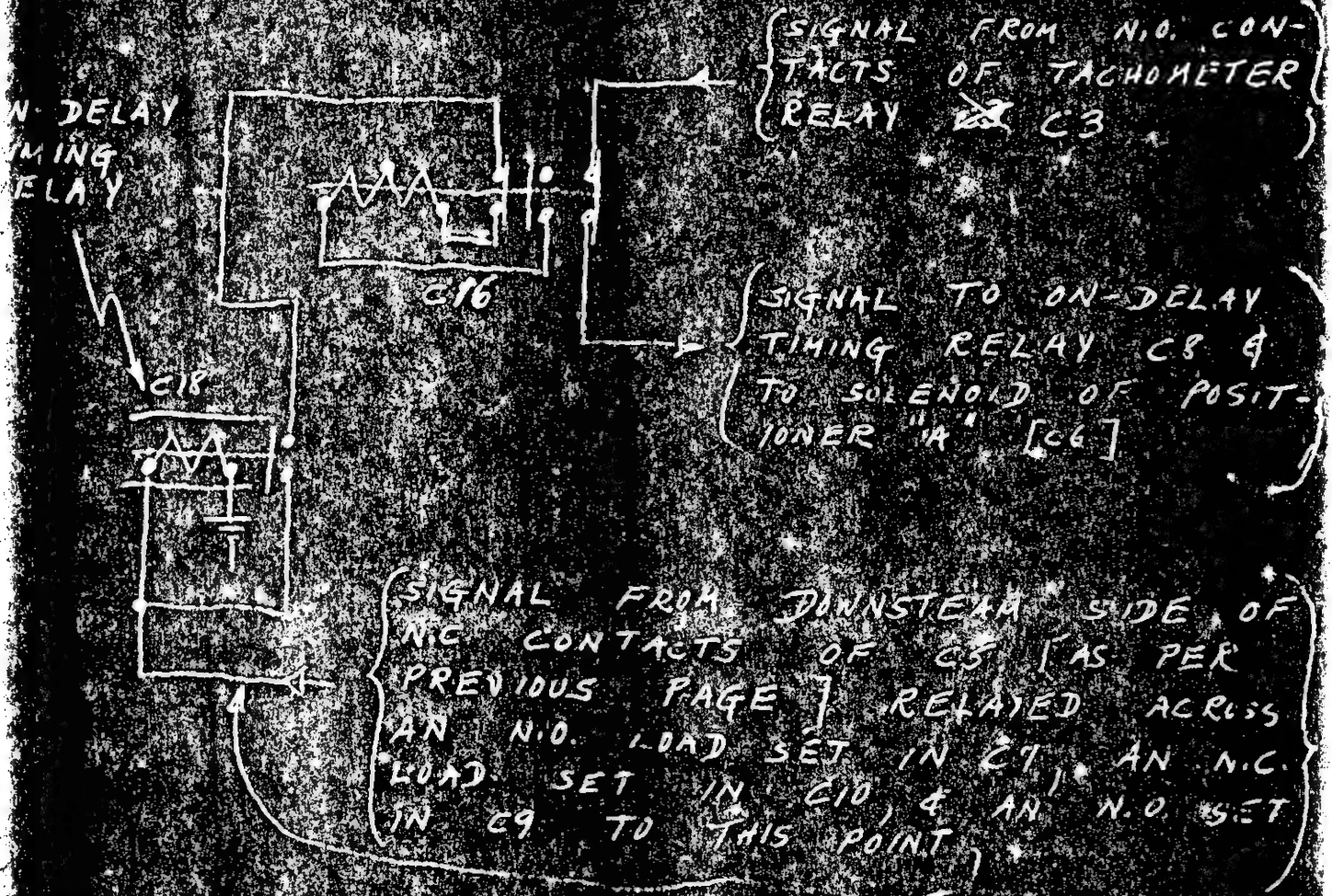
Studying the Meriscope Control Circuit as given on Diag. # 9, it will be seen that when C7 and C9 are engaged, and C10 is disengaged, a path is opened for a signal starting from phase supply, and after transmission ~~is~~ over an appropriate set of contacts in each of the mentioned relays, terminating at the normally-closed set of auxiliary contacts of the mechanically-held relay C16. The necessary conditions for the opened path, namely that C7 and C9 be engaged while C10 be disengaged, are fulfilled as a sequel to item (C) above. From pages 101-111, it will be found that after C7 is engaged as per (C) above, C10's disengagement is made responsive to a signal starting from the normally-open set of contacts in the limit switch C5. This signal which is transmitted across a normally-open set of load contacts in C5 to the normally-open set of auxiliary contacts in C10 occurs when the latch-pawl of Drum #2 has already moved the approach block of Knob "B" during the Drum's travel towards its black-and-white viewing required position. It will also be found in the "Description . . .", pages 101-111, that the movement of the approach block of Knob "B" by the latch-pawl member of Drum #2 is followed shortly thereafter by a locking of the latch-pawl



in the grab slot of Knob "B", signifying the arrival of Drum #2 at a position which is consistent with a proper alignment of the clear slot of Drum #2 with a clear slot in Drum #1 for the purpose of black-and-white viewing. Thus, since the signal which which engages C16 (and consequently disengages C6 [the arrival of Positioner "A"]") occurs when the locking action between the two Drums is impending rather than completed, it may be argued that a possibility exists that the ultimate absorbing of the flywheel energy of Drum #2 and the rotor of the Drive Motor could act to rotate the Drum Assembly's position past the "window" in the cabinet. To obviate this possibility, it would be possible practical to draw the same signal for the disengagement of C16 from the downstream side of the normally-closed set of contacts of C5 instead of from phase supply as now indicated on Diag. #9. This scheme is illustrated below:-



By the action illustrated above, the signal engaging C16, and consequently disengaging the Drum Assembly-arresting action of the plunger of Positioner "A", would await the completion of the locking-action between the Drums. This means, as well, that the newly-aligned Drums would be prevented from slipping past the 'window' in the cabinet. Any further assurance that the newly-aligned Drums should not slip past the 'window' would be obtained from introducing a time-delay factor between the completion of the afore-mentioned locking-action and the retraction of the Plunger of Positioner "A" from the drill hole of Knob "A". If this were done, then a way of doing it would be as indicated below:-





Of the matter raised on page 202, only one has thus far not been discussed, and that is Item (b) dealing with relay C15. On Mt. #19, as is recalled in Item (b), C15 was indicated as a conventional relay; while on Diag. #9, it appears as a mechanically-held relay. Two reasons underlie the change, of which the first is the more important -

1. Mt. #19 indicates that the prime signal for the engaging of C15 originates at the N.C. contacts of C5, is transmitted across an N.O. load set in C9, to an N.O. set in C14, is then transmitted across an N.O. set in C14 to an N.C. load set in C12 to an N.O. set in C11, and, finally, is then applied to the place-side of the operating coil of the conventional relay C15. This would demand that C9 be in its engaged position, C14 be engaged, that C12 be disengaged, and that C11 be engaged for C15 to be continuously engaged during color viewing. However, since the engagement of C14 is dependent on C15 being disengaged, it follows that the engaging of C15 would lead to the disengagement of C14, which would in turn lead to the secondary disengagement of C15 — and ultimately to a shattering relationship between C14 and C15. This is the prime reason for the change shown on Diag. #9.

The second reason lies in the inadvisability of C15, or any other relay, being continuously energized during the operation of the TV circuit, since A.C. chatter and electrical disturbances to the operation of the TV circuit are possible. By making C15 a mechanically-held relay, the permanent engagement of C15 prior to

the disengagement of C14 is assumed; and, once, the engagement of C15 is reestablished, it holds that engagement without any further feed of power. The latter fact satisfies the above-mentioned condition that no member of the switching circuit be capable of "clattering" or demand a continued feed of power during any viewing cycle, other than - possibly - the Facsimile Relay.

As C15 is now specified, its engagement follows the completion of the drum-re-alignment action, for the engagement signal is transmitted along the following path:

- a) the signal originates at the downstream side of the N.C. contacts of C5, which means that the latch-pawl of Drum #2 must be in its "low" position;
- b) the signal as of (a) is relayed across a normally-open load set in C7, which means that C7 must be engaged - and this condition is satisfied since C7's position is reversed only after C15 is engaged;
- c) the signal as of (b) is applied from the downstream side of the N.O. load set in C7 to the upstream side of an N.O. set in C13, which means that C14 must be engaged for the further relaying of the signal - and this is satisfied since C14 is engaged as long as C2 is in its "color" position and C15 is disengaged;
- d) the signal as of (c) is applied from the downstream side of the N.O. set in C14 to the upstream side of a N.C. set in C12, which means that C12 must be disengaged for the further relaying of the signal



— and this condition is satisfied by the fact that C12 is restored to its disengaged position once the latch-pawl of Drum # 2 is brought to a given state of 'left' by the approach block of Knot "A"

and,

e) the signal as of (d) is relayed from the downstream side of the N.C. lead set in C12 to an N.O. lead set in C11, which means that C11 must be in its engaged position for further relaying of the signal — and this condition is satisfied by the fact that C11 is sent into its engaged position by the 'drift' of Drum # 2 past the departure block of Knot "B" during the travel of Drum # 2 towards its color-aligned position with Drum # 1, and further C11 maintains its engaged position until the next black-and-white relaying alignment is signalled.

The signal as of (e) is then applied to C15. Since the 'left' of the latch-pawl by the approach block of Knot "A" imminently precedes the locking of Drum # 2 into its color-alignment position with Drum # 1, it follows that C15 is engaged only as color-alignment of the two drums is achieved or is imminently about to be achieved. By the reference of the Control Circuit given on Page 115, it would follow that C15 would ~~then~~ engage to release Positioner "B", disengage C14, and return C9 and C7 to their disengaged positions, only after <sup>the</sup> color-alignment of the two drums has been achieved.

Thus the (b) on Page 202 is explained!

## TWO IMPORTANT CONSIDERATIONS:

Two important considerations underlying the projected design of the Control Circuit. These are:-

- a) the type of mechanically-held relay used
- b) the timing behind the release of Section "A" after black and white alignment has been achieved.

It has been repeatedly set forth above that one of the functions served by the use of mechanically-held relays was to eliminate chatter and electrical disturbances to the operation of the TV circuit when the functional demands on any given relay demands its continued engagement. This set of qualifications more or less define the type of relay which is required. Explicitly, it would be required that:-

1. the holding of the relay's engaged position be accomplished either by a mechanical or a magnetic latch
2. a second operating coil which overcomes the mechanical or magnetic latching action be a part of the relay.

Mechanical latches for the holding of relays in their engaged positions are extremely common; and, in fact, the same — mechanical held relay — is derived from the original use of such mechanical latches. More recently, it has been common to replace mechanical latches by permanent magnets which hold the relay-plunger once the plunger is drawn against the permanent magnet pole-face. The latter type of construction, which has been referred to as a magnetic latch, is preferred here, since strictly mechanical latches are subject to imperfect operation when the baseboards to which they are attached are jammed.

Finally as regards the mechanically-held relays used, it



should be observed that to ensure the best operation of such a relay, the two operating coils of the relay — the one which acts to engage the relay, and the other which acts to disengage or de-latch the relay — should be signalled thru auxiliary contacts which are operated in common with the load contacts. The contacts which are auxiliary to the engaging action — the N.C. auxiliary contacts — should have a 'dragging effect' incorporated in them to assure the completion of the engaging stroke against a spurious or 'chattering' making action.

If the construction schedule for the models permits, I will design a set of relays suited in size and other characteristics to the demand of the Control Circuit.

On the subject of the decision to disengage Positioner "A" after black and white alignment of the Drive has been achieved, it has been held here that the inertia of the Drive Assembly and the Drive Motor rotor, plus the friction forces between the gears constituting the power transmission, would be sufficient to hold any previously established position once the desired Drive Assembly alignment and positioning in front of the cabinet window has been achieved. The further argument that a continued energizing of the Positioner solenoid might lead to chattering and also the electrical disturbances to the T.V. circuit in normal operation led to one of two solutions:-

A. either construct the Positioner potentiometer along mechanically-held lines,

or, B. hold any given Drive Assembly position on the basis of the inertia and friction forces named above.

The latter was chosen for the reason of the costs involved in the former alternative.

\* NOTE:- Will regard to item (A), see page 204 and 205

ERRATA, ADDENDA, & COMMENTS

RE: PAGES 101-111

\* \* \* \* \*

IMPORTANT

[NOTE:- Check relay C9 on Dwg. #9. The set of contacts in C9 delivering phase supply to the Drive Motor should be a normally-closed set. If Dwg. #9 indicates otherwise, it should be revised in this regard.]

\* \* \* \* \*

DIFFERENCES BETWEEN THE ORIGINALLY-SUBMITTED CONTROL CIRCUIT & THE ONE GIVEN ON DWG. #9 -

A proposed control circuit for the Mesoscope was submitted as Sheet #19 of the original group of sketches; and, this originally submitted Control Circuit was the basis of the document, pages 101-111, entitled "Description of the Drive Alignment Control Circuit" since the "Mesoscope Control Circuit" as submitted on Dwg. #9 differs in some respects from that given on Sheet #19, the descriptive material given on pages 101-111 will not correspond exactly to the facts of the latterly-submitted circuit. Therefore, this document is submitted to amend and correct pages 101-111 wherever this is required.

The 'Mesoscope Control Circuit' as given on Dwg. #9 differs from that given on the above-mentioned Sht. #19 in the following principal respects:-

- a) <sup>(see Dwg. #9)</sup> The signal from the downstream side of the normally-open set of load contacts in the Tachometer Relay C3 is passed to the timing relay C5 and to the forward of



Positioner "A" via a normally-closed set of load contacts in the mechanically-held relay C16; while, on Ltr. #19, the same signal is passed directly from the mentioned set of load contacts in C3 to C8 and C6 without any interposed relay effects;

b) on Dwg. #9, C15 is indicated as a mechanically-held relay, while on Ltr. #19 it appears as a conventional relay;

c) on Dwg. #9, the mechanically-held relay C9 appears as a 3 N.O. - 1 N.C. unit, the mechanically-held relay C10 as a 3 N.O. - 1 N.C. unit, and the mechanically-held relay C7 as a 2 N.O. - 1 N.C. unit. On Ltr. #19, C9 appears as a 2 N.O. - 2 N.C. unit, C10 as a 2 N.O. unit, and C7 as 1 N.O. - 1 N.C. unit;

and,

d) in correspondence to the above-mentioned equipment changes, certain details of the functional patterns have been altered.

The addition of C16 to the circuit as per (a) has been for the purpose of providing for the disengagement of C6 and C8 after the re-alignment of the frame for "black-and-white" viewing has been achieved. By so doing, any A.C. chatter associated with the continued engagement of C6 [the solenoid member of Positioner "A"] and C8 [the on-delay timing relay] is eliminated; and, further, any disturbing effects due to the continued feeding of these equipment items is eliminated.

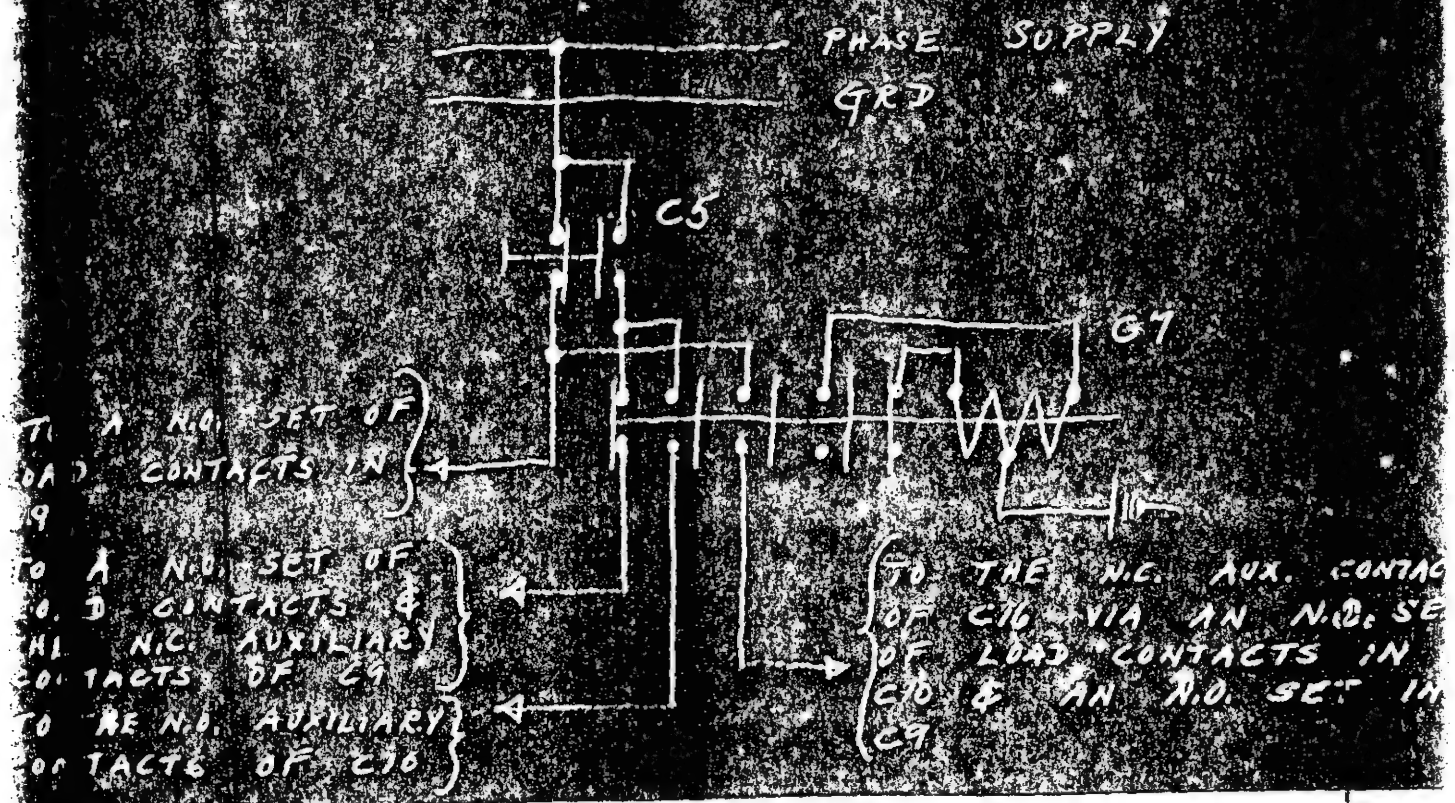
Associated with the addition of C16 to the "black-and-white" alignment section of the control circuit are the above-noted changes in the specifications for C10 and C7 and, in part, the changes in the specifications for C9. From a reading of pages 101-111, it will be observed that -

- A. when the resetting of the Drum Assembly and the disengagement of the latch-pawl from Knob "A" is accomplished as the first step in the re-alignment of the two drums for black-and-white viewing, C9 is ~~then~~ engaged;
- B. after C9 is engaged following the event mentioned in (A), C10 is engaged;
- and,
- C. after C10 is engaged as a consequence of the engagement of C9 and after the ensuing rotation of Drum #2 alone results in the return of the latch-pawl to a position where it no longer trips the actuator of the Permit Limit Switch, C7 is engaged.

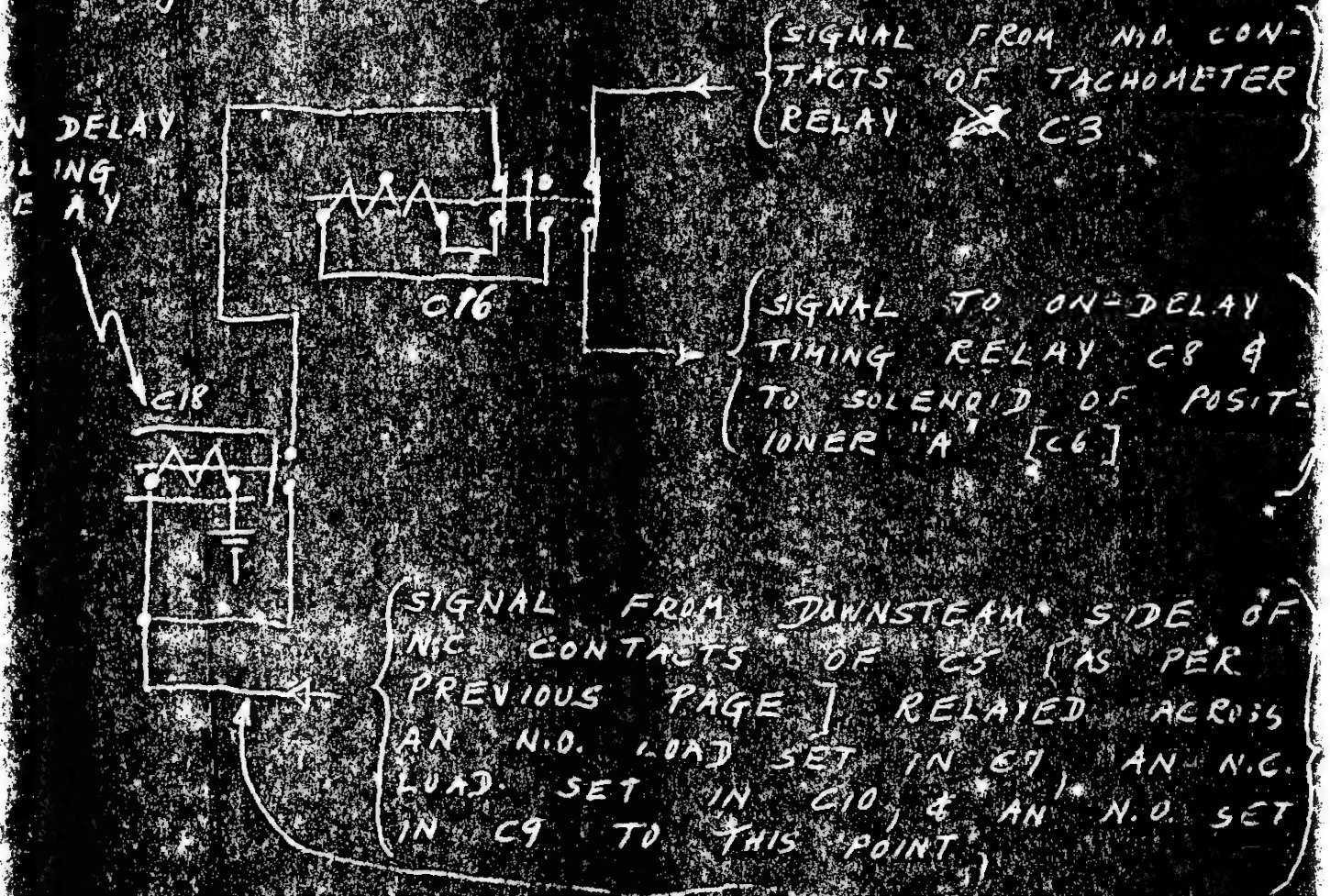
Studying the Mixoscope Control Circuit as given on Diag. #9, it will be seen that when C7 and C9 are engaged, and C10 is disengaged, a path is opened for a signal starting from phase supply, and after transmission ~~of~~ over an appropriate set of contacts in each of the mentioned relays, terminating at the normally-closed set of auxiliary contacts of the mechanically held relay C16. The necessary conditions for the open path, namely that C7 and C9 be engaged while C10 be disengaged, are fulfilled as a result to item 2) above. From pages 101-111, it will be found that after C7 is engaged as per (C) above, C10's disengagement is made responsive to a signal starting from the normally-open set of contacts in the limit switch C5. This signal which is transmitted across a normally-open set of load contacts in C9 to the normally-open set of auxiliary contacts in C10, occurs when the latch-pawl of Drum #2 has already started the approach block of Knob "B" during the Drum's travel towards its black-and-white viewing required position. It will be found in the "Description . . . .", pages 101-111, that the starting of the approach block of Knob "B" by the latch-pawl member of Drum #2 is followed shortly thereafter by a blocking of the latch-pawl



in the grab slot of Grab "B", signifying the arrival of Drum #2 at a position which is consistent with a proper alignment of the clear slot of Drum #2 with a clear station in Drum #1 for the purpose of black-and-white viewing. Thus, since the signal which which engages C16 (and consequently disengages C6 [the solenoid of Positioner "A"]) occurs when the locking action between the two Drums is impending rather than completed, it may be argued that a possibility exists that the ultimate absorbing of the flywheel energy of Drum #2 and the rotor of the Drive Motor could act to rotate the Drum Assembly's position past the "window" in the cabinet. To obviate this possibility, it would be possible practical to draw the prime signal for the disengagement of C16 from the downstream side of the normally-closed set of contacts of C5 instead of from phase supply as now indicated on Diag. #9. This scheme is illustrated below:



By the scheme illustrated above, the signal engaging C16, and consequently disengaging the Drum Assembly - arresting action of the plunger of Positioner "A", would await the completion of the locking - action between the Drums. This means as well that the newly-aligned Drums would be prevented from slipping past the 'window' in the cabinet. Any further assurance that the newly-aligned Drums should not slip past the 'window' would be obtained from introducing a time-delay factor between the completion of the above-mentioned locking - action and the retraction of the Plunger of Positioner "A" from the drill-hole of Knob "A". If this were done, then a way of doing it would be as indicated below -





Of the matter raised on page 202, only one has thus far not been discussed, and this is Item (b) dealing with relay C15. On Dwg. #19, as is recalled in Item (b), C15 was indicated as a conventional relay; while on Dwg. #9, it appears as a mechanically-held relay. Two reasons underlie the change, of which the first is the more important -

1. Dwg. #19 indicates that the prime signal for the engaging of C15 originates at the N.C. contacts of C5, is transmitted across an N.O. load set in C9 to an N.O. set in C14, is then transmitted across an N.O. set in C14 to an N.C. load set in C12 to an N.O. set in C11, and, finally, is then applied to the place side of the operating coil of the conventional relay C15. This would demand that C9 be in its engaged position, <sup>that</sup> C14 be engaged, that C12 be disengaged, and that C11 be engaged for C15 to be continuously engaged during color-viewing. However, since ~~the~~ the engagement of C14 is dependent on C15 being disengaged, it follows that the engagement of C15 would lead to the disengagement of C14, which would in turn lead to the secondary disengagement of C15 — and ultimately to a chattering relationship between C14 and C15. This is the prime reason for the change shown on Dwg. #9;
2. the second reason lies in the inadvisability of C15, or any other relay, being continuously energized during the operation of the TV circuit, since A.C. chatter and electrical disturbances to the operation of the TV circuit are possible. By making C15 a mechanically-held relay, the permanent engagement of C15 prior to

the disengagement of C14 is assured; and, once, the engagement of C15 is established, it holds that engagement without any further feed of power. The latter fact satisfies the above-mentioned conditions that no member of the switching circuit be capable of "chattering" or demand a continued feed of power during any viewing cycle, other than - possibly - the Tachometer Relay.

As C15 is now specified, its engagement follows the completion of the drum-re-alignment action, for the engagement signal is transmitted along the following path:-

- a) the signal originates at the downstream side of the N.C. contacts of C5, which means that the latch-pawl of Drum #2 must be in its "low" position;
- b) the signal as of (a) is relayed across a normally-open load set in C7, which means that C7 must be engaged - and this condition is satisfied since C7's position is reversed only after C15 is engaged;
- c) the signal as of (b) is applied from the downstream side of the N.O. load set in C7 to the upstream side of an N.O. set in C14, which means that C14 must be engaged for the further relaying of the signal - and this is satisfied since C14 is engaged as long as C2 is in its "color" position and C15 is disengaged;
- d) the signal as of (c) is applied from the downstream side of the N.O. set in C14 to the upstream side of an N.C. set in C12, which means that C12 must be disengaged for the further relaying of the signal



— and this condition is satisfied by the fact that C12 is restored to its disengaged position once the latch-pawl of Drum # 2 is brought to a given state of 'lift' by the approach block of Crab "A" and,

- e) the signal as of (d) is relayed from the downstream side of the N.C. load set in C12 to an N.O. load set in C11; which means that C11 must be in its engaged position for further relaying of the signal — and this condition is satisfied by the fact that C11 is sent into its engaged position by the 'drift' of Drum # 2 past the departure block of Crab "B" during the travel of Drum # 2 towards its color-aligned position with Drum # 1, and further C11 maintains its engaged position until the next black-and-white relaying alignment is signalled.

The signal as of (c) is then applied to C15. Since the 'lift' of the latch-pawl by the approach block of Crab "A" imminently precedes the locking of Drum # 2 into its color-alignment position with Drum # 1, it follows that C15 is engaged only as color-alignment of the two drums is achieved or is imminently about to be achieved. By the refinement of the control circuit given on Page 115, it would follow that C15 would ~~also~~ engage to release Position "B", disengage C14, and return C9 and C7 to their disengaged positions, only after <sup>the</sup> color-alignment of the two drums has been achieved. This too (b) on Page 202 is explained!

## TWO IMPORTANT CONSIDERATIONS:

Two important considerations underly the projected design of the Control Circuit. These are: -

- a) the type of mechanically-held relay used
- and b) the timing behind the release of Position "A" after black-and-white alignment has been achieved.

It has been repeatedly set forth above that one of the functions served by the use of mechanically-held relays was to eliminate chatter and electrical disturbances to the operation of the TV circuit whilst the functional demands on any given relay demands the continued engagement. This set of qualifications more or less defines the type of relay which is required. Explicitly, it would be required that: -

1. The holding of the relay's engaged position be accomplished either by a mechanical or a magnetic latch
- and 2. a second operating coil which overcomes the mechanical or magnetic latching action be a part of the relay.

Mechanical latches for the holding of relays in their engaged positions are extremely common, and, in fact, the name - mechanical held relay - is derived from the original use of such mechanical latches. More recently, it has been common to replace mechanical latches by permanent magnets which hold the relay plunger once the plunger is drawn against the permanent magnet pole-face. The latter type of construction, which has been referred to as a magnetic latch, is preferred here, since strictly mechanical latches are subject to improper operation when the baseboards to which they are attached are jarred.

Finally as regards the mechanically-held relays used, it



should be observed that to ensure the best operation of such a relay, the two operating coils of the relay — the one which acts to engage the relay, and the other which acts to disengage or de-latch the relay — should be signalled from auxiliary contacts which are operated in common with the load contacts. The contacts which are auxiliary to the engaging action — the N.C. auxiliary contacts — should have a 'dragging effect' incorporated in them to ensure the completion of the engaging stroke against a spurious or chattering 'making' action.

If the construction schedule for the models permits, I will design a set of relays suited in size and other characteristics to the demand of the Control Circuit.

On the subject of the decision to disengage Portioner "A" after black-and-white alignment of the Drum has been achieved, it has been held here that the inertia of the Drum Assembly and the Drive Motor rotor, plus the friction forces between the gears constituting the power transmission, would be sufficient to hold any previously established position once the desired Drum Assembly alignment with portioning in front of the cabinet window has been achieved. The further argument that a continued energizing of the Portioner solenoid might lead to chattering and also to electrical disturbances to the T.V. circuit in normal operation led to one of two solutions:-

A. either construct the Portioner solenoids along mechanically-held lines,

B. hold any given Drum Assembly position on the basis of the inertia and friction forces named above.

The latter was chosen for the reason of the costs involved in the former alternative.

\* (Note) - Will report to the (A), see page 204 and 205

(in continuation)

onto the departure block of Krab "B"; (b) a gliding of the latch-pawl down the slope of the departure block; and, (c), in consequence of (b), a return of C5's actuator to its normal position.

With the return of C5's actuator to its normal position, a signal would be caused to course from phase supply across the normally-closed set of contacts of C5, and then across a normally-open set of contacts in the still-engaged relay C9, to one of the normally-open sets of contacts of C14. X

C14, it will be recalled like C13, remains engaged as long as C2 is in the "color" position and C15 is not engaged. Therefore, the signal originating at the normally-closed set of C5's contacts is relayed across the indicated normally-open set of contacts in the now-engaged C14 to pass across a normally-open set of load contacts in the now-engaged C12, and appear finally at the upstream-side of the normally-closed set of auxiliary contacts of C11. Here, the signal results in the engagement of C11.

The engagement of C11, by the closing of its normally-open load contacts, opens a path for a succeeding signal from the normally-open set of contacts in C5 to be applied to the normally-open set of auxiliary contacts in C12. Thus, when Down #2, during the completion of the travel which is initiated when C12 engages, causes the latch-pawl to mount the approach block of Krab "A", the actuator of C5 is tripped, and a signal is caused to course from the downstream side of the normally-open contacts of C5 across the normally-open set of load contacts in the still-engaged C7, and then across a normally-open set of load contacts in the still-engaged C9, to the upstream side of one of the normally-open sets of contacts of the conventional relay C14. Since C14 is still engaged, this signal is relayed across a normally-open set of load contacts in C11 to wind up ultimately at the upstream-side of the normally-open set of auxiliary contacts of C12. The application of the signal to the mentioned set of auxiliary contacts causes an energizing of the disengaging section of the operating coil of C12, and a resultant disengagement of C12. Accordingly, the power signal to the drive motor is interrupted, and, in net effect, the motor is disengaged just as the latch-pawl mounts the top slope of the approach block of Krab "A". The engagement of the latch-pawl in Krab "A" is just what is



then accomplished on the basis of the residual momentum of Drum #2

## SENDING THE COLOR-VIEWING-ALIGNED DRUMS INTO ACTION:-

Once the latch-pawl drops into Knob "A"'s slot, the actuator member of C5 returns to its normal position, and, with C12 in its now-disengaged position and C11 in its <sup>still-</sup>engaged position, a path is opened for a signal from the downstream side of the normally-closed set of contacts of C5 to the operating coil normally-closed set of auxiliary contacts of the mechanically-held relay C15. The application of the mentioned signal to the normally-closed set of auxiliary contacts of C15 leads to the engagement of C15. The signal which accomplishes this task proceeds from the downstream side of the normally-closed contacts of C5 across a set of normally-open contacts in the still-engaged relay C9 to the upstream side of a normally-open set of contacts in the conventional relay C14. From the point, it travels across the mentioned set of contacts in the still-engaged C14 to a normally-<sup>closed</sup> set of contacts in the ~~still-disengaged~~ <sup>now</sup> mechanically-held relay C12, from which point it is relayed to a normally-open set of load contacts in the still-engaged C11. The still-engaged C11 permits the mentioned normally-open set of load contacts to convey the thus-relayed signal to the upstream side of the normally-open set of auxiliary contacts of the mechanically-held relay C15. As indicated above, the eventual travel of the signal to <sup>the</sup> normally-closed set of auxiliary contacts of C15 leads to the energizing of the engaging section of the operating coil of C15, and hence to the engagement of C15.

In the part, the thus-accomplished engagement of the mechanically-held relay C15 leads to:-

- a) the application of a maintained and continuous energizing signal to the Drive Motor
- b) the discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14
- c) the sending out of a "disconnect signal" to C9 and C7

The discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14 according to (b) above takes place via the opening of the normally-closed set of load contacts in C15 when C15 is engaged. The discontinuation of phase supply to C13, the solenoid member of Positioner "B", means the retraction of the plunger-member of Positioner "B" from the drill-hole member of Knob "B". The retraction of the plunger-member (see Div. #9) takes place under the action of the recoil spring member of the Positioner assembly. The retraction of the plunger-member of Positioner "B" from the drill-hole member of Knob "B" clears the impediment to the Drum Assembly's going into action which the energized Positioner constitutes. The simultaneous discontinuation of phase supply to ~~Positioner "B"~~ the conventional relay C14 means the de-energizing of C14, and the breaking of the paths whereby the 'activating' signals for C11 and C12 are transmitted.

The application of a maintained and continuous energizing signal to the Drive Motor according to Item (a) above is accomplished by the 'making', or closing, of a normally-open set of load contacts in C15 when C15 engages. As noted above, since the plunger-member of Positioner "B" is withdrawn from the drill-hole member of Knob "B" simultaneously with the application of the energizing signal to the Drive Motor, both conditions for the sending of the Drum Assembly into action are accomplished with the engagement of C15:-



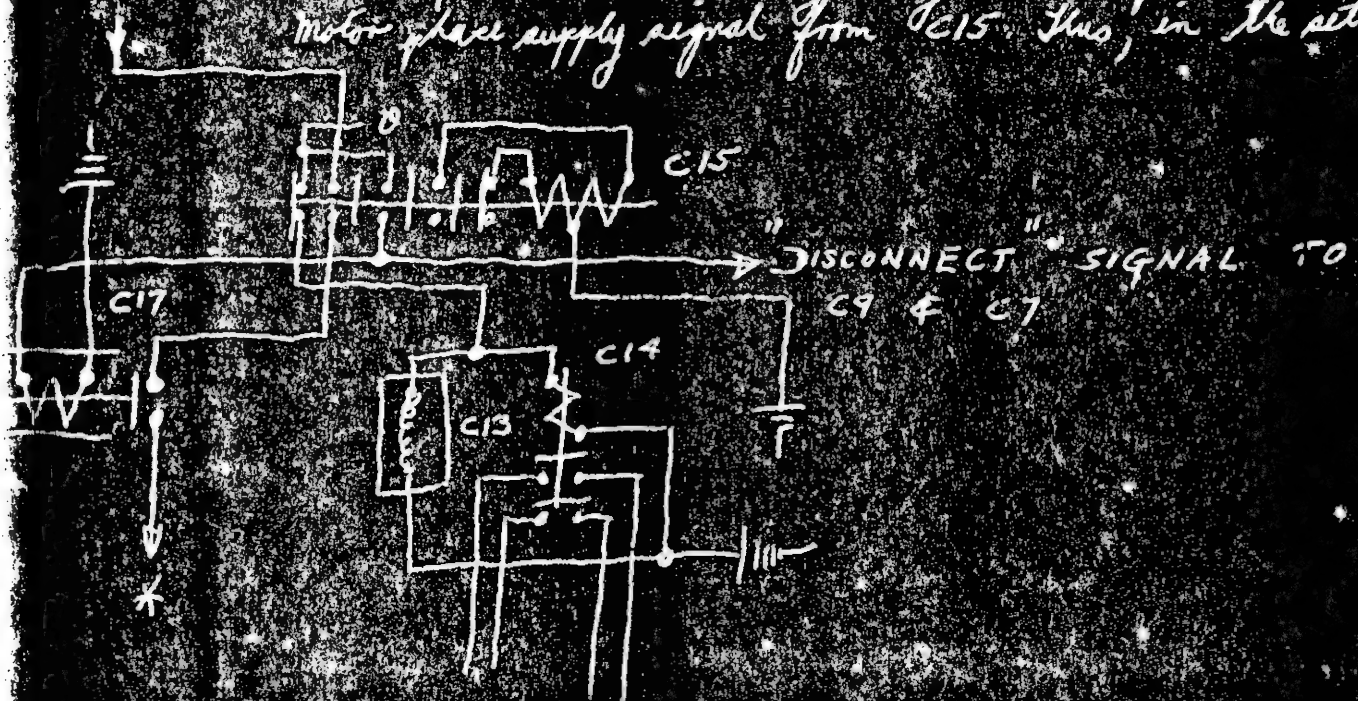
1. the plunger-member of Positioner "B" as a holding agency against rotation of the Drum Assembly is <sup>removed</sup>

and

2. the <sup>continuous</sup> power supply for the Drive Motor which is required for its operation in color-viewing is supplied.

NOTE:-

The simultaneity of action which C15 establishes between the retraction of the plunger of C13 and the energizing of the Drive Motor raises the question as to whether or not the retraction of the plunger assembly would not result in a jamming of the plunger in the drill-hole of Grab "B" and a possible consequent stalling of the motor. To forestall such an eventuality, it might be best to place a time-delay relay in the path of the motor phase supply signal from C15. Thus, in the set-up



shown below, the on-delay timing relay C17 would delay the application of the energizing signal to the Drive Motor for a sufficient period of time to guarantee the retraction of Positioner "B"'s plunger from the drill-hole of Grab "B",

thoroughly eliminating of possibility of jamming of the plunger or stalling of the motor.

Now, let us return Item (c) above, namely the 'disconnect' signal to C7 and C9. [NOTE:- Observe that in <sup>the</sup> sketch given above a 'tap' off the signal to C7 and C9 is used to activate the on-delay timing relay C17]. By its very nature, the 'disconnect' signal to C7 and C9 is a 'clear-the-board' signal which reads the "black-and-white alignment" section of the control circuit for its next call to action. This 'disconnect' or 'clear-the-board' signal is accomplished via the closing of a normally-open set of load contacts in C15 when C15 is engaged.

In connection with the 'clear-the-board' signal from C15 to C7 and C9, it might be well to point out that a 'clear-the-board' signal for the case of the mechanically-held relay C16 is provided via a 'tap' from the color-position contact of the 2-position selector switch C2. Thus when the 2-position selector switch C2 is turned to its color-position, C16 is 'cleared' for its next service in the functioning of the "black-and-white alignment" section of the control circuit. No activation of any portion of the "black-and-white alignment" section of the control circuit follows from this since the turning of the selector switch C2 to its color-position perforce removes phase supply from the "black-and-white alignment" section of the circuit.

Finally, it should be observed that the 'clear-the-board' signal for the "color-alignment" section of the circuit [in particular for the C15 and C11 components thereof] is obtained by a 'tap' from the black-and-white position of the 2-position selector switch C2. Thus, simultaneously with the next calling of the 'black-and-white' alignment section of the circuit into action,



The color-alignment section of the control circuit is readied for its next call to duty.

DWG. # 8

Page 1

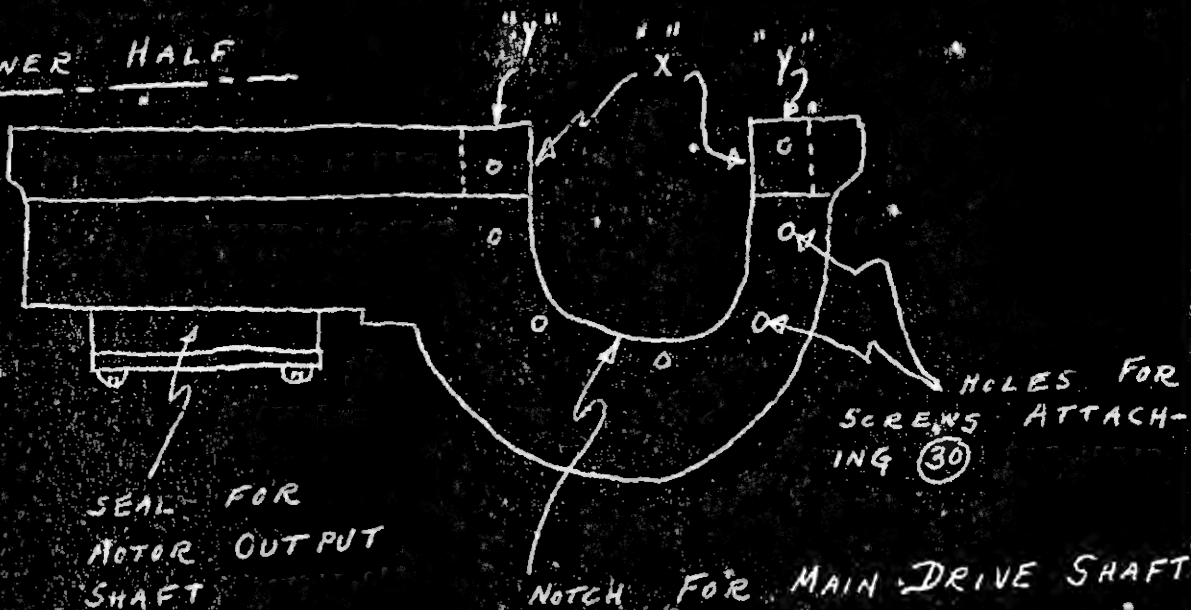
1.  $\frac{3}{4}$ " x  $\frac{3}{4}$ " x  $\frac{1}{16}$ " aluminum angle ring — (also see Item "JB")
2. See Item "JB"
3. " " "
4. Anchor gussets for the "support members" as per DWG. # 1  
(See Items "JD", both views)
5.  $\frac{3}{4}$ " x  $\frac{3}{4}$ " x  $\frac{1}{8}$ " aluminum angle spokes — (also see Items "JB" and "JC")
6. Nine 1600 series  $1\frac{13}{16}$ " shaft size double-sealed single row ball bearing
7.  $\frac{1}{16}$ "  $\frac{1}{2}$ " aluminum coverplate
8.  $\frac{1}{8}$ " x  $\frac{7}{8}$ " lg. rd. hd. machine screws — 6 req.
9. aluminum hub member (machine from solid round or tube stock)
10.  $\frac{1}{8}$ " x  $1\frac{1}{2}$ " lg. cap screw and bolt — 2 req. (See Item "JD" - Plan View)
11. mild steel support axle
12.  $\frac{1}{8}$ " R aluminum anchor gussets welded as shown to the rim — 6 equiv. spaced sets req.
13. Shank of support axle — see DWG. # 1 for members completing the "support hole" for roller pin
14.  $1\frac{1}{4}$ " x  $1\frac{1}{4}$ " x  $\frac{1}{16}$ " aluminum angle rim of Outer Drum L.H. End-Ring
15. Hole for the entry of Positioner "B" i.e. plunger into Knob "B"; hole is to be  $\frac{7}{8}$ " at its innermost and smallest point with the peripheral metal being bevelled off as indicated to give a larger "target" for the plunger.
16. departure block member of Knob "B"
17. filter seat [NOTE: - In the immediate region of the hole member]



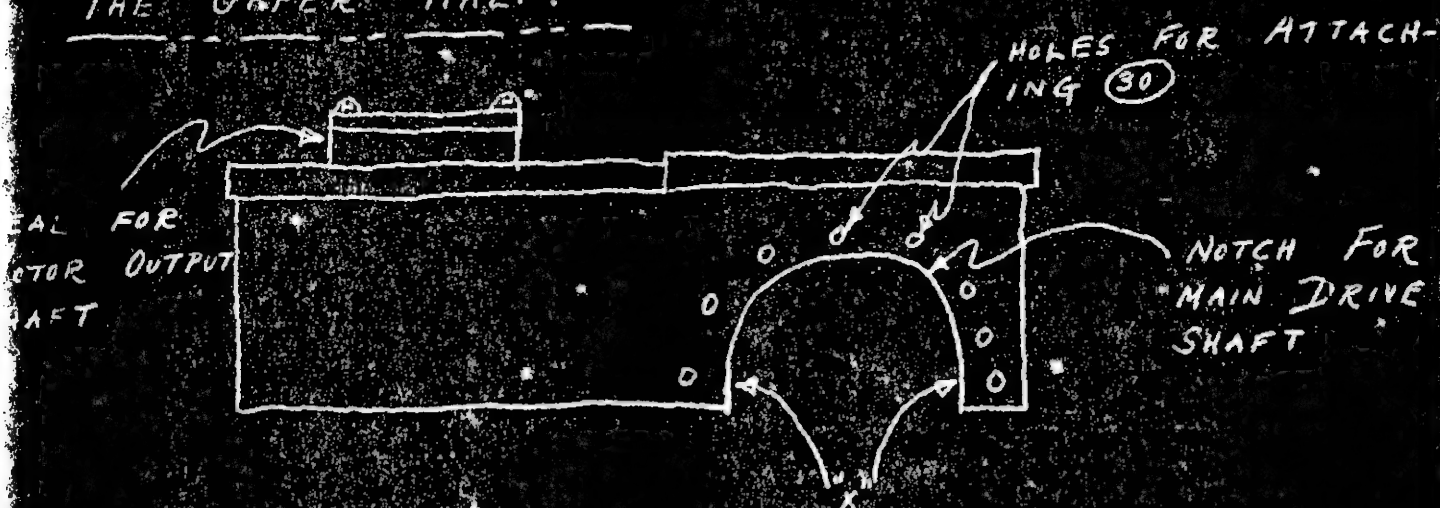
the filter slat is to be notched to permit the plunger a certain latitude in going "home" without incurring the risk of mechanical injury to the slat. The dotted-line extension of the filter slat as indicated in this detail shows the extent to which each slat covers the End-Ring for the balance of the Ring. For the indicated portion of the Ring, the dotted-line therefore shows the extent to which notching of the slat is projected. In the circumferential direction (first direction), a  $\frac{1}{2}$ " distance between the hole perimeter and the nearest portion of the notched slat is proposed.

17. The members labelled (19), when connected by brazing or welding as indicated, will form the "top portion" or "top half" of the Rear Housing. [NOTE:- The Rear Housing is composed of two halves:- an 'upper half' into which the members marked (19) enter, and, a 'lower half' into which the members marked (25) enter. The 'lower-half' is flared, as indicated in the Section Elevation View, to form a "female" at its top rim, while the bottom rim of the 'upper-half' forms the "male" member of the joint. The joint should be friction-tight at all points, or should be caulked or felt-lined to achieve a reasonable degree of tightness. Both halves should be notched to permit their sliding over (27), the main drive shaft of the assembly. The so-notched sections, with the principal portions of the notches following the contours of (27), would, when assembled, form a round opening about (27) with a minimum clearance from (27). These openings are then sealed by a "thick" felt seals (31) pressed "home" against both halves by retainer rings (30). In side Elevation Views, the halves would then appear as indicated approximately below:-

THE LOWER HALF



THE UPPER HALF:-



NOTE:- The <sup>immediate</sup> portions of the notches to which "x" points is in each case a straight line tangent to the circle described by the balance of each of the notches.

"y" in the case of the lower half, indicates regions in which the flange is eliminated to accommodate the members (30) and (31), and enable effective sealing. Both halves of the Housing to be made of 24 gage sheet steel galvanized.



20. Mild Steel Coverslate
21. Drive Motor Output Shaft
22.  $\frac{1}{16}$ "  $\phi$  x  $\frac{3}{16}$ " lg. rd. hd. mach. screws - 6 req.
23.  $\frac{1}{16}$ " thk. felt rings, 4 per seal, compressed to form  $\frac{3}{16}$ " thick seal
24. 18 gage sheet steel ledge for housing - size and shape to convenience
25. The members labelled (25) taken together form the 'lower-half' of the housing. See (19)
26. Driven Gear Member of Helical Gear Train
27. Main Drive Shaft ( $1\frac{3}{16}$ "  $\phi$  at the seal points)
28. Constantly-Maintained Oil Level
29.  $\frac{1}{16}$ "  $\phi$  x  $\frac{1}{4}$ " lg. rd. hd. mach. screws (12 per retainer ring), to screw into snugly-fitting holes in housing wall
30.  $1\frac{5}{8}$ " O.D. x  $1\frac{1}{4}$ " I.D. x  $\frac{1}{16}$ " thk. mild steel retainer rings containing 12 equi-spaced holes drilled and tapped on a  $1\frac{1}{16}$ "  $\phi$  hole circle
31. 2 -  $\frac{1}{16}$ " thk. felt rings  $1\frac{1}{8}$ " I.D. x  $1\frac{5}{8}$ " O.D. superimposed on one another to form a  $\frac{1}{16}$ " felt seal
32.  $\frac{1}{8}$ " x  $\frac{1}{8}$ " x  $\frac{3}{8}$ " lg. steel key between the Main Drive Shaft and the driven gear
33. the driving gear

BULKY EXHIBIT

Date received 8/27/51

ABRAHAM BROTHMAN

100-95068-1B  
(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained John D. Walker

Address Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

146. Photostatic copy of papers entitled "Notes".

80A  
100-95068-1B

✓  
Jm





## DRIVE MOTOR ARRANGEMENTS

### THE C.B.S. SYSTEM:-

The system employed by C.B.S. to maintain synchronization of the color wheel to match the output signal from a magnetic structure which works in coordination with the color wheel against the vertical P-P pulse of the color receiver. This matching operation which takes place in the phase detector (discriminator or comparator) section of a servo-mechanism results in the application of the out-of-balance voltage or D.C. output of the discriminator is applied to the grid of a full frequency adjustable reactor, and the adjustable reactor in turn controls the voltage applied to an induction motor driving the color wheel. The servo-mechanism is conventional in its principle but with its details of design. Like all servo-mechanisms it consists of: a) a discriminator section, b) an anti-hunt section to provide for the stability of the servo itself against undue reaction to a control pulse, c) a power output or control mechanism section which transmits the out-of-balance output of the discriminator into a signal operating a control mechanism which controls the mechanism itself. In magnetic structure which produces the synchronizing or stabilizing wave develops the output signal. This signal is inductively coupled arising from the periodic magnetic field through a well insulated hollow magnet, with the output winding on the color wheel or some other portion of the color wheel. To the end that the color wheel speed is

the same time, however, it must also be  
possible to apply the principle of broad-based induction  
to other areas of life. Fundamentally, the  
idea is to make men more comfortable



of an induction motor at any given output torque and applied voltage.

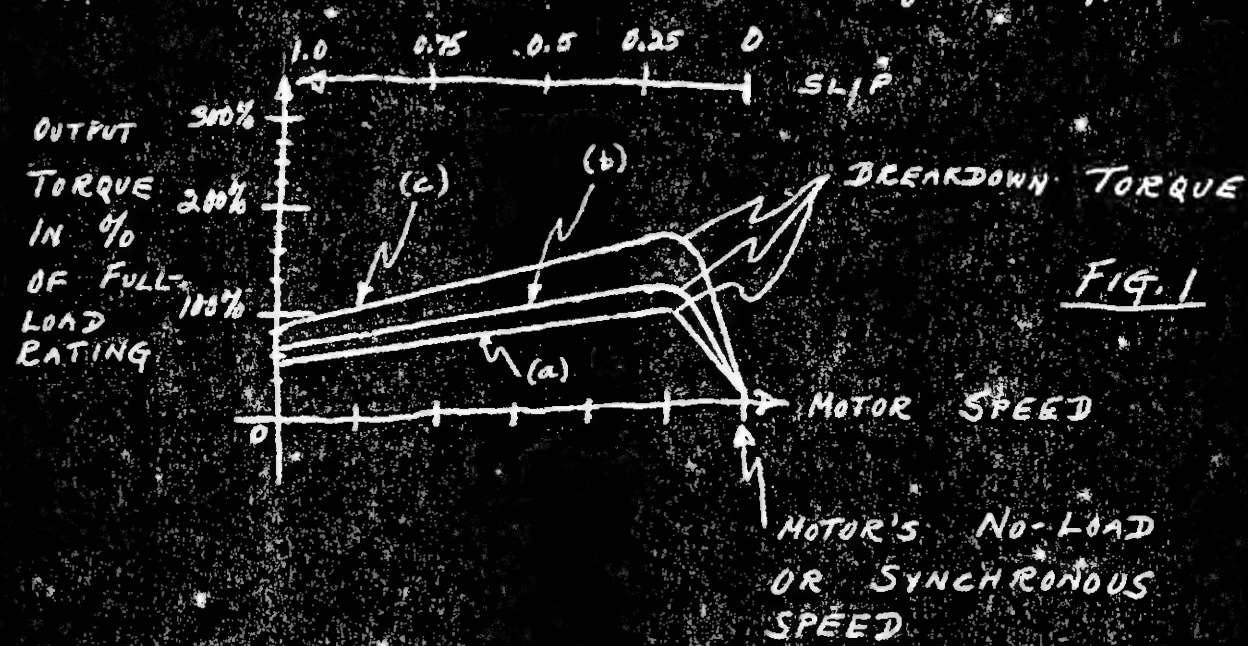


FIG. 1

Fig. 1 will illustrate the thought projected immediately above. Curves (a), (b), and (c) indicate generally the speed-torque (and for torque-slip) relationships for a polyphase induction motor where (a) holds for the lowest of three highly fixed applied voltages, (b) for an intermediate value, and (c) for the highest. If the motor is suitably within range of its designed task, then only that portion of each curve which lies between the full-load speed and the no-load speed of the motor is of interest. [NOTE: - The full-load speed of the motor is that speed which corresponds to the point nearest the no-load speed at which the output-torque of the motor most efficiently approximates the theoretical torque at the given input (given voltage) condition. Roughly speaking, this means that only that portion of each curve which lies to the right of the intercept of the breakdown torque with the motor speed axis is of interest.] In each of the cases of Curves (a), (b), and (c), it is clear that, in the indicated region of interest, the motor's speed is a highly defined function of the output torque of the motor.

the full input voltage, the motor will operate at such a constant speed as is determined by the torque which it is called on to deliver.

If now we wish to draw a vertical line from any given speed lying between the motor's full-load speed and its no-load speed, and if this vertical line were to intercept each of Curves (a), (b), and (c), it is clear that to obtain the arbitrarily chosen speed it would be necessary to do either of two things:-

- a) we might adjust the input conditions to the motor (the applied voltage to the motor) to obtain some speed vs. torque curve on which the required torque corresponds to the chosen speed.
- or  
b) we might <sup>adjust</sup> the driven machine so that at any arbitrarily chosen input condition to the motor, the required torque output corresponds to the desired constant speed.

In brief, the problem in driving the motor which is the motor driven portion of a CBS motor receiving unit is to establish and hold a given constant speed to a high level of accuracy and stability. The induction motor lends itself to such a service, to "constant speed service", if the input conditions to the motor are "matched" to its required output torque; -- or if the required output torque is closely regulated to a fixed input condition. CBS in its system chooses the former of the two possible alternatives, and establishes the required constant speed by adjusting the input conditions to the motor in such a fashion that the required output torque vs. speed curve is achieved.



In doing this, it employs a servo-mechanism operating a saturable reactor as the means of adjusting the input conditions (the voltage applied) to the motor.

## "SOME POSSIBLE NON-SERVO MECHANISMS" :-

In this class, some (6) alternatives have been offered :-

Let the required 48-cycle A.C. is obtained by a 2-step conversion from the 144-cycle vertical pulse using a multi-vibrator and amplifier. This is the components of the 2-step conversion system.

Let the required 144-cycle A.C. is obtained by a 1-step conversion from the 144-cycle vertical pulse of the rect. an amplifier constitutes the 1-step conversion system.

Let the required 60-cycle A.C. is obtained by a 3-step conversion from the 144-cycle vertical pulse of the rect. Two multi-vibrator circuits and an amplifier section form the conversion system.

- A. a system which provides for the feeding of a 48-cycle A.C. current to a 60-cycle, 4-pole, (1800 rpm) synchronous motor as a means of obtaining a <sup>constant</sup> output speed which is  $\frac{75}{60}$  of 1800 (i.e. 1440 rpm);
- B. a system which provides for the feeding of a 144-cycle A.C. current to a 60-cycle, 12-pole (600 rpm) synchronous motor as a means of a constant output speed which is  $\frac{144}{60}$  of 600 (i.e. 1440 rpm);
- C. a system which provides for the feeding of a 60-cycle A.C. current to a 60-cycle, 4-pole (1800 rpm) synchronous motor as a means of obtaining a constant 1800 rpm output which is then "gained down" mechanically to 1440 rpm;
- D. a system as per (A) except that the 48-cycle color pulse forms the base of the 48-cycle A.C. generating system;
- E. a system as per any of (A), (B), (C), or (D) as regards the A.C. fed to a synchronous motor

but in which the synchronous motor works as part of a tandem arrangement with an induction motor, with the synchronous motor supplying or a part of the start and run energy requirements and,

F. a system as per (A), (B), (C), or (D) as regards generating of an A.C. feed to a synchronous motor as per (E) as regards a tandem arrangement an induction motor but in which the two motors built into a common frame.

Each of the systems listed above have the following in common (a) they propose a "lock" to a powerful and <sup>light</sup> accurate signal [the 144-cycle vertical pulse in (A), (B) and (C), and the 48-cycle pulse in (D)] and, in fact, a signal which gates picture-projection of the set; and, (b) they lodge the phase detection or discrimination functions of the CBS servo-mechanism in the functional properties of a synchronous motor.

#### THE NOW-PROJECTED IDEA:-

The now-projected idea goes back to the use of an induction motor as the Driver for a color-wheel or color-drum, as already been indicated [Pages (2) and (3), — in particular (2)] and which induction motor lends itself to constant speed service at either the conditions imposed. The above here goes to that as listed under Item (b) under Page (3).

Let us suppose that as a primary condition, the motor is selected to drive a given color wheel or color drum of a particular normal and usual design procedure, 10-25% size, and that therefore its operating speed at standard supply voltage would lie somewhere between its full-load and its no-load speed. This condition would be indicated



but in which the synchronous motor works as part of a tandem arrangement with an induction motor, with the synchronous motor supplying only a part of the start and run energy requirements;

and,

F. a system as per (A), (B), (C), or (D) as regards the generating of an A.C. feed to a synchronous motor and as per (E) as regards a tandem arrangement with an induction motor but in which the two motors are built into a common frame.

Each of the systems listed above have the following in common:-

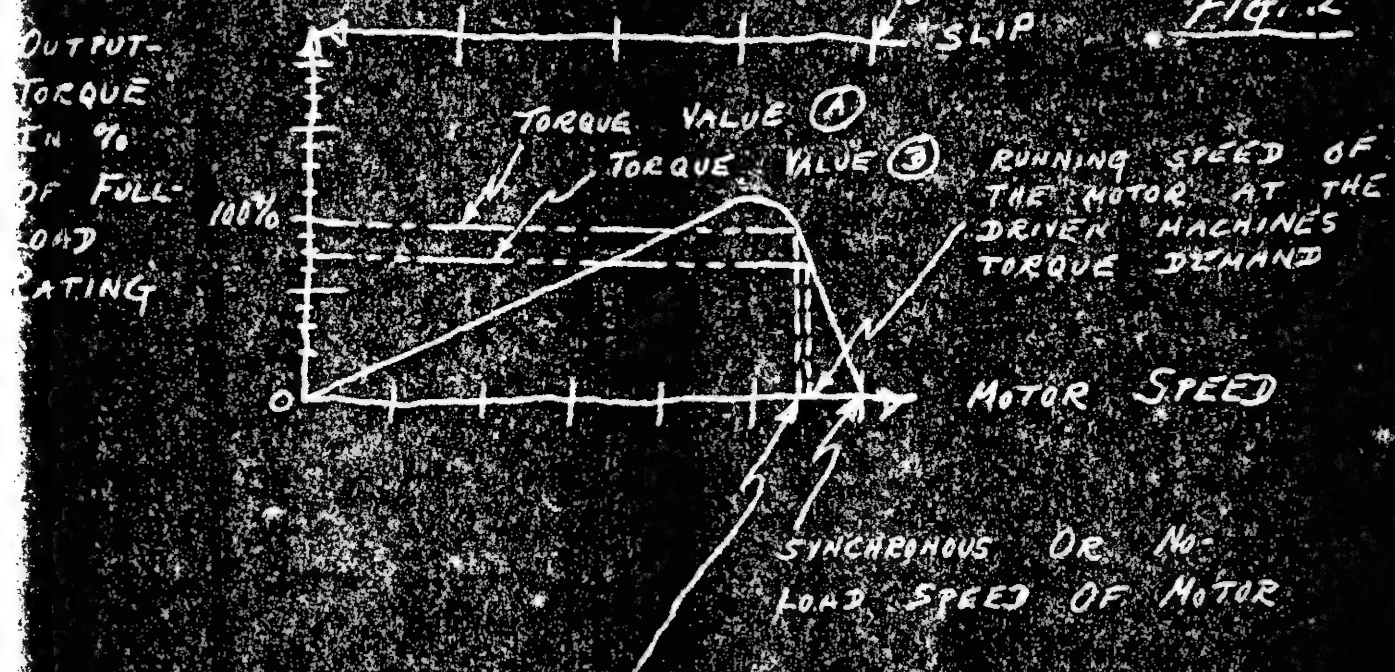
- (a) They propose a "lock" to a powerful and <sup>highly</sup> accurate signal [the 194 cycle vertical pulse in (A), (B) and (C), and the 48-cycle color pulse in (D)] and, in fact, a signal which gates the picture-projection of the set; and, (b) they lodge the phase-detection or discrimination functions of the CBS servo-mechanism in the functional properties of a synchronous motor.

THE NOW-PROJECTED IDEA:-

The now-projected idea goes back to the use of an induction type motor as the Driver for a color wheel or color drum. It has already been indicated [Page (2) and (3), - in particular (3)] that an induction motor lends itself to constant speed service if either of two conditions are imposed. The choice here goes to that alternative listed under Item (b) under on Page (3).

Let us suppose that as a primary condition, the motor that is selected to drive a given color wheel or color drum is, as per the normal and usual design procedure, 10-25% "over-size", and that, therefore its operating speed at standard supply voltage would lie somewhere between its full-load speed and its no-load speed. This condition would be indicated by

Fig 2:-



when the running speed of the motor and the machine would lie between the full-load speed of the motor and the motor's no-load or synchronous speed. Let us suppose that the full-load speed of the motor is 1725 rpm and its no-load speed is 1800 rpm, and, finally, let us suppose that the torque-demand of the driven roller-wheel or roller-drum within the equilibrium speed range is such that a speed of 1750 is obtained from the motor. There a gear ratio between the motor shaft and the wheel or drum-shaft of 50:60, this would mean a running speed of approximately 1458 rpm for the wheel or drum. To bring the wheel or drum to a constant speed of 1440 rpm then the indicated gear set would demand a motor speed of approximately 1729 rpm. To accomplish this with the conditions stated above, to reduce the motor speed from 1750 rpm to 1729 rpm, would require, by Fig 2, that the torque-demand on the motor be lifted from Torque Value (B) to a value very close to Torque Value (A). The task, which amounts to supplementing the driven device's torque-



demand by an increment in torque that when added to Torque Value (D) would approximate Torque Value (A), the newly-projected idea proposes be accomplished with an Eddy Current Brake which is controlled by a servo-mechanism linkage.

Before continuing with a description of the newly-projected idea, let us examine, at least superficially, what is involved. If 1725 rpm is the full-load speed of the motor involved and its nominal horsepower rating were  $\frac{1}{8}$  HP (0.125 HP), then the full load torque-output of the motor would be:

$$\frac{0.125(63025)}{1725} = 4.57 \text{ in-lbs.}$$

If the motor were as much as 25% overage and if its loaded speed without external influences were 1750 rpm as indicated above, then

$$\frac{(1-0.25)(0.125)(63025)}{1750} = 3.37 \text{ in-lbs.}$$

would be its output torque at the above-indicated condition of loading, and

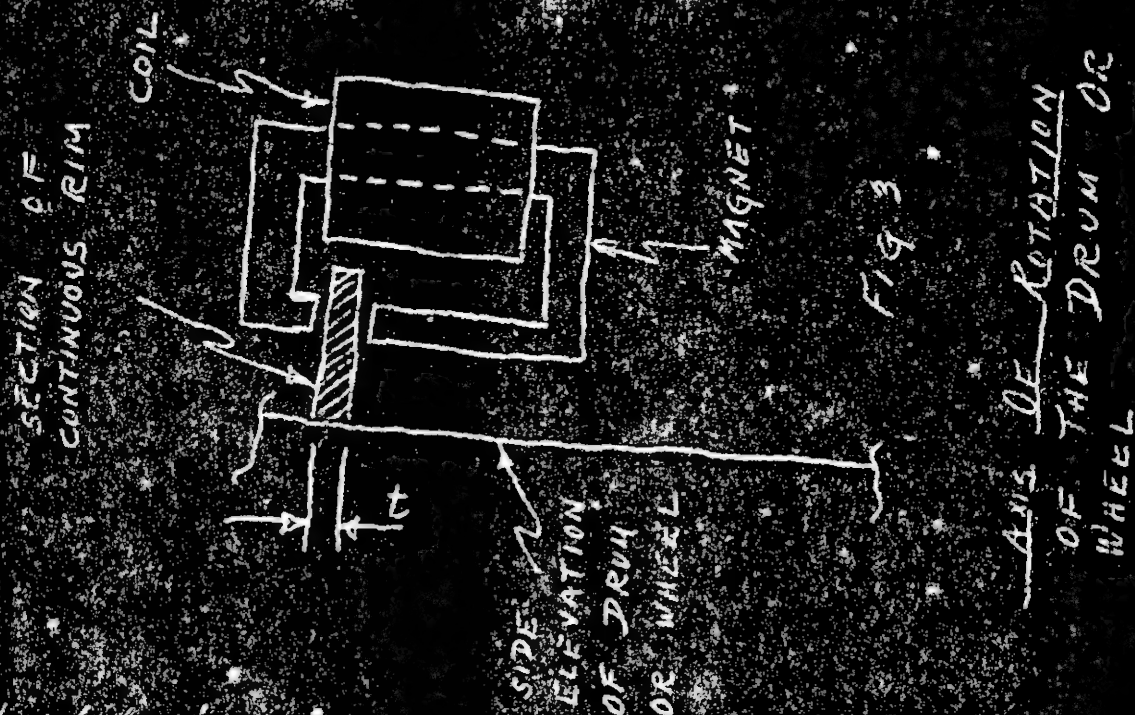
$$4.57 - 3.37 = 1.2 \text{ in-lbs.}$$

would have to be the torque increment borne by the Eddy Current Brake Assembly. Assuming that the braking action would occur at a radius of 12" from the axis of rotation, then

$$\frac{1.2}{12} = 0.1 \#$$

would have to be the force exerted by the Brake at the indicated radius.

Consider then an arrangement as per Fig. #3 in which a rim (of aluminum), attached to the rotor-wheel or rotor-drum, is made to pass thru a magnetic structure of the type indicated in Fig. #3:-



Let the pole face be square, and let the average path of the induced currents be assumed to be  $4l$ , where  $(l)$  is the length of any side of the pole face. The magnitude of the induced E.M.F. in a circuit in which a conductor of length  $(l)$ , cuts magnetic flux of density  $B$  at a velocity of  $(V)$  is given by:-

$$E = BlV \times 10^{-8} \quad (1)$$

where  $(E)$  is in volts,  $(l)$  is in cms., and  $(V)$  is in cms. per sec. If the resistivity of the conductor is given by  $(P)$ , then

$$R = \frac{Pl}{tA} = \frac{Pl}{tA} \quad (2)$$

we should define the resistance in terms of the induced currents, where  $(P)$  is in ohms-cms.,  $4l$  = the average current path, and the product of  $(t)$  - in cms. - and  $(A)$ , also in cms., defines  $(A)$ , the area of the conductor. From (1) and (2), it follows that  $I$ , in mps., would be given by:-

$$I = \frac{E}{R} = \frac{BlV \times 10^{-8}}{\frac{Pl}{tA}} = \frac{BlV (10^{-8}) tA}{Pl} \quad (3)$$



The force acting on a conductor in a magnetic field for the above-indicated construction is given by:-

$$F = \frac{B I l}{10} \quad (4)$$

where:-  $(F)$ , in dynes, is the mentioned force;  $(I)$ , in amps, is the current flow in the conductor; and,  $(l)$ , in cms, is the length of the conductor. Thus, by (3) and (4), we obtain

$$F = \frac{B l}{10} \cdot \frac{B l v (10^{-9}) t}{4 p} = \frac{B^2 l^2 v (10^{-9}) t}{4 p} \quad (5)$$

Converting  $(F)$ , which in (5) is yielded in dynes, to units of gms., since

$$980 \text{ dynes} = 1 \text{ gm},$$

then

$$(F) = \frac{B^2 l^2 v (10^{-9}) t}{4 p (980)} = \frac{B^2 l^2 v (10^{-11}) t}{39.2 p} \quad (6)$$

For a speed of 1740 rpm (29 rps) and a radius of 12",  $(v)$  would have a value of

$$v = 2\pi (29)(12)(2.5) = 4530 \text{ cms./sec.}$$

and, hence (6) may be written

$$F = \frac{45.3 B^2 l^2 t (10^{-11})}{39.2 p} = \frac{1.153 B^2 l^2 t (10^{-9})}{p}$$

Taking

$$B = 750 \text{ gauss}$$

$$l = 1 \text{ cm}$$

$$t = 0.2 \text{ cm}$$

$$p = 3.2 \times (10^{-6}) \text{ cm. sec.}$$

we get that

$$F = \frac{1.153 (10^9) (1) (0.2) (10^{-9}) (1.153)}{3.2 \times (10^{-6})} = 40.3 \text{ gms.}$$

$$\frac{40.3}{254} = 0.1586 \text{ #}$$

If we were to use two such magnetic structures as have been indicated above, thus giving the arrangement a wide latitude of operation about the required 0.1 # force calculated on Page 7; then a braking force of

would be available.  $2(0.0886) = 0.1772 \#$   
By definition

$$\phi = BA \quad (7)$$

and since  $A = l^2 = 1 \text{ cm}^2$ , then  $B = \phi$ . The required magnetomotive force is given by :-

$$\phi = \frac{\text{mmf}}{R} \quad (8)$$

where  $R$  = the reluctance of the magnetic path, and is, in turn, given by

$$R = \frac{l_p}{\mu A} \quad (9)$$

where :-  $l_p$  = the length of the magnetic path;  $\mu$  = the permeability of the path; and,  $A$  = the area of the flux path. Setting  $l_p = 0.3 \text{ cm}$ ,  $\mu = 1$  and since  $A = 1 \text{ cm}^2$ ,

$$R = \frac{0.3}{(1)(1)} = 0.3 \text{ reluctance units}$$

By (8) then, since

$$\text{mmf} = \frac{4\pi NI}{10} \quad (10)$$

then

$$750 = \frac{4\pi NI}{0.3}$$

$$NI = \frac{750(0.3)}{0.4\pi} = 179 \text{ amp-turns}$$

If (I) is to be not more than 0.005 amps as an average condition,

$$\frac{179}{0.005} = 35,800 \text{ turns/coil}$$

would be required.



Assume the wire of 24 gauge wire, then, since 36 gauge wire = 0.002 in.

$35,800(25) = 895,000 \text{ cir. mils} \div 0.895 \text{ in.}^2$   
 would have to be the x-sectional area of the winding on any one side of the square pole section. For  $1 \text{ in.} = \frac{1}{4}$ , then

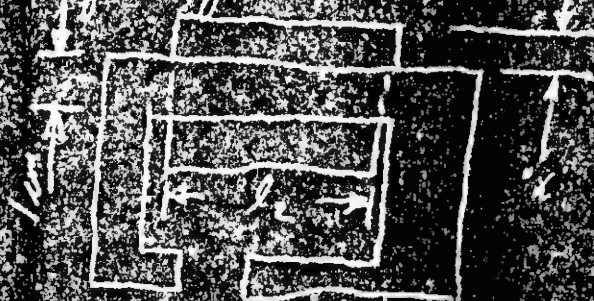


FIG. 4

$$l_2 = \frac{0.895}{\frac{1}{4}} = 1.790 \text{ in.}$$

Since any side of the pole is  $1 \text{ cm.} = 0.4 \text{ in.}$ , then the minimum length of any winding-turn would be  $1.8 \text{ in.}$  while  $5.6 \text{ in.}$  per turn would be the maximum length.

This would mean an average length of  $3.6 \text{ in.}$  per turn; or a wire length of

$$\frac{35,800(3.6)}{12} = 10,720 \text{ ft. per coil}$$

Since the resistance of 36 gauge wire is approximately  $450 \text{ ohms/1000 ft.}$ , then

$$\frac{10,720}{1000} \times 450 = 4830 \text{ ohms}$$

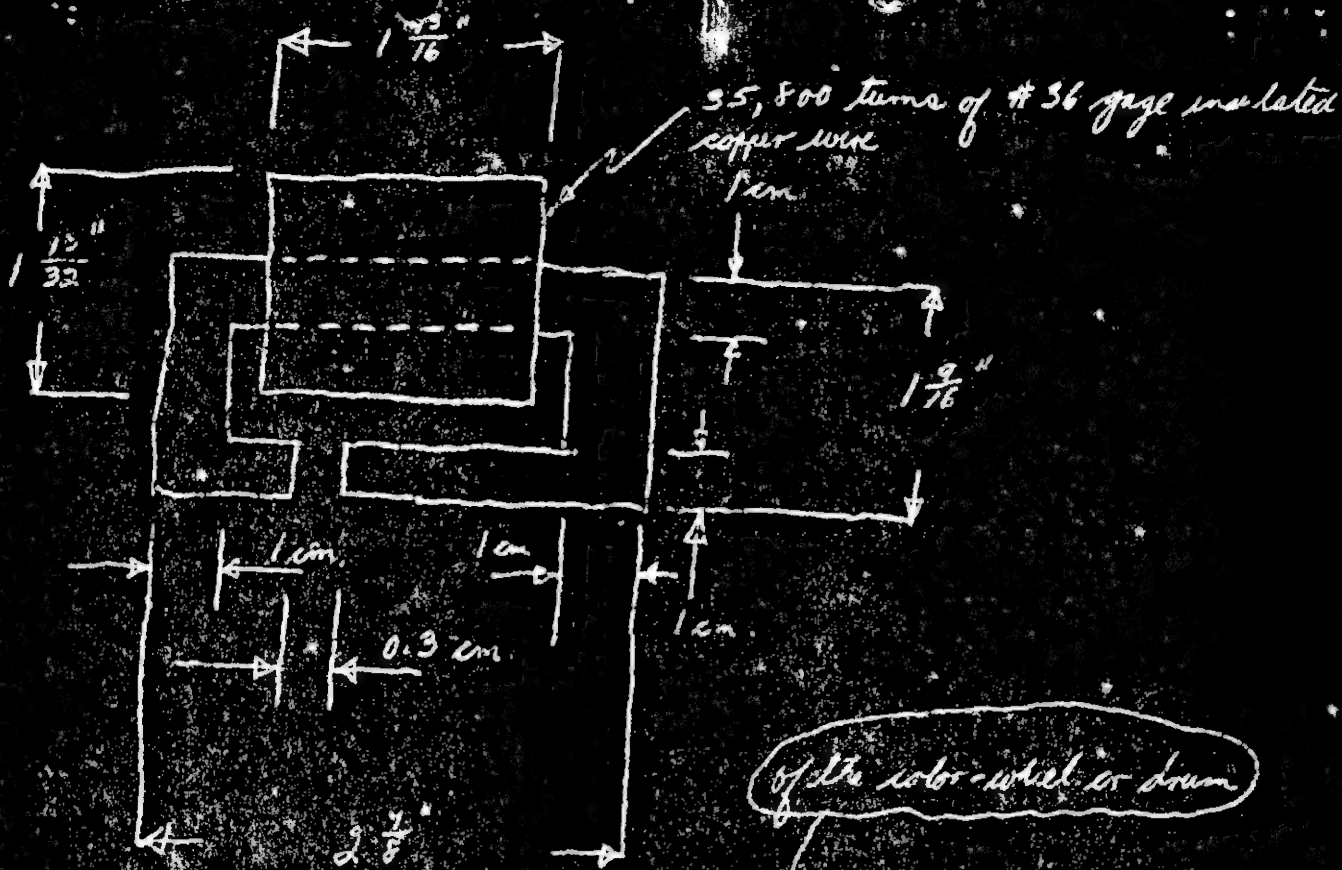
would be the resistance per coil. Two coils in series, as stated above would mean a total resistance of

$$2(4830) = 9660 \text{ ohms}$$

The feeding of 5 milliamperes against a resistance of roughly  $10,000 \text{ ohms}$  is a test which lies comfortably within the range of a 6SN7 vacuum tube.

By the above approximations, it will be seen that:-

a two-coil magnetic structure as per the sketch given below:-



placed opposite another (to establish balance around the axis of rotation) opposite fed by a tube of the class indicated above

and

b. a servo-mechanism based on a phase detection or discrimination section comparing the pulse frequency from a slug-actuator and pulse magnet arrangement with the vertical r-p pulse of the act, in which the out of balance or error voltage from the phase detection circuit is used to bias the operation of the tube feeding the brake magnets

would provide a system, when properly stabilized by anti-hunt provisions, that, in conjunction with an aluminum rim of c. a. electrodes attached to the wheel or drum, would yield accurate control over an induction motor towards obtaining constant (and controlled) speed service from the motor.

Thus a real servo-mechanism for the control of an induction motor (single-phase, - or even 2-phase) has been outlined. It now remains to merge the merits of one system



with respect to another.

## CRITIQUE OF THE DESCRIBED SYSTEM

For obvious reasons, it would be best to treat with each system on their individual merits, and then to treat with their comparative positions.

The CBS synchronizing method has as its strongest advantage the fact that it employs a type of motor, an induction motor, which will permit of a wide latitude in translation as the screen is built up upward. As the industry moves towards larger screen color viewing sets, CBS will be able to use its system, almost intact, except for increasing the motor sizes involved. The larger motors which will become involved will call for a comparative moderate increase in the cost of the synchronization systems they employ. As a rule, induction motors are less expensive, more rugged, and smaller than corresponding speed synchronous motors. There are important factors from many points of view. There can be no doubt that the "tightness" of CBS system's arrangement would be something less than one could obtain from the best kind of a design in a synchronous motor power; but a stable and accurate servo solution <sup>using an induction motor</sup> is possible at a lower production cost.

The systems described heretofore under the heading of "SOME POSSIBLE NON-SERVO MECHANISMS" require some comment, after their common properties are discussed. In each of systems from (A) thru (F) respect the use of one of the best & powerful and accurate operating signals as a comparison standard to gauge the performance of an externally powered motor, but rather than systems use such signals as a point of reference to guide the performance of a motor-power-generating section of the system, and underlying principle is rigidly adhered to in (A) thru (E), and, possibly, less rigidly in the case of (F).

(79)

The principle of employing adding a motor-power-generating section to the set and controlling the characteristics of the generated power by "locking" the motor-power-generating section to one of the set's powerful and accurate signals connects one to the class of synchronous type motors, for these are the only type of motor that can exploit the aforementioned "lock". There can be no doubting of the control which the "lock" exerts over the performance of the motor-power-generating section of the set, but every <sup>theoretically</sup> reason exists for believing that only a fairly special type of synchronous motor can avoid attributing a certain "looseness" to the system as a whole. Ordinary construction synchronous motors do "hunt" and oscillate about their nominal "absolutely" constant speeds. For most synchronous motor service, the mentioned "hunting" or oscillation is a negligible item, for the service tolerances are sufficiently wide to take this into account. In the "NON-SERVO MECHANISMS" which these motors serve, they, as noted above, incorporate within themselves the phase detection and anti-hunt functions which are otherwise taken care of in the CBS synchronization system. Hence, the synchronous motors which must be used here must be of a construction that limits the "hunting" and oscillating tendencies to a negligible limit. Given such a specially constructed synchronous motor (which means that, if one were to use a motor which approximates the stability which the "locked" motor-power-generating section would have), there could be no questioning of the stability which such an arrangement would have.

Finally, we are brought to the system projected under the heading of the "THE NEW-PROJECTED IDEA". It has already been indicated that the "NEW-PROJECTED IDEA" amounts to a complete reversing of the fundamental concept behind the CBS servo. Whereas CBS achieves constant speed servo through a control exerted over the input conditions to the motor. The "NEW-PROJECTED IDEA", which will hereafter be referred to as the Eddy Current Brake



Principle, elect to achieve stable constant speed service by so the motor's work-output. The fact that the Eddy Current Principle uses an induction motor means that every Eddy-Tagh must that was previously attributed to the CBS servo-system and it employs an induction type motor, must also be attributed to now-proposed system. The other advantages which the now-proposed system makes available will come out in the comparisons and treatments listed below:-

For quite clear reasons, the comparisons noted below will be referred to the now-proposed idea as a reference standard:-

Control over the input-conditions to the motor, which in CBS is achieved by obtaining constant speed service from an induction motor is achieved. There is a saturable reactor as a means of controlling the applied voltage. Saturable reactors are expensive equipment, and in the best of production conditions will remain so, for the iron of this must answer to the very highest of standards for magnetic iron. It is the writer's belief that a saturable reactor of the type used cost in the order of \$20 each; and, further, it is anticipated that little hope can be held for this to be produced at a selling price less than \$5 each. By comparison, the two magnets of the now-proposed idea would cost substantially less than \$5.00 for both, a more good estimate being about \$1.00 for the two magnets. A less important factor needs to be a comparison between the costs of a 65H7GT (which is used to "power" the magnets) and the cost of the 6AH6 (which is used to operate the saturable reactor). A difference in the order of \$1.00 is involved here. A more important factor is the "time factor" of a saturable reactor versus that of the magnetic saturations which have been proposed here. A saturable reactor has a "time factor" of 1/20 sec., which is large in comparison to the phenomenon to which

\* The optimum gain properties of a saturable reactor are critically dependent on the quality of the iron used.

accomodation must be made, and is certainly very much larger than one would obtain from the brake magnets.

Now, turning to a comparison between the "NON-SERVO MECHANISMS" and the now projected idea, the cost of a synchronous motor versus that of an induction motor forms the most obvious item of comparison. The cost of a 4-pole synchronous motor is substantially larger than that of a 4-pole induction motor. The cost of a 12-pole synchronous motor as is proposed in item (B) Franklin "SOME POSSIBLE NON-SERVO MECHANISMS" would be even larger being into the question of the motor power generating sections with part of the proposals from (A) that (C) involve, it is clear that there will be large item of additional expense which must be compared with the high cost of a synchronous motor of fairly special design. It is not that the motor power generating section would play a leading part in the overall cost of the system, but it would form a large equally pronounced part of the cost of some motor systems (as it would happen with the induction motor toward large larger power systems). In the connection, it should be recalled that the ability of the CFS synchronization system to be installed without removal of the existing larger synchronous power would also be one of its outstanding advantages. The factor which arises from the principle of type motor form with the characteristics of an induction motor to an accurate and fundamental signal and which results in a motor of very general character is also the factor which is the factor to item (A), item (D), but is substantially different from item (E) and (F). In looking at item (E) and (F) it is not that the bulk of the motor and its power generating section is shifted to the induction motor, but that the power generating section is larger than the induction motor section.



[illegible]

Without further belaboring the point, it is then clear that schemes (A) thru (F), the translation of the basic motion to larger size drives would be costly because of the higher cost of synchronous motors as compared with induction motors, and because the necessary power-generating sections would have to increase with the size of drive involved (even when schemes (E) and (F) are used).

Before leaving the topic of the "NON-SERVO MECHANISM" it should be observed that as larger size screens are supplied for color-viewing, and as larger especially as this begins to involve the use of drive rather than drive assemblies, the question of the size (the physical spatial dimensions) of the motor frame will become increasingly important. As previously pointed out, synchronous motors are larger than induction motors of the same horsepower rating, and hence this factor would be aggravated by the use of synchronous motors. And, lastly, it should be remembered that when schemes (A) thru (F) involve multi-vibrator or counting circuits as component parts of the vertical pulse-to-generated A.C. motor-driving power assemblies, there are an additional cost item.

Returning to the question of the comparative merits of schemes (A) thru (F) versus those of the now-proposed idea, it will be recalled that it was said of the "NON-SERVO MECHANISMS" that there would be no doubling of the "tightness" of the "lock" that would be obtained via the "NON-SERVO MECHANISMS". This puts it up against any servo-mechanism, whether it be the CBS servo or the Fly Current Brake Principle servo, to match the stability record.

When going into the question of motor size, it should be noted in connection with scheme (B) the frame size of a 12-pole motor would be larger than that of a corresponding horsepower 4-pole motor.



...the factor of the magnetic structure  
...the ... - say for  
...the ... itself could rep  
...the ... by the serv  
...the ... determining the stat  
...the ... provisions, the  
...a stability which would give a comparat  
...obtained in Scheme (A) then (F). The possible  
...be incorporated into the short-linkage are the  
...of the principle of (F) - a) developing a feed-back  
...the feed-back with the discriminator or pho  
...operating the servo feeding the brake magnet  
...the general principle could give the short-linkage  
...it would indeed match the best of what could be  
...then (F). One of the ways of achieving the regu  
...would be to have the Main Drive shaft drive  
...discriminator of the type made by Ellinger; while a  
...would be to take a portion of the pipe - or  
...of the alternator, full-wave rectify the said output  
...the ... of a turn - to - filter, and then employ it  
...as suggested above. Finally, towards the goal  
...of the stability - which Scheme (A) does  
...it is possible to alter the slope of the speed  
...of an induction motor towards a less steep  
...a less steep ... by introducing  
...resistance into the motor rotor. There are an  
...of conventional ways of accomplishing this, and  
...experiment would suggest.

It is necessary, the now-projected idea offers the following advantages over the CBS synchronization system:-

(1) A great advantage is that the now-projected idea employs a gas experiment tube to "power" the operated mechanism, in that, now-projected employs a far less expensive operated mechanism (an Eddy Current Brake) than the CBS system (with its adjustable reactor).

(2) A great advantage is that the Eddy Current Brake operated by the now-projected idea involves a smaller "factor" than does the adjustable reactor, and results in the lower "time factor" characteristic of the Eddy Current Brake permits of the addition of other effects such as have been mentioned, on the same without interfering with the accuracy of the system as a whole.

(3) A great advantage is that the now-projected idea offers the following advantages over the CBS system:-

(a) A great advantage is that the now-projected idea does not involve any motor in its motion in that the now-projected idea does not involve generating or converting between a set pulse and a signal generator from which a translation is made. It is noted that the now-projected idea does not involve a motor-power-generating section as part of the set.

(b) A great advantage is that the induction motor used in the now-projected idea is smaller, for any given purpose, than a synchronous motor.

(c) A great advantage is that the now-projected idea does not require a 3 cycle adjustable reactor would that be used to produce the set as indicated above, even on a mass production basis.



BULKY EXHIBIT

Date received 8/20/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained John D. Walker

Address Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 147. Photostatic copy of Drawing #6 Revised.
- 148. Photostatic copy of Drawing #7 Revised.
- 149. Photostatic copy of Drawing #8 Revised.
- 150. Photostatic copy of Drawing #9 Revised.
- 151. Photostatic copy of Notes on Drawing #9.
- 152. Photostatic copy of Paper entitled "Errata, Addenda, and Comments".

81  
100-95068-1B  
S.M.

Dr. G. H. H. H. H.

張

1. 7' x 1" x 1/8" bright strip glued to plywood base (2)
2. plywood base 1" x 1" x 1/8" forms tongue & full bar of contact of (1) with the Outer Drum L.H. Contacting along the Ring's periphery
3. mill steel housing for bronze bushing (1). To be formed from 1/2" x 1/2" x 1/8" 1020 stainless steel tubing, 7/8" I.D. and welded round off at chamber (6)
4. 1/2" x 1/2" x 1/8" 1020 x 1/8" I.D. brass bearing bushing (1) outer diam. 1/2"
5. do (6)
6. 1/2" x 1/2" wide slot in which the actuator pin (1) rides  
7/8" drill hole (steel), hardened, and press-fitted into the hole (3). The actuator pin to be 1/2" by 1/2"  
7/8" wide x 1/2" thick x 1 1/2" long mild steel bar, to be fixed in according to convenience into the indicated end of the solenoid's plunger
8. Pin - sticking through (3) into the mounting support plate in the plunger
9. Actuating solenoid's plunger
10. Allen - Bradley type #6 small portable model, 240 v., 60 cycle, A.C. Solenoid (Bulletin 860)
11. Capscrews & bolts anchoring the solenoid's plunger to bedplate
12. 1/8" x mild steel channel running from the solenoid's bedplate to the brake's baseplate



15. Identical with (14) except that this gusset is also welded to the gusset (17)
16. Tops of the solenoid's coil
17.  $\frac{1}{2}$ " mild steel gusset plate running between one leg of the angle (16) and the baseplate (59)
18.  $\frac{3}{4}$ " x  $\frac{3}{4}$ " x  $\frac{1}{4}$ " structural steel angle
19. #5 wood-screws
20. "knot" at one end of the solenoid's plunger
21. Retainer for the Recoil Spring (22). Dimensions to conform with (20) to be tied into the "knot" portion (20) of the solenoid's plunger by any means that insures squaring of the Retainer with the plunger's principal axis
22. Recoil Spring (Specifications soon)
23. Vertical strips for Recoil Spring Mount of mild steel plate. Thickness of same material. Dimensions of all named members to conform where they can not be defined by Proj. # 6
24.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " x  $\frac{1}{4}$ " spacer to mount tying the Retainer (21) to the horizontal strips of the Recoil Spring Mount
25. Retainer for the other end of the Recoil Spring Mount. Identical with (21) except for method of mounting, and the fact that (21) is tied with the "knot" (20) while (25) is fixed
26.  $\frac{1}{2}$ " mild steel gusset running between the angle (16) and the plate (59). Height of the gusset plate same as (17)
27.  $\frac{1}{2}$ " x  $\frac{1}{2}$ " Lull for the mounting of the plate assembly
28. Recoil Spring (22) in Plan Perspective

29. The end of the Leonard's plunger is seen in Plain Perspective
30. Bronze Gear Works  $\frac{1}{4}$ " I.D.  $\times \frac{5}{8}$ " O.D.  $\times \frac{3}{16}$ " Thick. Best-Bronze Wheel Rings
31.  $\frac{1}{2}$ "  $\times$  mild steel rod, welded as indicated into one leg of the angle (E)
32. Induction Type Drive Motor (further specifications soon)
33.  $\frac{1}{2}$ "  $\times$  mild steel bedplate for the Drive Motor (see End Connection View)
34.  $1\frac{1}{2}$ " shaft size ball bearing pulley block
35. Bronze Gear Works 3" P.D., 50 tooth, L.H., 45° helix,  $\frac{3}{4}$ " face helical gear \*
36. Bronze Gear Works 2.5" P.D., 50 tooth, L.H., 45° helix,  $\frac{3}{4}$ " face helical gear \*
37. Drive Motor's output shaft
38.  $1\frac{1}{4}$ " shaft size ball bearing pulley block
39.  $\frac{3}{4}$ "  $\times$   $1\frac{1}{2}$ "  $\times$   $\frac{1}{4}$ " aluminum angle spokes of Outer Drum L.H. End-Ring
40. Outer Drum L.H. End-Ring
41. Hub of Outer Drum L.H. End-Ring
42. Hub of Inner Drum L.H. End-Ring
43.  $\frac{3}{4}$ "  $\times$   $\frac{3}{4}$ "  $\times$   $\frac{1}{8}$ " aluminum angle spokes of Inner Drum L.H. End-Ring

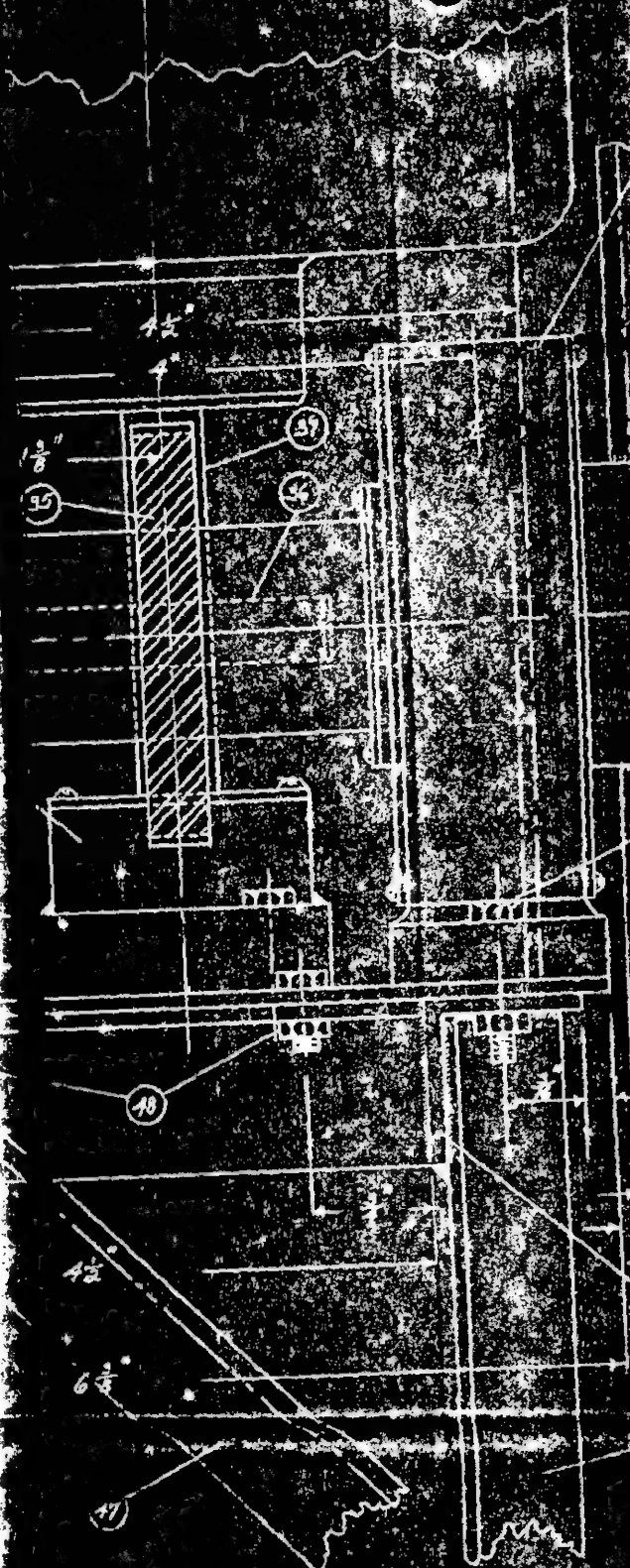
Oil Bath in which gears run is not shown here. See drawing #8





L.H. END ASSEMBLY

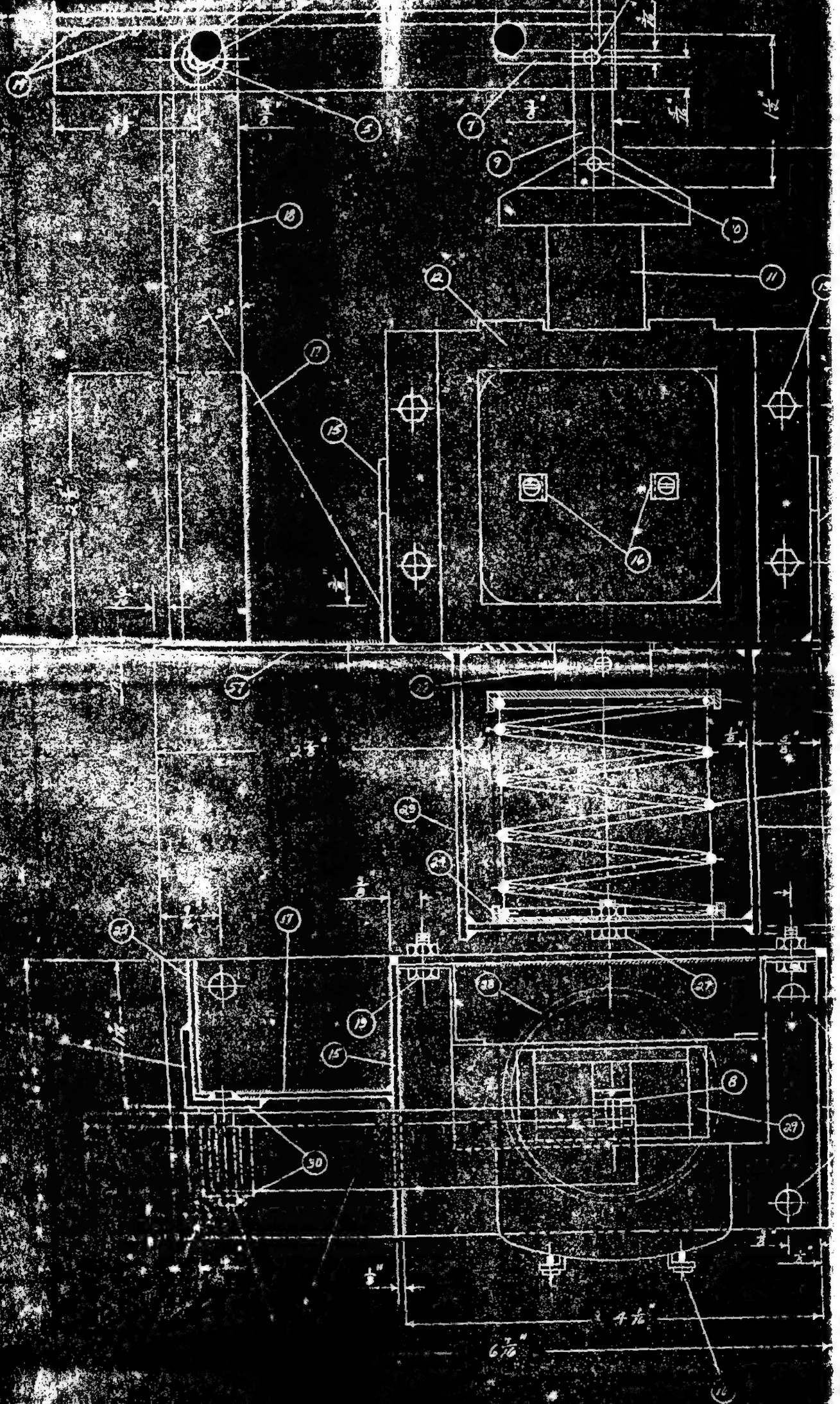
SCALE



END ELEVATION





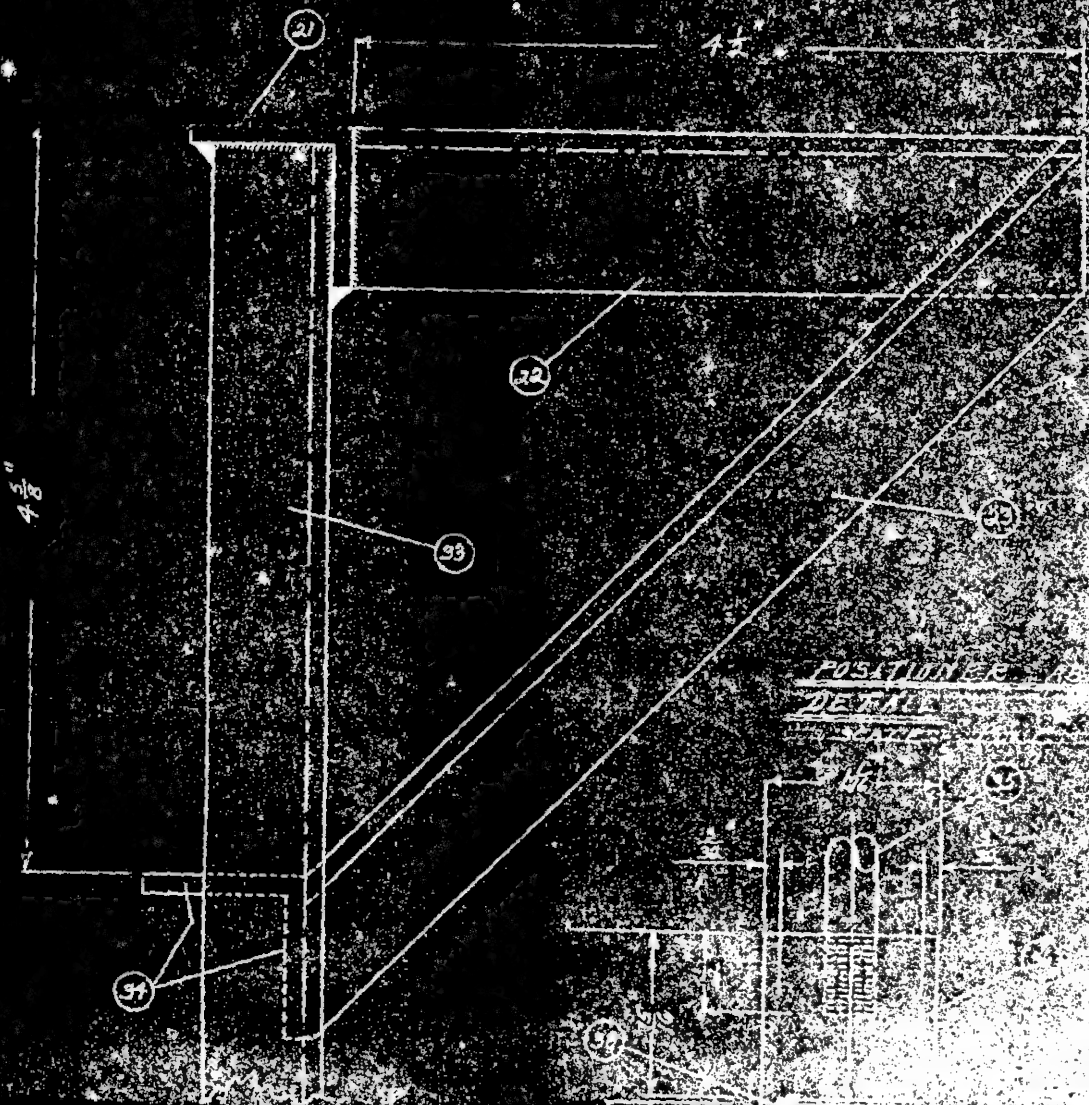


1. Mild Steel Cover-plate
2.  $\frac{7}{16}$ " R. H. machine - 6 reg. on  $1\frac{1}{2}$ " D.S.C.
3. S.A.E. 1020 steel housing, to be fabricated from  $1\frac{5}{8}$ " o.d.  $1\frac{1}{2}$ " I.D. tube stock
4.  $\frac{1}{2}$ " shaft size Flange 1600 series, permanently lubed and sealed, ball bearing
5. Pad plate of  $\frac{1}{4}$ " mild steel R
6.  $\frac{1}{4}$ " & holes for mounting of pad plate
7. Outboard bearing member of the Pad-plate
8. See Item ②
9. Drill & tap for  $\frac{1}{4}$ " cap screw to mount  $1\frac{1}{2}$ " shaft size ball bearing yellow block
10. Horizontal pin-point centerline of  $1\frac{1}{2}$ " shaft size ball bearing yellow block
11. Drill and tap for  $\frac{1}{4}$ " Allen Key between shoulder against inner race of  $1\frac{1}{2}$ " shaft size ball bearing to catch keyway for  $\frac{7}{16}$ " x  $\frac{7}{16}$ " set screw connecting the driver against the Main Drive Shaft
12. Keyway for  $\frac{1}{2}$ " x  $\frac{1}{2}$ " key connecting the sub member of the Outer Drive L.H. End-Ring to the Main Drive Shaft
13. Shaft of  $1\frac{1}{4}$ " o.d. x  $\frac{5}{8}$ " I.D. seamless SAE 1020 Steel Tube Stock
14. Direction of Rotation of the Drive Assembly
15. L.H. End Ring of the Outer Drive
16. Position "3"

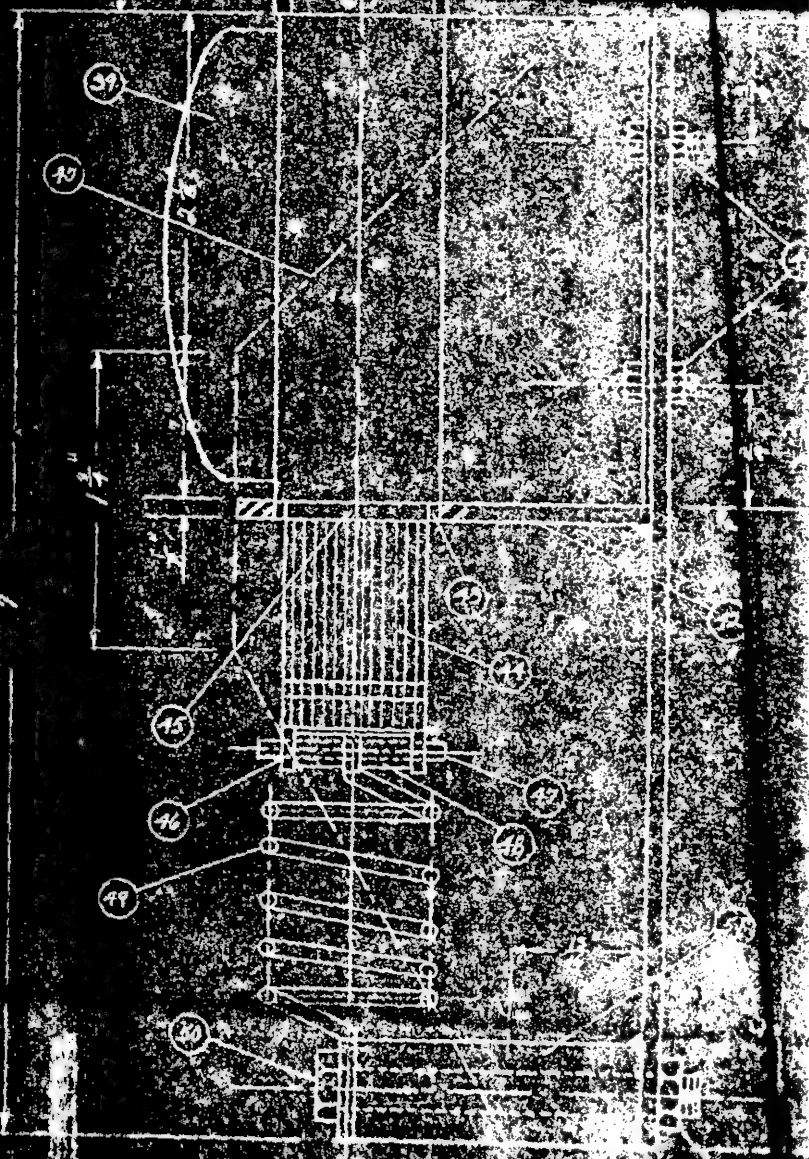
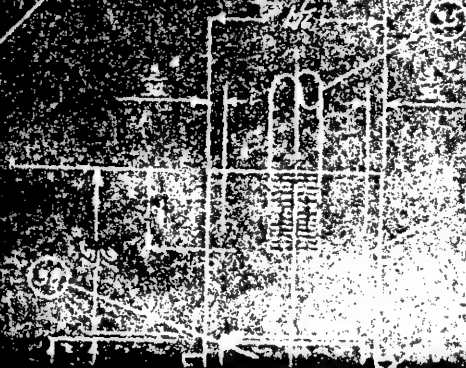


38. "Knob" portion of solenoid's plunger
39. Allen-Bradley, Size #5, Wall Mounting Type, 110 v., 60 cycle, A.C. Bulletin 560 Solenoid
40.  $\frac{1}{8}$ " thick mild steel gusset plate between (42) and vertical portion of frame
41. Cap screws and nuts tying mounting channel of solenoid to the bedplate member of the frame
42. Horizontal plate member of frame,  $2\frac{1}{16}$ " x  $4\frac{1}{8}$ " x  $\frac{1}{8}$ "
43. Slot in (42) for plunger (44) Must be wide enough to accommodate "stop" portion of the plunger
44. Plunger (armature and thereof) of solenoid
45. Pole Faces of Electromagnet, against which (44) goes "home"
46. Mounting Wings on "stop" end of plunger
47.  $\frac{1}{8}$ " x shaft, press-fitted into drill holes in the Mounting Wings (46)
48.  $\frac{1}{4}$ " O.D. x  $\frac{1}{4}$ " I.D. steel tube extends on both sides of spring member to prevent sideways motion of spring
49. Recil spring (specifications soon)
50.  $\frac{1}{4}$ " x cap screw and nut anchoring the bottom end of the Recil Spring (49)
51.  $\frac{5}{8}$ " O.D. x  $\frac{1}{4}$ " I.D. <sup>steel</sup> tube - stock welded to bedplate of frame
52. Nut member of (50)

ITEM "FC"  
SCALE: 1"=1"



POSITIONER ASSEMBLY  
DETAIL

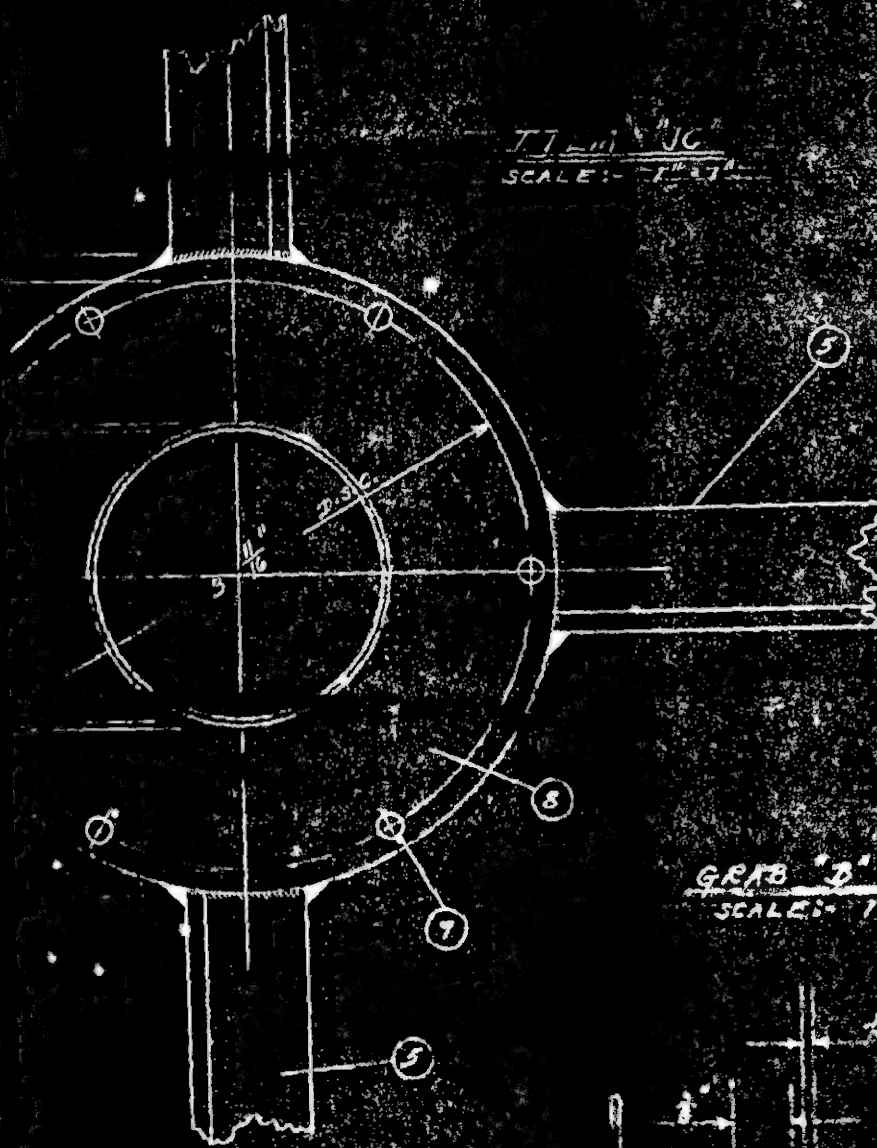


THE MIRASCOPE — FOR A  
RECTANGULAR C.R. TUBE  
V. 1.7 REVISED





77-111 JG  
SCALE: 1" = 1"

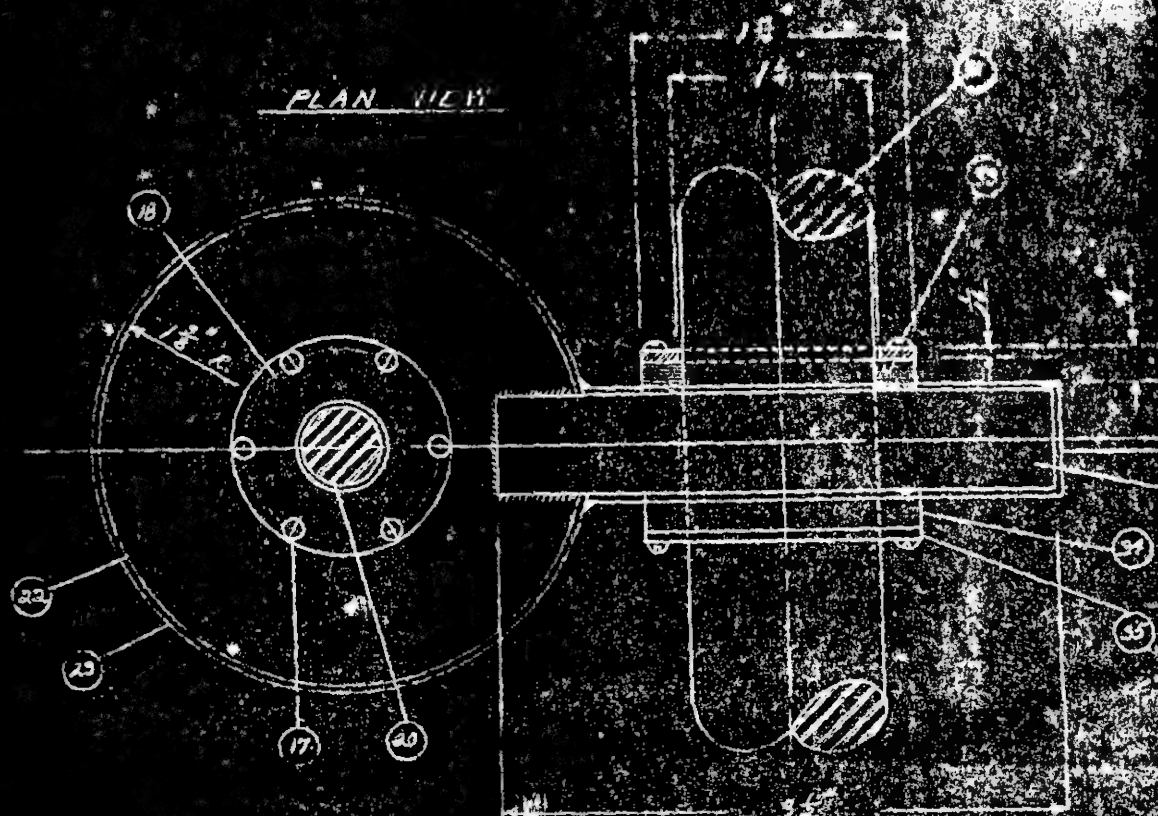


GRAB "B" DETAIL  
SCALE: 1" = 1"

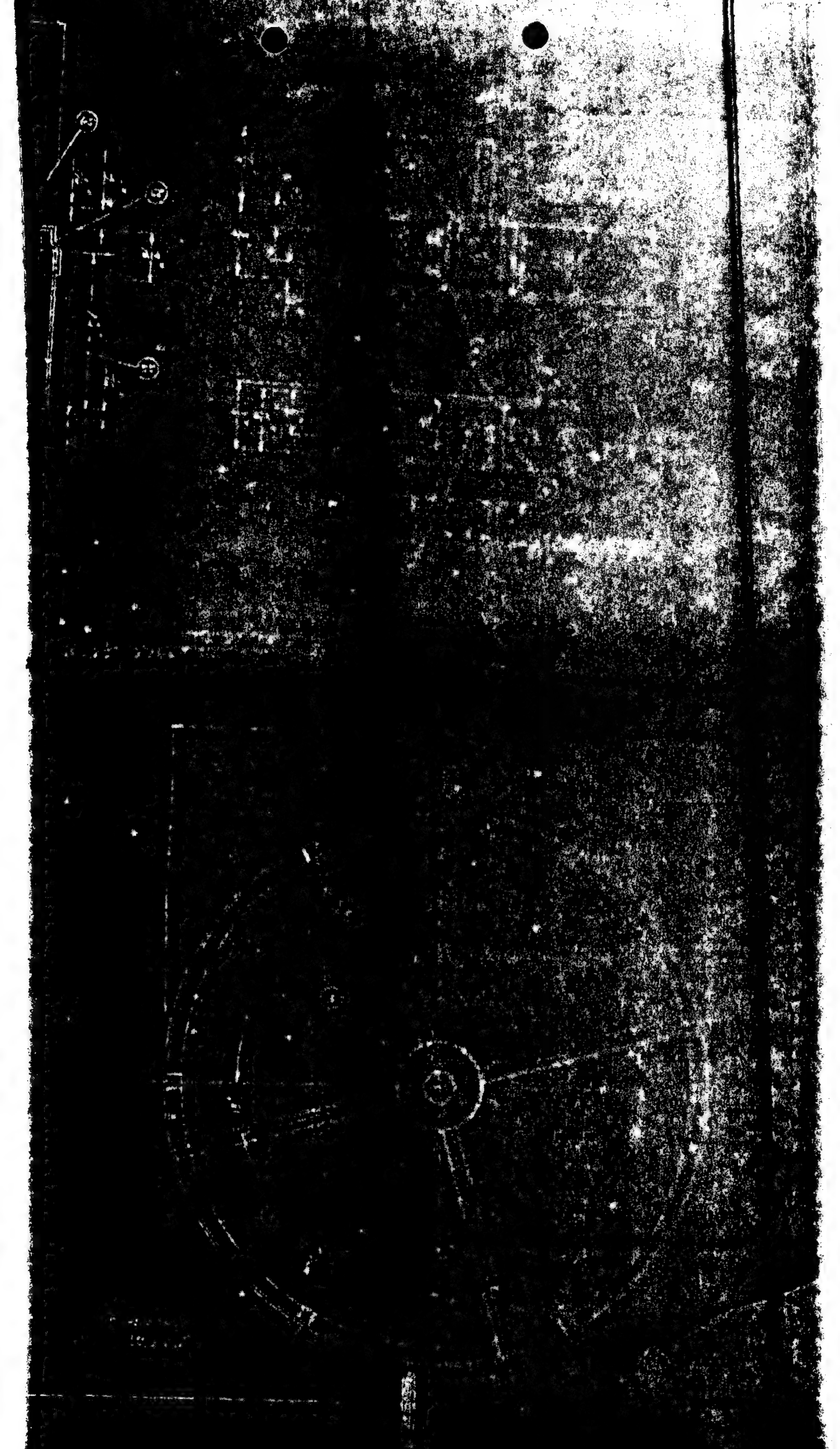


1-1/2" C.R. TUBE  
REVISED

PLAN VIEW

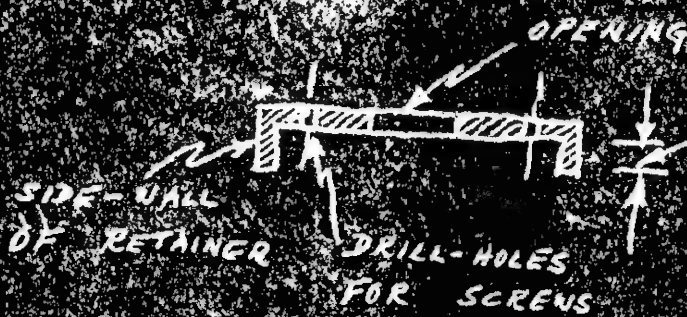






1. Rem of  $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$  aluminum angle
2. Sub-assembly of Inner Drum End-Ring (R.H.) see Item "1B" & "1C"
3. End plate. To which the axle member of each "support member" is anchored. see Item "1D". - 6 sq. square-faced
4. For detail of the spoke-to-rem joint, see Item "1B"
5.  $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$  aluminum angle spoke
6. Aluminum sub-housing. Fabricated from 4" aluminum round stock, or 4" O.D. x 1 1/2" I.D. tube stock - if available
7. Two rollers 1000-1 1/2" shaft size permanently sealed and permanently-lubed ball bearing
8. Aluminum steel cover-plate
9.  $\frac{1}{4} \times \frac{3}{4}$  sq. and hd. mach. screws - 6 sq. on 3 1/8" disc
10.  $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$  aluminum angle rem, see part 1
11. ditto (3)
12.  $\frac{1}{4} \times \frac{3}{4}$  sq. cap screws to nut - 2 sq. per "support member"
13. Axle portion of "support member" assembly, to be fabricated from mild steel bar stock (13), in particular, refer to the roller-bearing portion of the axle
14. Anchored portion of the axle member, see (13)
15. side-plate of  $\frac{1}{8} \times \frac{1}{4} \times \frac{1}{8}$  plates welded to both legs of the rem angle as indicated
16.  $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$  aluminum angle rem
17.  $\frac{1}{4} \times \frac{3}{4}$  sq. and hd. mach. screws - 6 sq. threading into properly drilled holes in the top of (2.5)
18. Retainer Ring, of mild steel. A retainer with a side-wall to restrain the outward "creep" of the felt rings as they are compressed around, of course, the preferable steel a Retainer would be as shown below:



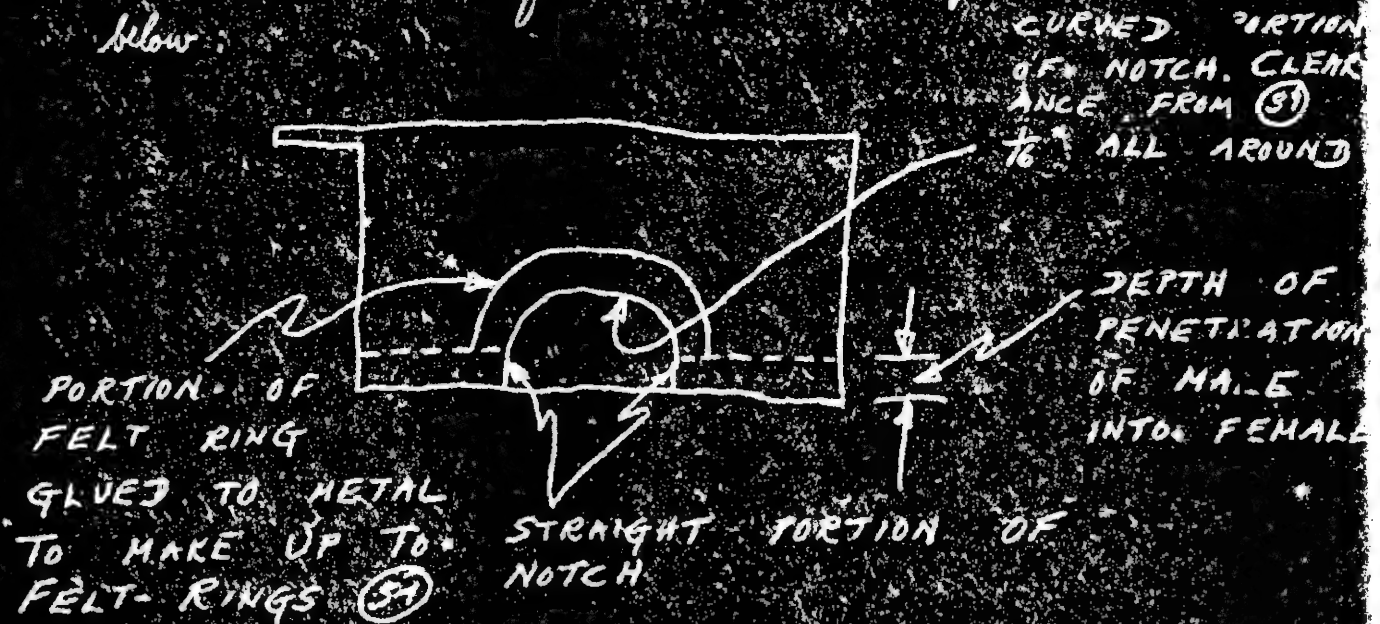


THIS HEIGHT SUFFICIENT  
TO CONTAIN <sup>APPROX.</sup> 50% OF  
THE UNCOMPRESSED  
FELT-RINGS HEIGHT  
PERMITTING AN <sup>ULTIMATE</sup> COMPRES-  
SION OF THE FELT RING  
TO APPROX. 50% OF  
THEIR STARTING HEIGHT

19.  $\frac{1}{8}$ " thick, medium soft felt ring. It may be used to allow for a greater "area of contact" with the shaft.
20. Output shaft of the Drive Motor
21. Keyway for  $\frac{1}{8}$ " x  $\frac{3}{16}$ " key between driving gear and the output shaft of the Drive Motor
22. 21 gage sheet steel, galvanized, metal. Member (22), which is formed as an approximately 360° surface-of-revolution of a line about the  $\phi$  of the Motor-shaft, together with (30) forms the top half of the bath. The bottom edge of the 'top half' of the bath forms the male member of the joint between the 'top' and 'bottom' halves of the bath.
23. 21 gage sheet steel, galvanized. Member (23), which is of the same shape as (22) for the most part, together with member (32) form the 'bottom half' of the bath. The top edge of (23) and (32) is flared to form the 'female member' of the joint between the 'top' and 'bottom' halves.
4. 50-Tooth,  $\frac{5}{8}$ " face, 45° helix angle, 2.5" P.D., L.H., helical gear, steel.
5. Housing for Hardock Helgare. To be formed from  $1\frac{3}{8}$ " O.D. x  $\frac{7}{16}$ " I.D. seamless S.A.E. 1020 steel tube-stock, and braced

or welded to member ②⑤.

26.  $\frac{1}{16}$ "  $\times$   $\frac{3}{16}$ " lg. rd. hd. mach. screws - 6 sq. on  $1\frac{3}{4}$ " D.S.C.
27. Carlock  $\frac{1}{4}$ "  $\times$   $\frac{1}{4}$ " double- lip Klegum leather or felt seal
28. The end of shaft enters the Outboard Bearing on the Pad-plate
29. Key between driven gear and the Main Drive Shaft. Key  $\frac{3}{16}$ "  $\times$   $\frac{3}{16}$ "
30. Member ③① is notched for the Main Drive Shaft as indicated below:

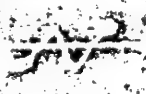
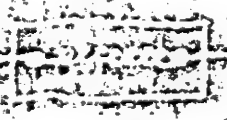


31. Main Drive Shaft. See DWG. # 7 REVISED. Though shown here as a solid shaft, the Main Drive Shaft is hollow in fact.
32. Member ③② is correspondingly notched for the Main Drive Shaft as in member 30, and a portion of a felt ring is circular, glued beneath the flange to make-up to the felt-rings ③④.
33.  $\frac{1}{16}$ "  $\times$   $2\frac{3}{8}$ " lg. rd. head machine screws to draw-up on Klegum Rings ③⑤.
34. Medium soft felt rings, each  $\frac{1}{8}$ " thk. or one  $\frac{1}{4}$ " thk, making-up to glued portions of rings above noted in ③④ and beneath the flanged portion of noted in ③②.



35. Retainer Ring of shot steel — 2 req., 1 each side of (30)
36.  $1\frac{1}{4}" \times 1\frac{1}{4}" \times \frac{1}{16}"$  thick aluminum angle ring of Oil Drum End-Ring (L.H.).
37. ~~Drum~~ Slide-member of Grab "B"
38. Departure block of Grab "B"
39. Plastic Drum (NOTE:- In the immediate vicinity of the hole (37), in the longitudinal as well as girth sections, a general clearance for the hole is used. The dotted extension of (39) indicates the normal overlap of (39) over (36).
40. The plunger-member of Positioner "B" which consists simply of a square-finished drill-rod instead of the ball-point assembly used in Positioner "A"

NOTE:- The normal oil level in the Oil Ball is indicated by the horizontal discontinuous line across the bottom of (32).



*[Faint, illegible handwritten text, likely bleed-through from the reverse side of the page.]*



# NOTES ON DWG.

# 9

Since Pages 112-117 and Pages 201-210 were written, the following changes have been made in Day #9: - a) C16 has been equipped with 2 H.C. contacts <sup>and</sup> instead of one H.C. set; b) has been installed in the circuit; and, (c), C18 has been installed in the circuit.

The inter-act of H.C. load contacts in C16 provides for the disengagement of C17 immediately after C16 engages. Thus, soon after C17 fails to introduce a Time-Delay between the achievement of Black-and-white alignment between the two Prisms and the disengagement of Positioner, the engagement of C16 leads not only to the disengagement of C18, but to the disengagement of C17's operating coil as well. The no member of the black-and-white alignment section of the circuit functioning during black-and-white viewing.

The purposes served by C17 are commented on on Page 215 of the enclosed. [NOTE: - On Page 205, C17 is given as C18. Note the change in legend.] Also please read Page 209 in the connection.

The purposes served by C18 are commented on on Page 115 of the enclosed. The method of guarding against the hazard raised Note on Page 115 is inadequate and incorrect. The solution provided by C18 is positive, and the setting of the Drive Motor into regular color-viewing service definitely avoids the tripping of C18 by plunger member of Positioner 'H', and thus guarantees that plunger pin is withdrawn from Grab "B" when the Drive Motor is set into regular color-viewing service.

(Continuation)

onto the departure block of Grab "B"; (b) is gliding of the latch-pawl down the slope of the departure block; and, (c), in consequence of (c), a return of CS's indicator to its normal position.

With the return of CS's actuator to its normal position, a signal would be caused to course from phase supply across the normally-closed set of contacts of CS, and then across a normally-open set of contacts in the still-engaged relay C9, to one of the normally-open sets of contacts of C14. X

C14, it will be recalled like C13, remain engaged as long as C2 is in its "color" position and C15 is not engaged. Therefore, the signal originating at the normally-closed set of CS's contacts is relayed across the indicated normally-open set of contacts in the now-engaged C14 to pass across a normally-open set of load contacts in the now-engaged C11 and appear finally at the upstream-side of the normally-closed set of auxiliary contacts of C11. Here, the signal results in the engagement of C11.

The engagement of C11, by the closing of its normally-open load contacts, opens a path for a succeeding signal from the normally-open set of contacts in CS to be applied to the normally-open set of auxiliary contacts in C12. Thus, when I run #2, during the completion of its hook which is initiated when C12 engages, causes the latch-pawl to mount the approach block of Grab "A". The actuator of CS is tripped and a signal is caused to course from the downstream side of the normally-open contact of CS across the normally-open set of load contacts in the still-engaged C9, and then across a normally-open set of load contacts in the still-engaged C9, to the upstream side of one of the normally-open sets of contacts of the conventional relay C14. Since C14 is still engaged, this signal is then relayed across a normally-open set of load contacts in C11 to wind up ultimately at the upstream-side of the normally-open set of auxiliary contacts of C12. The application of this signal to the mentioned set of auxiliary contacts causes an energizing of the disengaging section of the operating coil of C12, a resultant disengagement of C12. Accordingly, the power signal to the drive-motor is interrupted, and, in net effect, the motor is disengaged just as the latch-pawl mounts the approach block of Grab "A". The engagement of the latch-pawl in Grab "A" is a grab shot is



then accomplished on the basis of the residual momentum of Drum #2

# SENDING THE COLOR-VIEWING-ALIGNED DRUMS INTO ACTION:-

Once the latch-pawl drops into knob "A"'s slot, the actuator member of C5 returns to its normal position, and, with C12 in its now-disengaged position and C11 in its <sup>still-</sup>engaged position, a path is opened for a signal from the downstream side of the normally-closed set of contacts of C5 to the operating and normally-closed set of auxiliary contacts of the mechanically-held relay C15. The application of the mentioned signal to the normally-closed set of auxiliary contacts of C15 leads to the engagement of C15. The signal which accomplishes this task proceeds from the downstream side of the normally-closed contacts of C5 across a set of normally-open contacts in the still-engaged relay C9 to the upstream side of a normally-open set of contacts in the conventional relay C14. From this point, it travels across the mentioned set of contacts in the <sup>now</sup>still-engaged C14 to a normally-<sup>closed</sup> set of contacts in the <sup>now</sup>disengaged mechanically-held relay C12, from which point it is relayed to a normally-open set of load contacts in the still-engaged C11. The still-engaged C11 permits the mentioned normally-open set of load contacts to convey the thus-relayed signal to the upstream side of the normally-open set of auxiliary contacts of the mechanically-held relay C15. As indicated above, the eventual travel of the signal to <sup>the</sup> normally-closed set of auxiliary contacts of C15 leads to the energizing of the engaging section of the operating coil of C15, and hence to the engagement of C15.

For its part, the thus-accomplished engagement of the mechanically-held relay C15 leads to:-

- a) the application of a maintained and continuous energizing signal to the Drive Motor
- b) the discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14
- c) the sending out of a "disconnect signal" to C9 and C7

The discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14 according to (b) above takes place via the opening of the normally-closed set of load contacts in C15 when C15 is engaged. The discontinuation of phase supply to C13, the solenoid member of Positioner "B", means the retraction of the plunger-member of Positioner "B" from the drill-hole member of Knob "B". This retraction of the plunger-member (see Diag. #9) takes place under the action of the recoil spring member of the Positioner assembly. The retraction of the plunger-member of Positioner "B" from the drill-hole member of Knob "B" clears the impediment to the Drum Assembly's going into action which the energized Positioner constitutes. The simultaneous discontinuation of phase supply to ~~Positioner "B"~~ the conventional relay C14 means the de-energizing of C14, and the breaking of the paths whereby the 'activating' signals for C11 and C12 are transmitted.

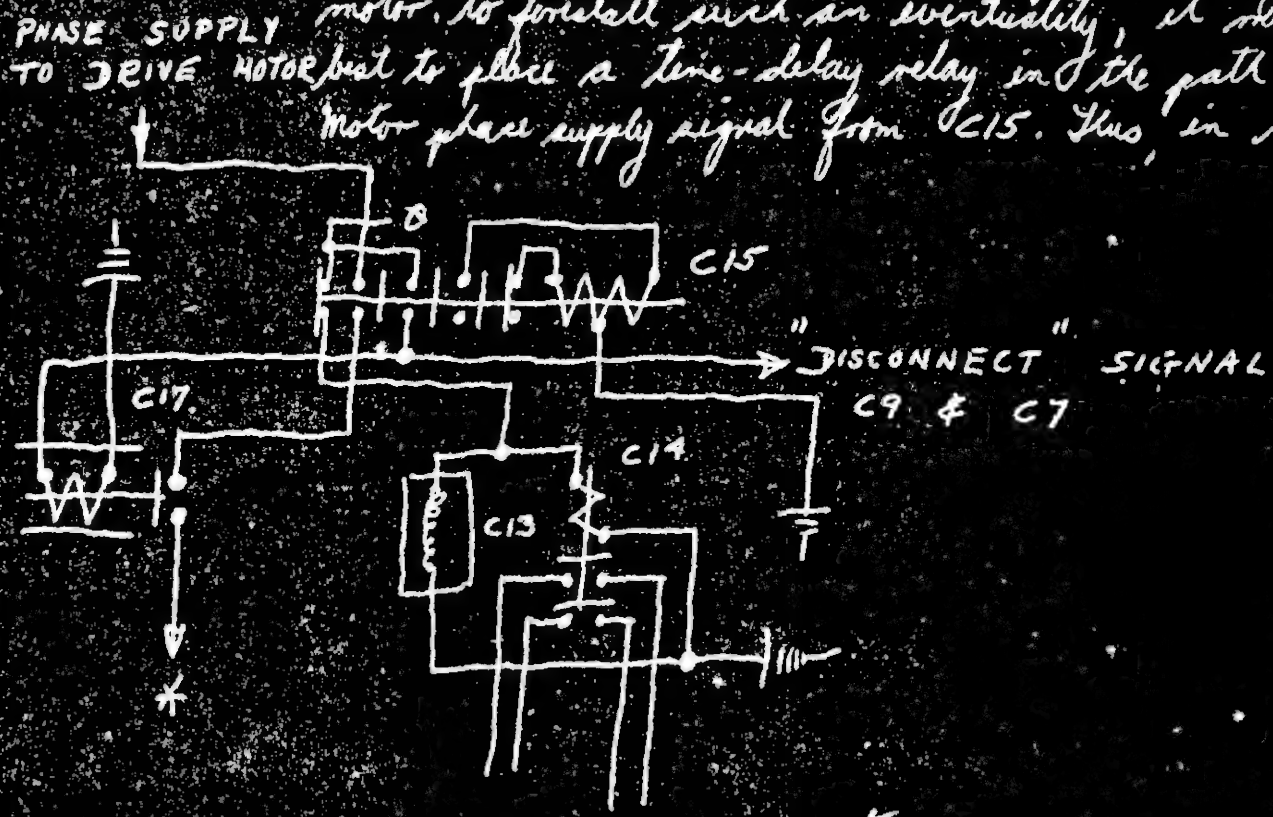
The application of a maintained and continuous energizing signal to the Drive Motor according to Item (a) above is accomplished by the 'making', or closing, of a normally-open set of load contacts in C15 when C15 engages. As noted above, since the plunger-member of Positioner "B" is withdrawn from the drill-hole member of Knob "B" simultaneously with the application of the energizing signal to the Drive Motor, both conditions for the sending of the Drum Assembly into action are accomplished with the engagement of C15:-



1. the plunger-member of Positioner "B" as a holding agency against rotation of the Drum Assembly is removed <sup>continuous</sup>
2. the power supply for the Drive Motor which is required for its operation in color-viewing is supplied.

NOTE:-

The simultaneity of action which C15 establishes between retraction of the plunger of C13 and the energizing of the Drive Motor raises the question as to whether slowness of the recoil action of plunger assembly could result in a jamming of the plunger in the drill of Knob "B" and a possible consequent stalling motor. To forestall such an eventuality, it may be desirable to place a time-delay relay in the path of motor phase supply signal from C15. Thus, in the



shown below, the on-delay timing relay C17 would delay the application of the energizing signal to the Drive Motor for a sufficient period of time to guarantee the retraction of Positioner "B" plunger from the drill-hole of Knob

thereby eliminating of possibility of jamming of the plungers or stalling of the motor.

Now, let us return Item (C) above, namely the 'disconnect' signal to C7 and C9. [NOTE:- Observe that in <sup>the</sup> sketch given above a 'tap' off the signal to C7 and C9 is used to activate the on-delay timing relay C17]. By its very nature, the 'disconnect' signal to C7 and C9 is a 'clear-the-board' signal which readies the "black-and-white alignment" section of the control circuit for its next call to action. This 'disconnect' or 'clear-the-board' signal is accomplished via the closing of a normally-open set of load contacts in C15 when C15 is engaged.

In connection with the 'clear-the-board' signal from C15 to C7 and C9, it might be well to point out a 'clear-the-board' signal for the case of the mechanically-held relay C16 is provided via a 'tap' from the color-position contact of the 2-position selector switch C2. Thus when the 2-position selector switch C2 is turned to its color-position, C16 is 'cleared' for its next service in the functioning of the "black-and-white alignment" section of the control circuit. No activation of any portion of the "black-and-white alignment" section of the control circuit follows from this since the turning of the selector switch C2 to its color-position perforce removes phase supply from the "black-and-white alignment" section of the circuit.

Finally, it should be observed that the 'clear-the-board' signal for the "color-alignment" section of the circuit (in particular for the C15 and C11 components thereof) is obtained by a 'tap' from the black-and-white position of the 2-position selector switch C2. Thus, simultaneously with the next calling of the 'black-and-white' alignment section of the circuit into action.



The color-alignment section of the control circuit is readied for its next call to duty.

ERRATA, ADDENDA, & COMMENTS

NOTE: PAGES 1-27, THE MIRIASCOPE  
PRINCIPAL DIFFERENCES BETWEEN THE  
ORIGINALLY SUBMITTED DESIGN & THE  
DESIGN SET FORTH ON PAGES DWGS #1-

9.

The original outlines of the Miriascope were set forth in a series of Preliminary Sketches numbering 19, sketches of which the last was devoted to a proposed Control Circuit. The balance was devoted to detail aspects of the design. The original design, its objectives, its fundamental principles, and its detail aspects were discussed in a 27-page document beginning with an untitled communication dated 8/6/51. Later, a series of 9 formal drawings were submitted which in many aspects differed from the originally-submitted drawings (Sketchs 1 thru 19). The differences are for the most part in detail aspects of the design rather than <sup>in fundamental</sup> principles.

NOTE

In the series of drawings numbered #1-9, it will be found that successive drawings in dealing with <sup>any</sup> detail may differ. Such differences when they occur between succeeding drawings are intentional, and are meant to convey revisions of the design as given on previous drawings. Therefore, any and all conflicts between successive drawings are to be construed in favor of the drawing bearing the most recent series number.

IMPORTANT



Positioner "A" via a normally-closed set of load contacts in the mechanically-held relay C16; while, on Sht. #19, the same signal is passed directly from the mentioned set of load contacts in C3 to C8 and C6 without any interposed relay effects;

- b) on Dwg. #9, C15 is indicated as a mechanically-held relay; while on Sht. #19 it appears as a conventional relay;
- c) on Dwg. #7, the mechanically-held relay C9 appears as a 3 N.O. - 1 N.C. unit, the mechanically-held relay C10 as a 2 N.O. - 1 N.C. unit, and the mechanically-held relay C7 as a 2 N.O. - 1 N.C. unit. On Sht. Sht. 19, C9 appeared as a 2 N.O. - 2 N.C. unit, C10 as a 2 N.O. unit, and C7 as 1 N.O. - 1 N.C. unit;

and,

- d) in correspondence to the above-mentioned equipment changes, certain details of the functional patterns have been altered.

The addition of C16 to the circuit as per (a) has been for the purpose of providing for the disengagement of C6 and C8 after the re-alignment of the Druma for "black-and-white" viewing has been achieved. By so doing, any A.C. chatter associated with the continued engagement of C6 [the solenoid member of Positioner "A"] and C8 [the on-delay timing relay] is eliminated; and, further, any disturbing effects due to ~~the~~ a continued feeding of these equipment items is eliminated.

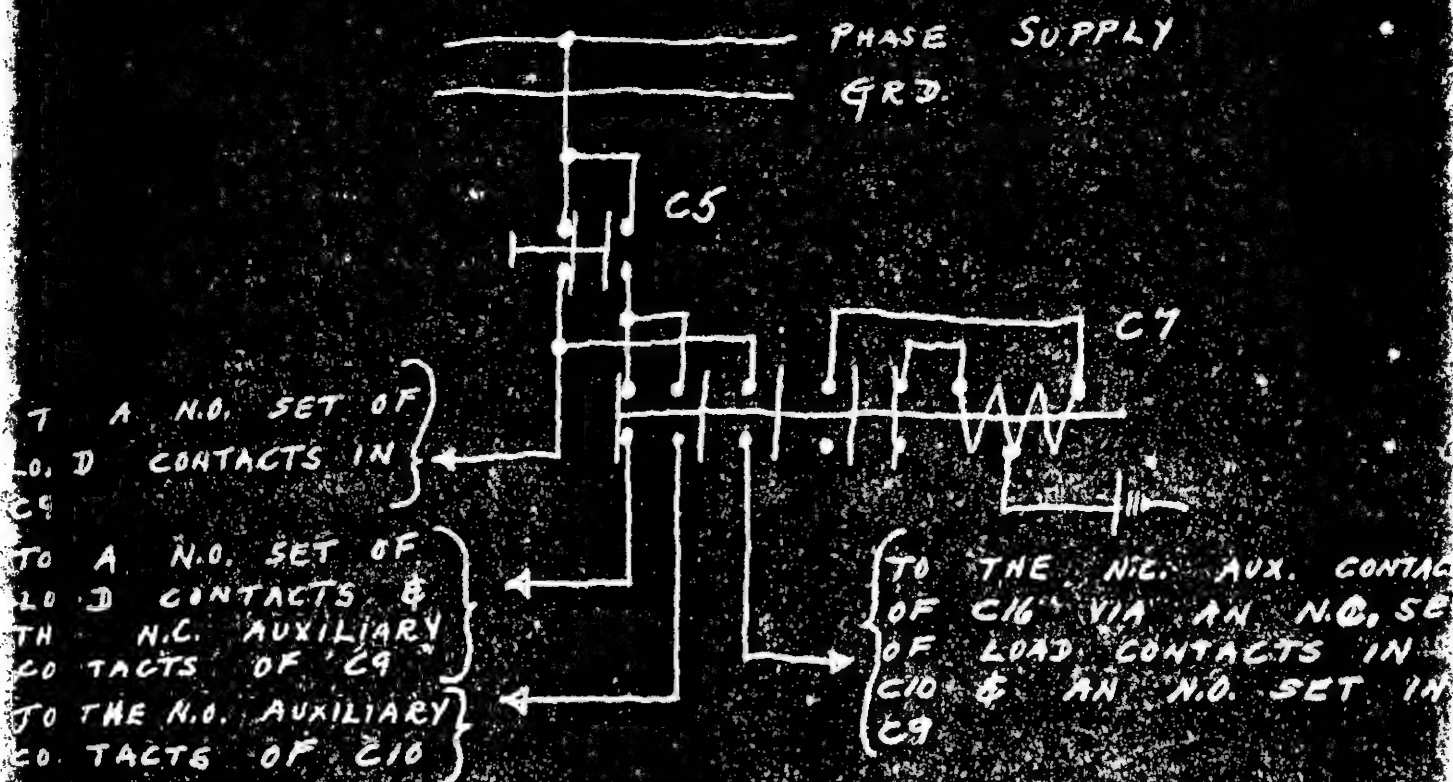
Associated with the addition of C16 to the "black-and-white" alignment section of the control circuit are the above-noted changes in the specifications for C10 and C7 and, in part, the changes in the specifications for C9. From a reading of pages 101-111, it will be observed that:-

- A. when the resetting of the Drum Assembly and the disengagement of the latch - pawl from Knob "A" is accomplished as the first step in the re-alignment of the two drums for black-and-white viewing, C9 is ~~then~~ engaged;
  - B. after C9 is engaged following the events mentioned in (A), C10 is engaged;
- and,
- C. after C10 is engaged as a consequence of the engagement of C9 and after the ensuing motivation of Drum #2 alone results in the return of the latch - pawl to a position where it no longer trips the actuator of the Permit Limit Switch, C7 is engaged.

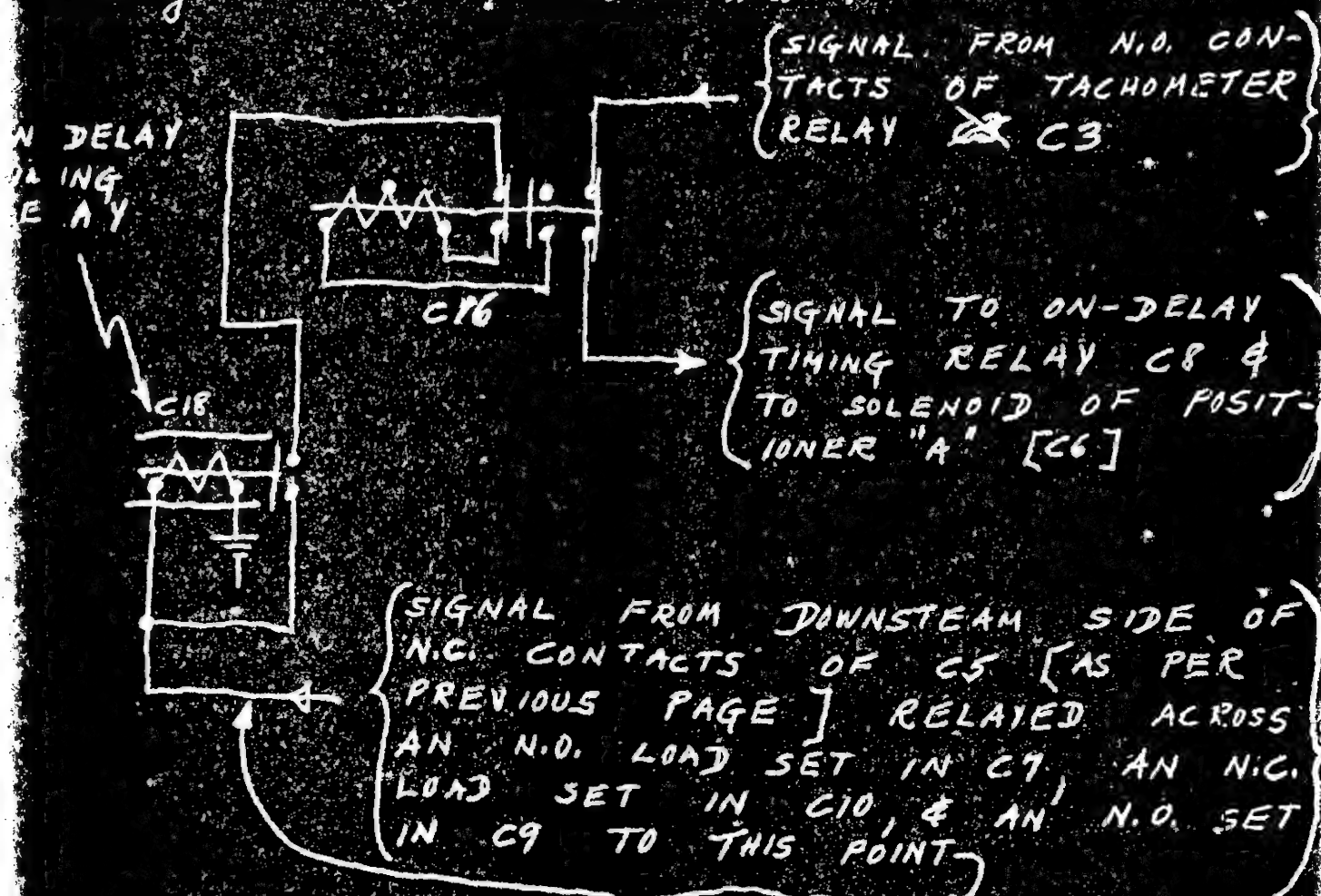
Studying the Microscope Control Circuit as given on Dwg. #9, it will be seen that when C7 and C9 are engaged, and C10 is disengaged, a path is opened for a signal starting from p'see supply, and after transmission ~~to~~ over an appropriate set of contacts in each of the mentioned relays, terminating at the normally-closed set of auxiliary contacts of the mechanically-held relay C16. The necessary conditions for the opened path, namely that C7 and C9 be engaged while C10 be disengaged, are fulfilled as a sequel to item (C) above. From pages 101-111, it will be found that after C7 is engaged as per (C) above, C10's disengagement is made responsive to a signal starting from the normally-open set of contacts in the limit switch C5. This signal which is transmitted across a normally-open set of load contacts in C7 to the normally-open set of auxiliary contacts in C10 occurs when the latch pawl of Drum #2 has already mounted the approach block of Knob "B" during the Drum's travel towards the black-and-white viewing, required position. It will also be found in the "Description . . . .", pages 101-111, that the mounting of the approach block of Knob "B" by the latch-pawl member of Drum #2 is followed shortly thereafter by a blocking of the latch-pawl



2. The grab-slat of Drum "B", signifying the arrival of Drum #2 at a position which is consistent with a proper alignment of the clear slot of Drum #2 with a clear slot in Drum #1 for the purpose of black-and-white viewing. Thus, since the signal which engages C16 (and consequently disengages C6 [the suboid of Positioner "A"]) occurs when the locking action between the two Drums is impending rather than completed, it may be argued that a possibility exists that the ultimate absorbing of the flywheel energy of Drum #2 and the rotor of the Drive Motor could act to rotate the Drum Assembly's position past the 'window' in the cabinet. To obviate this possibility, it would be possible practical to draw the prime signal for the disengagement of C16 from the downstream side of the normally-closed set of contacts of C5 instead of from phase supply as now indicated on Dwg. #9. This scheme is illustrated below:-



By the scheme illustrated above, the signal engaging C16, and consequently disengaging the Drum Assembly-rotating action of the plunger of Positioner "A", would await the completion of the locking-action between the Drums. This means as well that the newly-aligned Drums would be prevented from slipping past the 'window' in the cabinet. Any further assurance that the newly-aligned Drums should not slip past the 'window' would be obtained from introducing a time-delay factor between the completion of the afore-mentioned locking-action and the retraction of the Plunger of Positioner "A" from the drill-hole of Grab "A". If this were done, then a way of doing it would be as indicated below:-





Of the matter raised on page 202, only one has thus far not been discussed, and this is Item (b) dealing with relay C15. On Skt. #19, as is recalled in Item (b), C15 was indicated as a conventional relay; while on Diag. #9, it appears as a mechanically-held relay. Two reasons underlie the change, of which the first is the more important:-

1. Skt. #19 indicates that the prime signal for the engaging of C15 originates at the N.C. contacts of C5, is transmitted across an N.O. load set in C9 to an N.O. set in C14, is then transmitted across an N.O. set in C14 to an N.C. load set in C12 to an N.O. set in C11, and, finally, is then applied to the place side of the operating coil of the conventional relay C15. This would demand that C9 be in its engaged position, <sup>that</sup> C14 be engaged, that C12 be disengaged, and that C11 be engaged for C15 to be continuously engaged during color-viewing. However, since ~~the~~ the engagement of C14 is dependent on C15 being disengaged, it follows that the engagement of C15 would lead to the disengagement of C14, which would in turn lead to the secondary disengagement of C15 — and ultimately to a shattering relationship between C14 and C15. This is the prime reason for the change shown on Diag. #9;
2. The second reason lies in the inadvisability of C15, or any other relay, being continuously energized during the operation of the TV circuit, since A.C. chatter and electrical disturbances to the operation of the TV circuit are possible. By making C15, a mechanically-held relay the permanent engagement of C15 prior to

(29)

the disengagement of C14 is occurred; and, once, the engagement of C15 is established, it holds that engagement without any further feed of power. The latter fact satisfies the above-mentioned conditions that no member of the switching circuit be capable of "chattering" or demand a continued feed of power during any viewing cycle, other than — possibly — the Tachometer Relay.

As C15 is now specified, its engagement follows the completion of the downer-realignment action, for the engagement signal is transmitted along the following path:—

- a) the signal originates at the downstream side of the N.C. contacts of C5, which means that the latch-point of Down #2 must be in its "low" position;
- b) the signal as of (a) is relayed across a normally-open load set in C9, which means that C9 must be engaged — and this condition is satisfied since C9's position is reversed only after C15 is engaged;

- c) the signal as of (b) is applied from the downstream side of the N.O. load set in C9 to the upstream side of an N.O. set in C14, which means that C14 must be engaged for the further relaying of the signal — and this is satisfied since C14 is engaged as long as C2 is in its rotor position and C15 is disengaged;

- d) the signal as of (c) is applied from the downstream side of the N.O. set in C14 to the upstream side of an N.C. set in C12, which means that C12 must be disengaged for the further relaying of the signal.



— and this condition is satisfied by the fact that C12 is restored to its disengaged position once the latch-pawl of Drum #2 is brought to a given state of 'left' by the approach block of Crab "A"

and,

- e) the signal as of (d) is relayed from the downstream side of the N.C. load set in C12 to an N.O. load set in C11, which means that C11 must be in its engaged position for further relaying of the signal — and this condition is satisfied by the fact that C11 is sent into its engaged position by the 'drift' of Drum #2 past the departure block of Crab "B" during the travel of Drum #2 towards its color-realigned position with Drum #1, and further C11 maintains its engaged position until the next black-and-white relaying alignment is signalled.

The signal as of (e) is then applied to C13. Since the 'left' of the latch-pawl by the approach block of Crab "A" eminently precedes the locking of Drum #2 into its color-alignment position with Drum #1, it follows that C13 is engaged only as color-alignment of the two drums is achieved or is eminently about to be achieved. By the refinement of the control circuit given on Page 115, it would follow that C13 would ~~also~~ engage to release Position "B", disengage C14, and restore C9 and C7 to their disengaged positions, only after <sup>the</sup> color-alignment of the two drums has been achieved.

This item (b) on Page 202 is explained:

## TWO IMPORTANT CONSIDERATIONS:

Two important considerations underlie the projected design of the Circuit. These are:-

- a) the type of mechanically-held relay used
  - b) the timing between the release of Position "A" block and white alignment has been achieved
- It has been repeatedly set forth above that one of the functions served by the use of mechanically-held relays was to eliminate better and electrical disturbances to the operation of the TV circuit with the functional demands on any given relay at its continued engagement. This set of qualifications more or less defines the type of relay which is required. Explicitly, it would be required that:-

- i. The holding of the relay in engaged position be accomplished either by a mechanical or a magnetic latch
- ii. a second operating coil which overcomes the mechanical or magnetic latching action be a part of the relay.

Mechanical latches for the holding of relays in their engaged position are extremely common, and in fact, the name — mechanically-held relay — is derived from the original use of such latches. More recently it has been common to replace mechanical latches by permanent magnets which hold the relay-plunger the plunger is drawn against the permanent magnet pole-face. This type of construction, which has been referred to as a magnetic latch, is preferred here, since strictly mechanical latches are subject to imperfect operation when the baseboards to which they are attached are jammed.

Finally as regards the mechanically-held relays used



should be observed that to ensure the best operation of such a relay, the two operating coils of the relay — the one which acts to engage the relay, and the other which acts to disengage, or de-latch the relay — should be signalled, thru auxiliary contacts which are operated in common with the load contacts. The contacts which are auxiliary to the engaging action — the N.C. auxiliary contacts — should have a 'dropping effect' incorporated in them to secure the completion of the engaging stroke against a spurious or 'chattering' 'making' action.

If the construction schedule for the models permits, I will design a set of relays suited in size and other characteristics to the demand of the Control Circuit.

On the subject of the decision to disengage Positioner 'A' after black-and-white alignment of the Drive has been achieved, it has been held here that the inertia of the Drive Assembly and the Drive Motor rotor, plus the friction forces between the gears constituting the power transmission, would be sufficient to hold any previously established position once the desired Drive Assembly alignment and positioning in front of the cabinet window has been achieved. The further argument that a continued energizing of the Positioner solenoid might lead to 'chattering' and also to electrical disturbances to the T.V. circuit's normal operation led to one of two solutions:-

\* A. either construct the Positioner potentiels along mechanically-held lines;

B. hold any given Drive Assembly position on the basis of the inertia and friction forces named above.

The latter was chosen for the reason of the costs involved in the former alternative.

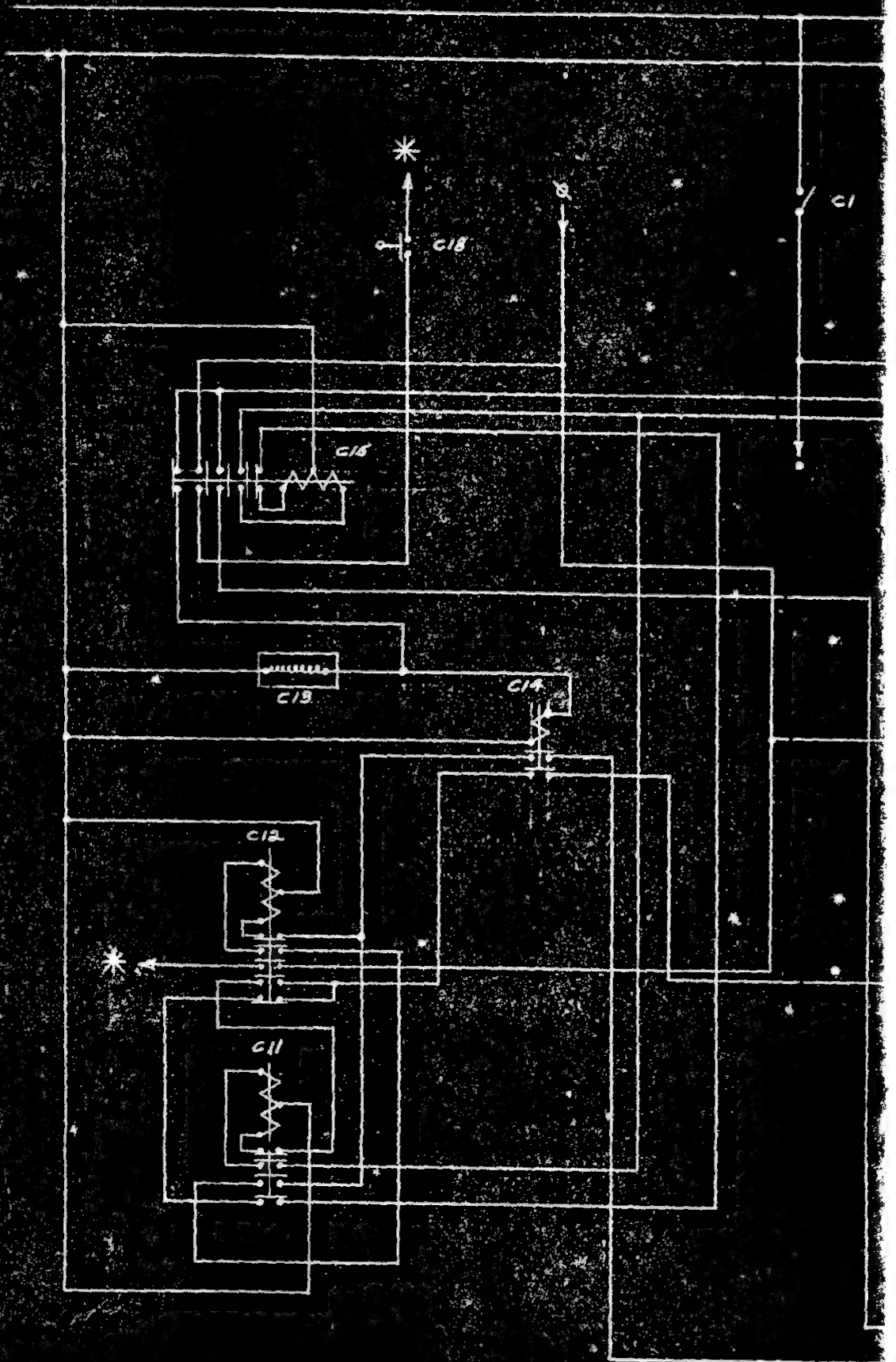
\* NOTE:- WILL NEW 7 17 11

and 205

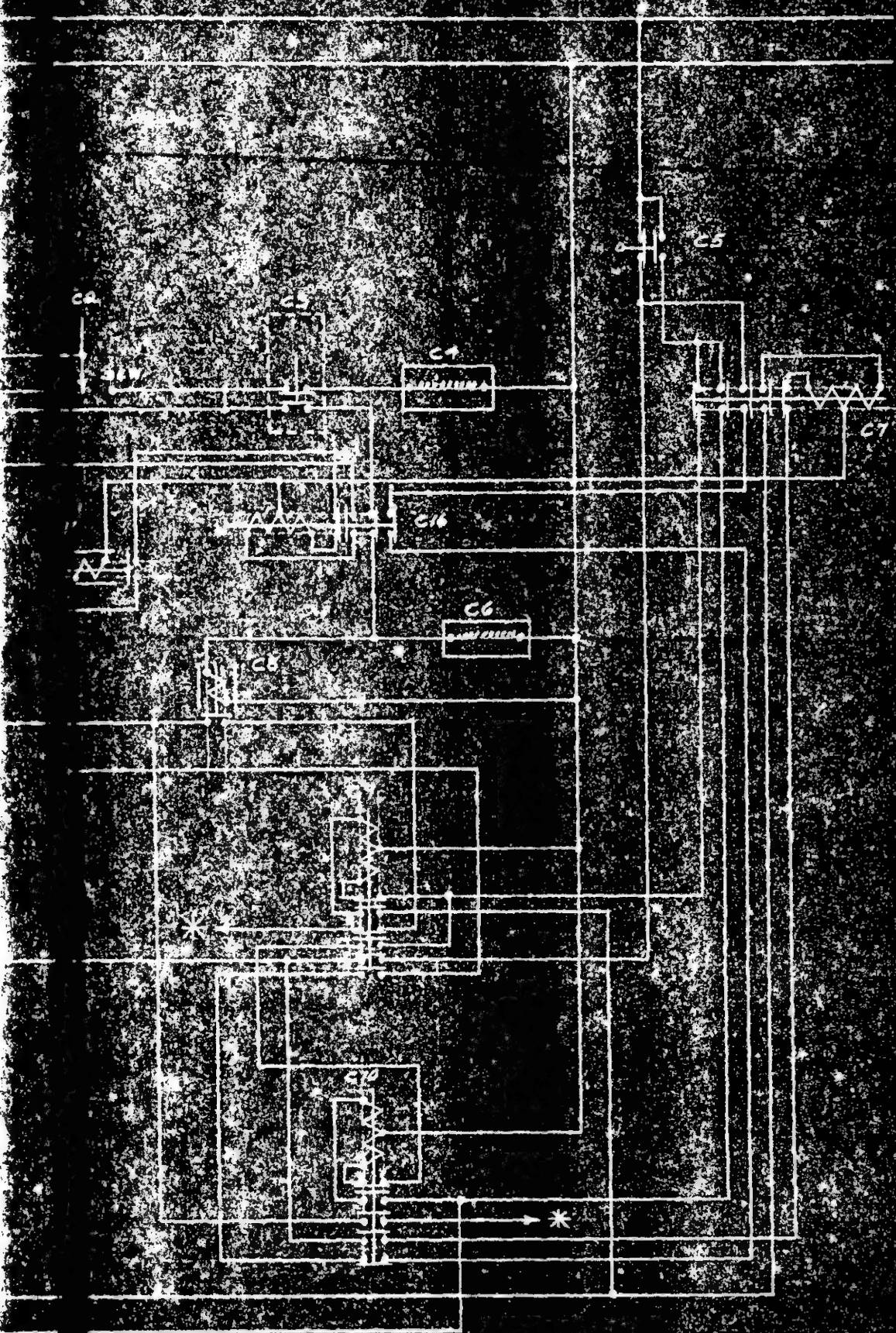
June 21

THE MICROSCOPE CONTROL CIRCUIT

DW







Journal of the  
Exploration of the  
Interior of the  
United States  
by  
Major  
John W. Powell  
and  
Lieutenant  
John H. Smith  
of the  
United States Army  
in the  
Year 1859

The first object of the expedition was to explore the country between the Colorado River and the Rocky Mountains, and to determine the extent of the Great Salt Lake. The second object was to explore the country between the Colorado River and the Rocky Mountains, and to determine the extent of the Great Salt Lake. The third object was to explore the country between the Colorado River and the Rocky Mountains, and to determine the extent of the Great Salt Lake.

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The principal <sup>design</sup> provisions set forth by Draw. # 1-9, as referred to Sheets # 1-19, are the following:-

A. THE DECISION TO GIVE INNER DRUM END-RING (R.H.) A DOUBLE SUPPORT:- Draw. # 1 in its DETAILS "J" indicates that the Inner Drum End-Ring (R.H.) is to be a spoked ring, with its spokes attached at one end to a central hub and at their other end to an angle rim. DETAILS "J" further indicates that the rim bears support members which ride on the inner side of the Outer Drum End-Ring (R.H.). The "double support" for the Inner Drum End (R.H.) in this case can then be said to consist of:-  
a) the spoked construction which supports the ring from the stationary shaft (Detail "D"); and, (b) the "support members" construction which supports the ring from the Outer Drum End-Ring (R.H.).

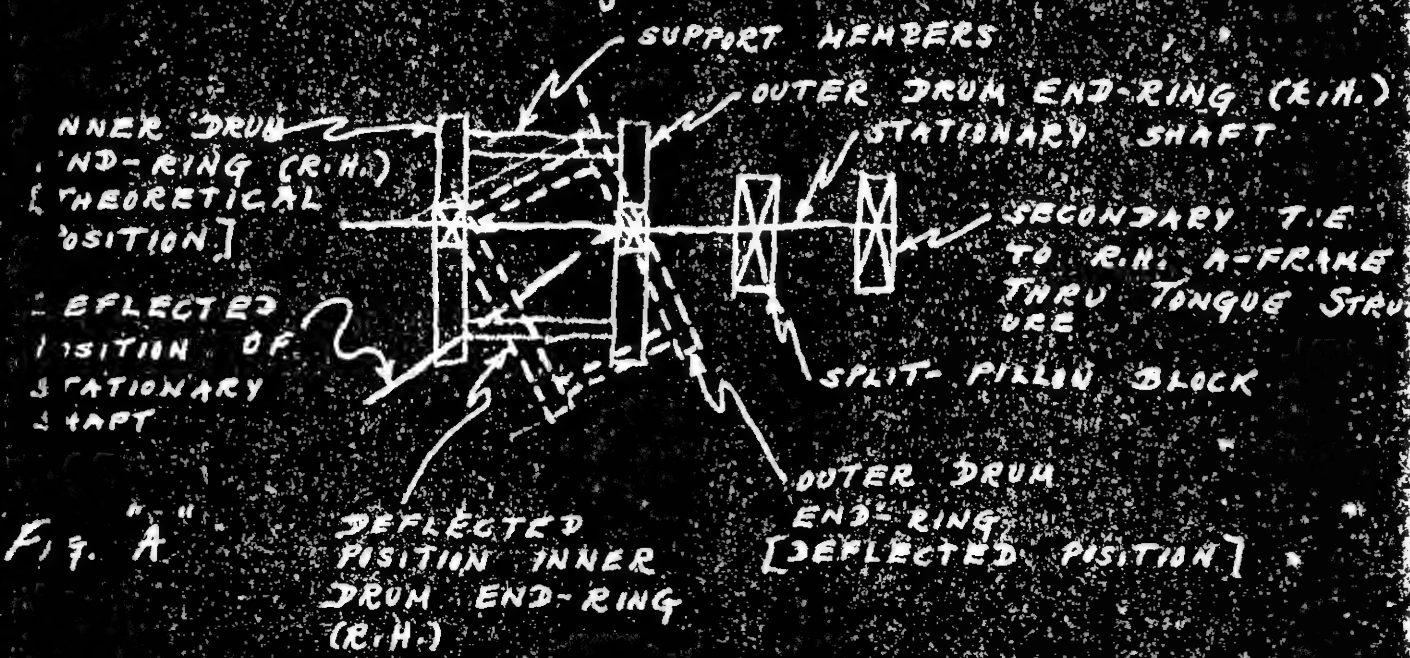


Fig. "A" sets forth the operative principle of the assembly which is obtained via the "double support" arrangement. It will

apparently be seen that the "support members" (the Drums #1 & 2) are a means of assuring "squareness" between both rings and the stationary shaft about which they rotate, in that they (the "support members") establish a parallel alignment between both rings (as they are related to one another). Thus, if either of the rings were to depart from its theoretically "square" geometrical relationship to the principal axis of the shaft, the "support members" would force the other ring into a parallel alignment to the first, and, thus the spoke support structure of the second, the second ring would communicate the slope of the deflected shaft at the first ring to the point at which the second ring is anchored.

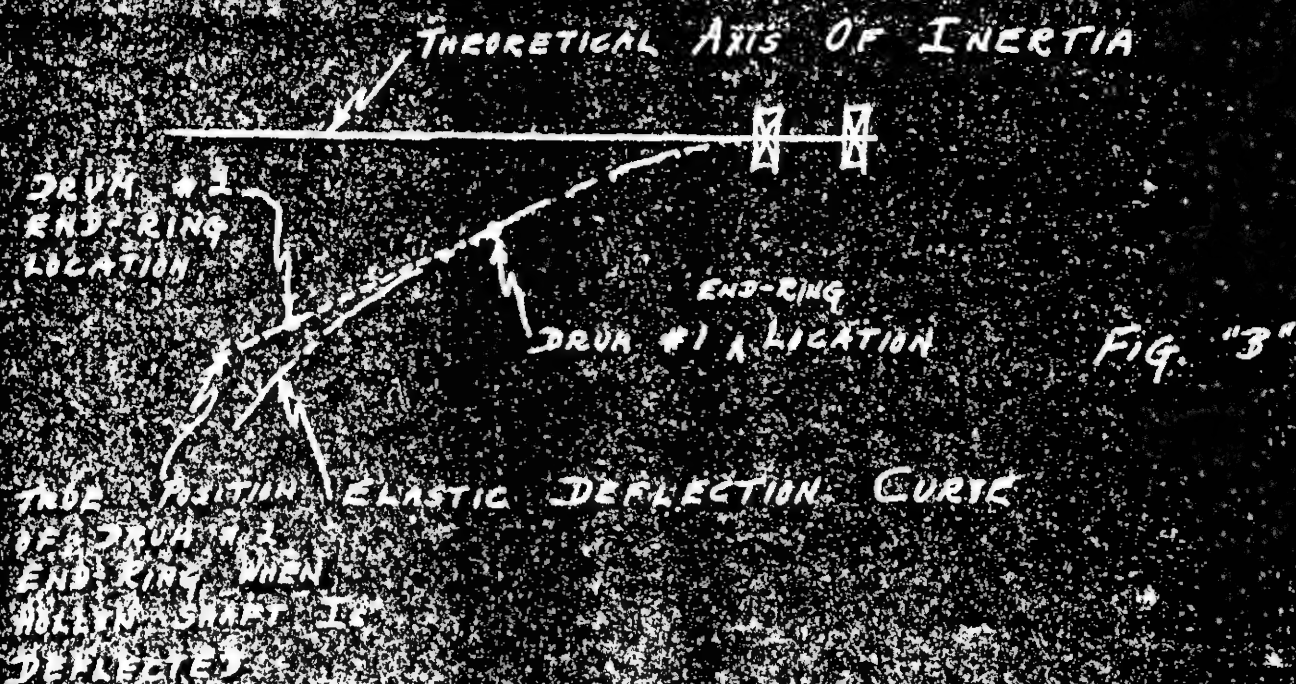


Fig. "B" illustrates the thought expressed above, and indicates that, if the stationary shaft is a sufficiently stiff member, the R.R. End-Rings as an assembly would be a stable one. Having arrived at this conclusion, it was then possible to consider the R.R. End-Rings as an independent assembly. Further, this is illustrated in the diagram.



used on the L.H. side; -

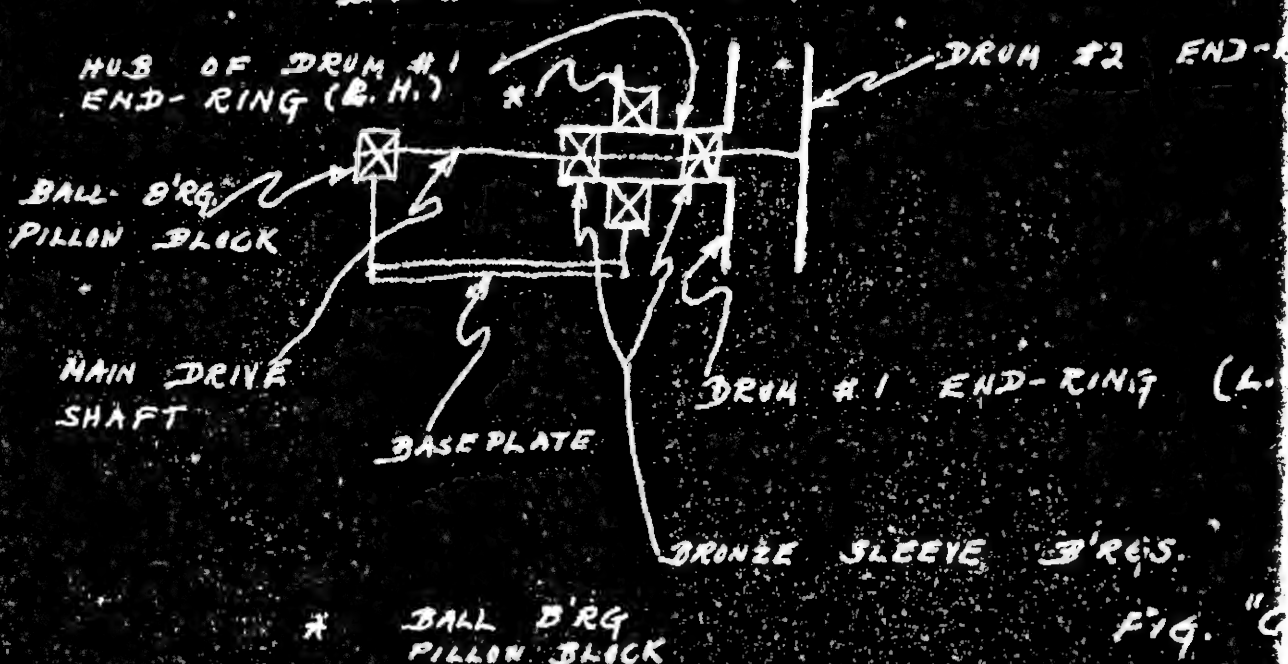


FIG. "C"

Observing Fig. "C", it is clear that the Bronze Sleeve is a means of preserving a parallel alignment between two indicated End-Rings. Once this is clear, it is that if the thus-aligned rings are now adequately secured as an assembly the stable independence of the L.H. Assembly is an established fact. The two ball-bearing block units provide the support for the assembly as a whole.

Thus, it will be seen that both the R.H. and the L.H. Rings - Assemblies form individually stable, independent devices. Each draws its fundamental stability from its A-frame on which it is mounted. And so, if the connections between the two A-frames are made in a manner that the two A-frames are integrated as a stable and stiff composite structure, it will be that little if any of the responsibility for the operation

of the Microscope as a whole would be imposed on the plate comprising the Drum Assemblies. In fact, the load imposed on the Drums would be transmission of the accelerating and the braking torques to the R.H. Ring-Assembly. The narrowing <sup>down</sup> of the structural and dynamic functions of the Drums, to the ones which have just been cited makes it feasible to adopt the following lines of assembly and maintenance:-

i. in assembling the Microscope, it is possible to establish a sequence in which the two A-frames and their inter-connecting members are first put together to form the prime structure. Next, each of End-Assemblies of the device should be assembled onto each of the A-frames. This should then be followed by a mounting of the C.R. tube and its auxiliaries on the Mounting Plate (See Diag. # 4) and a connecting of these members to the appropriate leads in the cable coming thru the hollow shaft member of the Mounting Assembly. With the foregoing having been accomplished, the plate for the Inner Drum, and later the plate for the Outer Drum, should then be fastened onto the appropriate End-Rings to yield a fully-assembled unit which is then placed in the cabinet.

and, ii. in the replacement of the C.R. tube or in checking the leads to the tube and its auxiliaries, this will be done by removing one or more adjacent plates on both Drums to get at the Tube Mounting Plate. The plate which may be removed for such purposes might best be clearly indicated by some special marking on the non-viewed ends of the plate.



It will already be surmised from what has already been said on the assembly and the maintenance topics that the "welded longitudinal frame" which, between plates, which Aug. #1 sets forth, and which were similarly set forth in the earlier sheets #1-19, are to be abandoned in favor of an individual fastening of each plate to the appropriate End-Rings, with each plate remaining an individually constituted member not otherwise connected to its adjacent plate, then by the "ring effect" of the End-Rings. As to the fit of each plate to its next adjacent plate, more will be said in the comments which are to follow on the fabrication of the plate themselves. It therefore just seems to say that as a result of the "double support" principle which has been built into the R.H. End-Rings, and because of the mutual parallel alignment feature which has been built into both End-Rings - assemblies, no reliance is now made on the Drons themselves towards the stiffness of the assembly as a whole; and the comments in the report which appear on Pages 7 & 8 of the communication of 7/6/51 are therefore to be disregarded.

B. THE SPECIFIC DESIGN OF EACH OF THE END-RINGS:- In Augs. 1-9, the rim members of the End-Ring have been specified to be of angle members, rather than the types of rims specified in sheets #1-19. In the case of both Outer Dron End-Rings, the spoke formation has also been altered over that previously given. Concerning the End-Rings rim members, the choice now of an angle section over the simple rectangular section previously indicated on sheets #1-19 was dictated by the desire to give all of the rims a greater stiffness to with-stand roundness distortion influences. Moreover, the use of an angle shape in the case of both Outer Dron End-Rings contributes towards the ability to employ spoke formation which would otherwise not be possible.

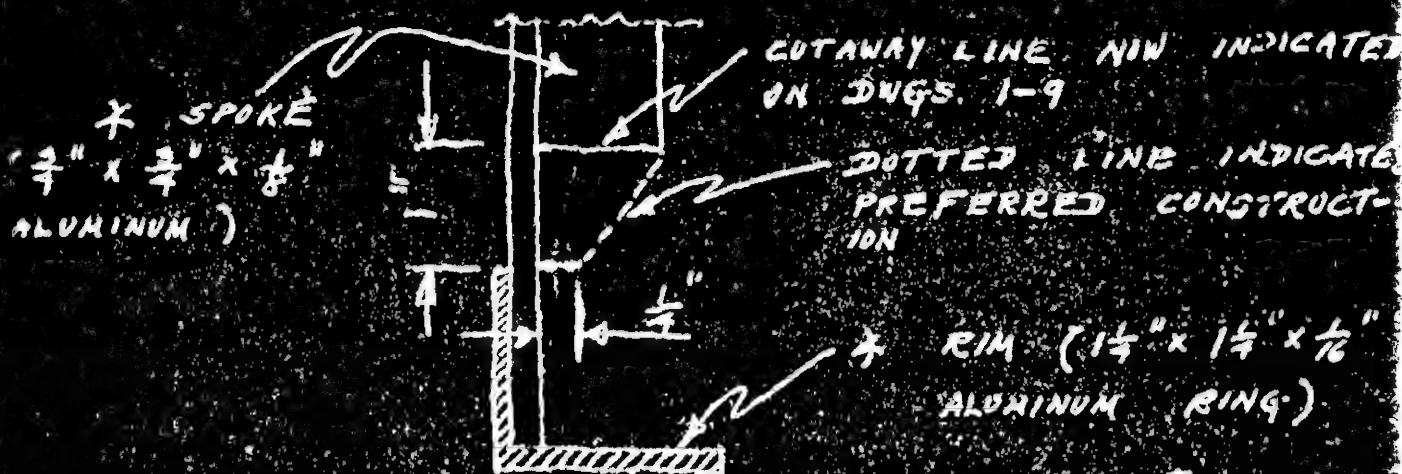
<sup>dependence of the</sup>  
The shifting of the structural (i.e. static) and dynamic  
boundaries of the wrist as a whole from its previous base in  
the 'complete cylinder effect' of the Drum to its later base  
in the metal parts of the assembly was the principal motivating  
factor in going to an angle section for the rim. But the  
fact that the angle shape is a stronger form and its necessity  
(from the standpoint of ease of assembly and maintenance) for  
shifting from a dependence on the Drums for a weighty contribution  
to the strength and roundness properties of the assembly need no  
further discussion. Let us turn therefore to the way in which  
the angle rims have contributed to other aspects of the construction.

The 'other leg' of the angle rims employed, it will be seen,  
has served as:- a) a means of securing of firm joint between  
the rims and the spokes; and; (b) a means of anchoring  
such gadgetry as the support plate for the recoil spring and the  
limit switch components of the latch-pawl device (on the L.H.  
Inner Drum End-Ring) and the side-plate to which the  
the support ends of the "support members" are attached (in the  
case of the Inner Drum R.H. End-Ring). Specifically, on the  
junctions of both Outer Drum End-Rings, the inner surfaces  
of the rims must be 'clear' for the movement of gadgetry associated  
with the Inner Drum. This necessitates, in both instances, that  
one leg of the angle spokes be cut away to provide the necessary  
freedom of movement. The fact the Outer Drum End-Rings <sup>rims</sup> are  
formed of an angle section make it possible to provide the  
necessary cut-away without risking a wobbling of the  
rings due to a weakening of the spoke, since the stiffness  
of the rim can be held to be transmitted in part to the  
one remaining leg (of the cutaway spoke), by which the rim  
~~is fixed to the drum members of each ring~~ Here, the fact that  
the remaining leg is welded along all of its lines-of-contact  
to the side leg of the rim, and the <sup>strength</sup> properties of the



residual span of the cutaway length of the spoke, combine ~~to~~ to draw on the angle rim for a stiffness which would not otherwise be expected for the cutaway length.

A preferred construction in regard to the spokes-to-rim joint for both Outer Prime End-Rings would have been that shown below over that indicated in Dwg. 1-9:-



In any case, the use of angle spokes in the <sup>vicinity</sup> of both Outer Prime End-Rings in the place of the constructions indicated in Dts. 1-19 which call for the use of channels tied into relatively complicated joints with each rim, is a move in the direction of space-saving and a more rigid construction for the overall rings. The use of an angle section for the End-Rings rings and the use of angle spokes tied into angle butt-joints with the rims and hubs of the Ring-Assemblies is in fact a part of the general conclusion that the plastic frame per se should not be depended on for any substantial contribution to the stiffness of the overall assembly.

III. THE CHANGES IN THE SPECIFICATIONS FOR THE BEARINGS:- Inspecting Dwg. 1-4, it will be

stated that anti-friction bearings have been used wherever the members in motion are involved in roller-creeping (that is, wherever the members in relative motion experience duty for substantial periods of time); and, where the members in relative motion experience duty only during Drum-realignment, these bearings have been specified to be skirt-type bearings of the "proven" construction type. Thus, the bearing between the stationary shaft and the Outer Drum End-Ring has been changed from the construction shown in Sheet #1-19 to an anti-friction bearing as shown in Sheet #1-9. With regard to the stationary shaft-to-Outer Drum End-Ring bearing, it is well to point out that the "the assurance of equivalence" with the stationary shaft, which the construction shown on Mt. #12 would have contributed to is accomplished in the case of the presently-indicated construction by the Balke-Support Effect between the two R.H. End-Rings, as was noted above. The reasoning behind the preference for anti-friction bearings when prolonged bearing duty is involved is of course obvious.

#### B. THE DESIGN OF THE "SUPPORT MEMBERS" :-

On Sheet #11 of the originally submitted Sketch Sheets, "bearing arms" of methyl-methacrylate were proposed. These were to be attached to a at that time proposed plastic end-ring of the same material for the R.H. side of Drum #2. These "bearing arms" were to ride on the inner surface of the R.H. Outer Drum End-Ring, and to play a part not different from that now proposed for the "support members" on Drums #1 of the series Drums #1-9.

The presently-proposed "support members", which involve a roller action on an axle attached to the Inner Drum R.H. End-Ring, were substituted for the originally-proposed "bearing arms" because they are capable of taking a larger load, and also because over a long period of time the presently-proposed "support members" would require less



maintained and would be more noise-free.

E. THE LATCH-PAWL MECHANISM ALTERATION:

I  
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Before discussing the alteration in the design of the latch-pawl, it would do well to point out a revision which should be made in the design now projected on Draw. #1 of Draw. #1-9. As presently indicated on Draw. #1, it would appear as if the 'relaxed' position of the latch-pawl would involve its hub member resting on the floor of the inner Outer Drum L.H. End-Ring. This should be altered so that the relaxed position of the spring (Ⓢ on Draw. #1) controlling the pawl's position keeps the pawl about 1/8" off the mentioned floor. This would mean that there would be no scraping action by pawl's hub on the floor of the given End-Ring when drum-realignment occurs; and, yet, the engagement of the End-slot of either drum would not be ill-affected as to the positiveness of engagement between the two drums. With the slight modification of the design shown on Draw. #1, it is clear that the only contact between the Inner latch-pawl and L.H. End-Ring of the Outer Drum would occur when: (a) the two drums are engaged; and, (b), when the latch-pawl mounts the slope of either drum's approach-block. For the case where action (b) occurs, the roller-covered roller on the shank of the pawl would give a noiseless rolling action whereas the design originally submitted on Sketch Draw. #1-19 would involve a scraping action between the latch-pawl and each approach block.

and,

F. THE SPECIFICATIONS FOR AND THE FABRICATION OF THE SLATS:-

The originally-submitted bill-of-materials and the document of 7/6/51 called for the use of 1/8" malleable sheet of steel, saturated blue, patented green, and saturated red colors.

At the time, these specifications were laid down it was <sup>the</sup> ~~understanding~~ understanding of the writer that polymethacrylate sheet of the correct optical filter properties is available. This is apparently not true. It now appears that true colors depend on the use of filters of tight optical specifications. Against this fact information, it would appear that the optimum construction for the filter-slats would consist of Wratten Blue #1, Wratten Green #58, and Wratten Red #26 filter slats sandwiched <sup>in an optical grade</sup> unwrinkled and uncreased form between two  $\frac{1}{16}$ " thick <sup>poly-</sup> polymethacrylate sheets preformed to the specified curvatures. [NOTE: - At a later date, some experimentation in the deposition of filter gelatin on one of the two methacrylate sheets forming each composite slat would be in good order, and instructions in this regard will be furnished.]

As to the composite slat as defined above, the adjacent longitudinal edges should be so finished off that tight, square fits between the slats are possible. In the case of clear slats, two slats of  $\frac{1}{16}$ " thick polymethacrylate sheet should be employed encasing a balancing sheet of clear cellophane should be used. [ \* Balancing here means balancing the filter Wratten color filter sheets used in the color filter slats. ] No bonding, as previously indicated, between the longitudinal slat joints will be necessary. Each slat made up as above outlined is to be independently attached to the appropriate End-Rings.

## THE PRINCIPAL ASSEMBLY PROBLEMS:-

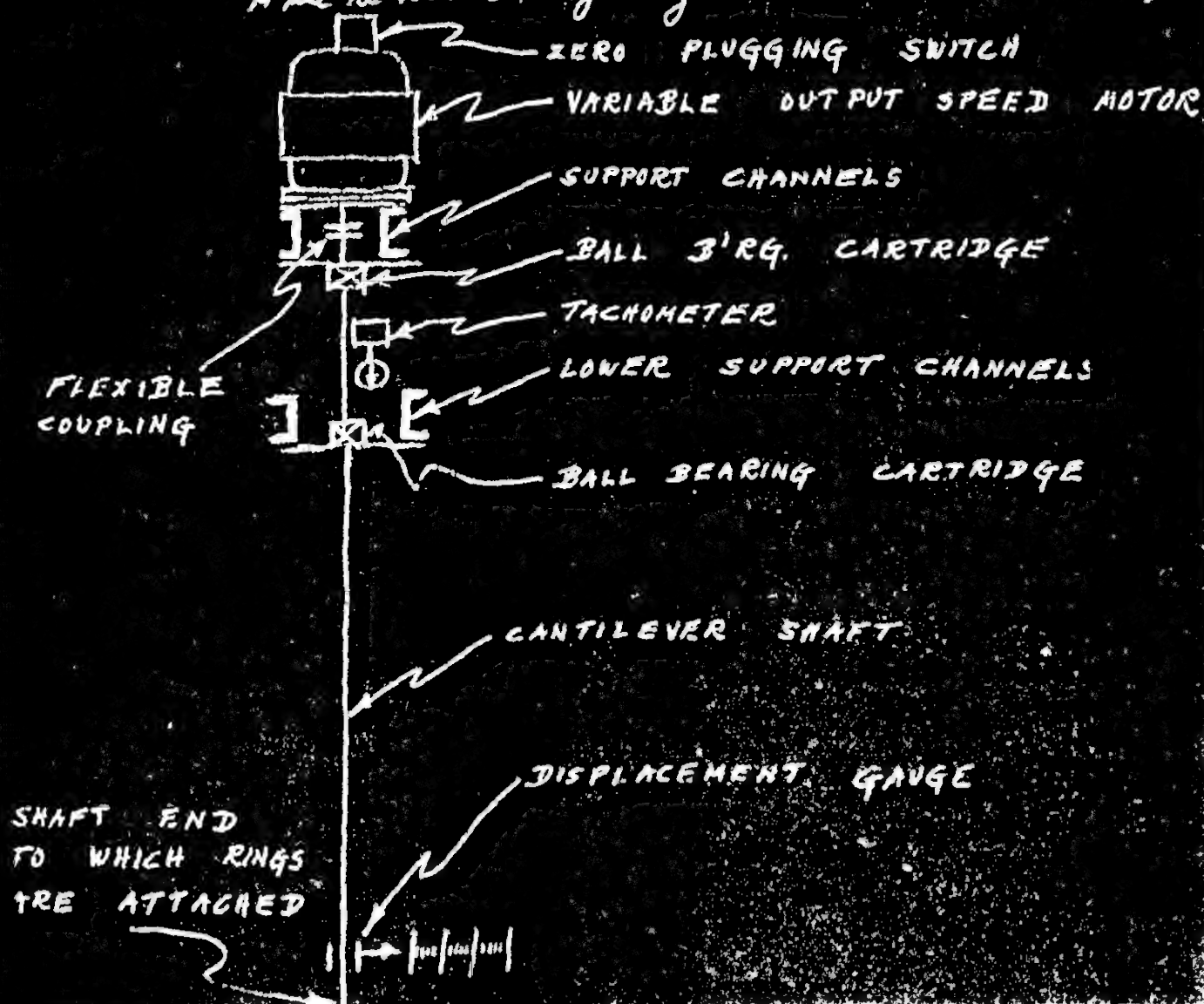
The proper operation of the microscope as it is now projected depends on the following critical factors:-

### I. THE PROPER BALANCING OF EACH OF THE END-RING UNITS:-

Quite obviously, at least two of the End-Rings [ The L.H. End-Rings of the



Inner and Outer Drums] are not balanced as shown on Diagrams 1-9. It goes without saying that a substantial order of 'dynamic balance' is demanded of all of the End-Rings. As a first step, each of the Rings shall be brought to 'static balance' individually. Conventional procedure for the accomplishment of 'static balance' will suffice. After each Ring has been brought to 'static balance', a satisfactory method of testing for 'dynamic balance' and adjusting according to measurements determined thereby would be to use a device as generally outlined below:-



The apparatus sketchedly indicated above would operate on the relationship between  $(E)$  - the eccentricity of the attached rotor,  $(\omega_n)$  - the natural frequency of the loaded Ring & loaded cantilever shaft assembly,  $(\omega)$  - the angular velocity of the rotating assembly, and  $(y)$  - the linear displacement of the shaft due to the influence of  $(E)$ . Of the above variables,  $(y)$  would be determined by the displacement gauge and  $(\omega)$  by the tachometer. Since  $(\omega_n)$  is an analytically-computable property of any system in which the weight of the Ring, the length, diameter, and weight of the shaft, and modulus of elasticity of the shaft are known, it follows that an alignment chart of proper make-up would yield a value for  $E$ , the amount at which the rotor mass acts to induce the displacement of the shaft. The determination at any identical shaft velocity of the displacement following from the clamping of a known weight to any randomly-chosen but accurately determined point on the rim of any Ring would then permit the determination from a second alignment chart of the radial direction of the centrifugal force due to the rotor's mass acting at the previously determined eccentricity. The same second alignment chart could be set up to yield the point at which a balancing weight should be placed to yield a given order of balance at the test shaft velocity. A series of three, at most, such combined measurements, each followed by the appropriate attachment of balancing weights, — with one test being performed at a low velocity, one test at an intermediate velocity, and the third at the full operating velocity of the Ring, would suffice to yield a properly balanced ring for incorporation in the Winiacscope.

Yet the balancing of each of the Rings to a high tolerance would not necessarily mean the obtaining of a suitably balanced overall assembly

rules  
of  
in-  
spection



even if the method of attaching the slats and the distribution of mass amongst the slats were perfect, which admittedly is not a theoretically obtainable condition. Before the driving gear is located in its designated position, it would be necessary to test the unit for static balance. Once assured of, ~~not~~ corrected to, an adequate condition of static balance, the device in its assembled form would have to be mounted on a ~~spring supported~~ <sup>for</sup> test table ~~or frame~~, preferably a light frame (which is to say, a frame composed of light members). Using a vibrometer to measure the amplitude of the vibrations induced in the floor frame where the A-frames are tied in, it is possible to correct any assembly unbalance condition according to which of three classes of unbalance is determined to exist. These three conditions of unbalance can always be resolved to the operation of two centrifugal forces acting from the same side of the axis of rotation and in the same axial plane; or, two forces — producing a rotation couple — acting in the same axial plane but from equidistant opposed arms as referred to the axis of rotation; or, two forces — capable of being resolved into a couple and one additional force — when the two forces act in different axial planes. The addition of compensating weights to produce opposing the Outer Drum End-Rings to produce opposing couples and/or forces then corrects the dynamic balance of the assembly. The balancing of the microscope should be accomplished in two stages: — the first at Drum speed roughly  $\frac{1}{2}$  of the operating speed; and, the second at the full operating speed of the assembly.

II. THE FITS BETWEEN CRITICAL MEMBERS OF THE ASSEMBLY :- To assist in this matter, a schedule of the required fits between various assembled members is given below :-

BULKY EXHIBIT

Date received 9/5/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

153. Miscellaneous papers found in Brothman's cell after his removal to Atlanta.

100-95068-1B

8/2



# BETWEEN

&

# CLASS OF FIT

Plastic Commutator  
Ring Holder

Inner Core of  
Main Drive Shaft

Friction Fit

Outer Race of  $1\frac{1}{8}$ "  
shaft size bearing

Core of the Pillow  
Block Housing

Loose Fit

Core of the Inner  
Race of the  $1\frac{1}{8}$ "  
shaft size bearing

Main Drive  
Shaft

Tight Fit

Output Shaft of  
the Motor Drive

Core of the Inner  
Race of the Outboard  
Bearing

Loose Fit

Hub of the Outer  
Drum L.H. End-  
Ring

Core of the Inner  
Race of the  $1\frac{3}{4}$ "  
shaft size bearing

Tight Fit

Outer Race of the  
 $1\frac{3}{4}$ " shaft size  
ball bearing

Core of  $1\frac{3}{4}$ " pillow  
Block Housing

Loose Fit

Main Drive Shaft

Core of the Bearing  
Housing in the Hub  
of the Inner Drum  
L.H. End Ring

Medium Fit

Main Drive Shaft

Core of the Inner  
Race of the  $1\frac{3}{4}$ "  
shaft size bearing

Working Fit

Stationary Shaft

Core of the Inner  
Race of the  $1\frac{1}{16}$ " shaft  
size ball bearing

Loose Fit (Medium)

Outer Race of the  
 $1\frac{15}{16}$ " ball bearing  
in the Hub of the  
Inner Drum R.H.  
End-Ring

Core of the Hub of  
the Inner Drum  
R.H. End-Ring

Tight Fit

| <u>BETWEEN</u>  | <u>&amp;</u>  | <u>CLASS OF FIT</u> |
|---|---|---------------------|
| Stationary Shaft  | Core of the Inner<br>Race of the $1\frac{13}{16}$ "<br>shaft size ball<br>bearing in the hub<br>of the Outer Drum<br>R. H. End Ring | Medium Force Fit    |
| Outer Race of the<br>$1\frac{13}{16}$ " shaft size<br>b. b. in the hub<br>of the Outer Drum<br>R. H. End Ring | Core of the Hub<br>of the Outer<br>Drum R. H.<br>End Ring   | Tight Fit           |
| Member (43)<br>Dwg. #1  | Member (45)<br>Dwg. #1  | Medium Fit          |
| Member (46)<br>Dwg. #1  | Member (45)<br>Dwg. #1  | Free Fit            |
| Member (66)<br>Dwg. #1  | Outer Portion of<br>Member (62)<br>Dwg. #1  | Medium Fit          |
| Member (53)<br>Dwg. #1  | Shaft member of<br>Disintegrator<br>Assembly - Dwg. #1  | Loose Fit           |

- ① Where the superscript ① appears, attention is called to the fact that the fit should approach a "wringing" or "turning" fit.
  - ② Where the superscript ② appears, the specified " snug fit " should be a typical "snug fit".
  - ③ Where the superscript ③ appears, the specified "Tight Fit" should approach a "wringing" or "turning" fit.
  - ④ Where the superscript ④ appears, the specified "medium force fit" should approach a "tight fit".
- \* The ball bearing referred to here is in the hub of the Inner Drum R. H. End Ring.



BETWEEN&CLASS OF F1

Bearing Bushings

Bore of the Outer  
Drum L.H. End-  
Ring

Wringing Fit

Bearing Bushings

Bore of the Stationary  
Shaft

Wringing Fit

Hollow Shaft Member  
of the Tube Support  
PlateBore of the Bearing  
Bushings in the  
Stationary Shaft

Slug Fit (2)

Hollow Shaft Member  
of the Tube Support  
AssemblyBore of the Hub of  
the Tube Support  
Bracket

Wringing Fit

Stationary Shaft

Hub of the "second  
support" anchor

Slug Fit (1)

Bore of the Lower  
Gear

Main Drive Shaft

Slug Fit (2)

Output Shaft of  
the Motor Drive

Driving Gear

Slug Fit (2)

Finally, as regards the Support Member of the Inner End-Ring (R.H.) and the Outer Drum End-Ring R.H., it should be taken that each roller member is in solid contact with the whole rotation of these roller members with the inner surface of the rim of the Outer Drum End-Ring R.H. And, regarding the Stationary Shaft in the Split Pillow Block, the latter, be drawn up rigidly tight against the Stationary Shaft, the capscrews fixing the two halves of the Split Pillow Block be provided with lock-washers to prevent a loosening of the Stationary Shaft.

III. A variety of assembly and operational factors will be discussed in the final section of this document under the collective heading of a "Syllabus of Possible Reqs. And Their Correction".

\* \* \* \* \*

RE-CALCULATIONS CONCERNING THE  
SALIENT FEATURES OF THE  
DESIGN

THE SLATS



The larger diameter set of slats would have an outer diameter of  $24 \frac{1}{16}$ ". The approximate area of each slat is

$$\frac{2\pi(13)(60)(24 \frac{1}{16})}{360} = 338 \text{ in}^2$$

and if each slat were  $\frac{7}{16}$ " thick the volume of each slat would be -

$$\frac{338 \text{ in}^2}{\frac{7}{16} \text{ in}} = 21.1 \text{ in}^3$$

and since the specific gravity of polymethylacrylate sheet is 1.1 and assuming each slat would have a weight of

$$\frac{21.1 \text{ in}^3}{1.1} (1.1) (21.1 \text{ in}^3) = 0.902 \#$$

being at an angular velocity of

$$24 \text{ rpm } \left( \frac{2\pi \text{ rad}}{60 \text{ sec}} \right) = 150.8 \text{ rads/sec}$$

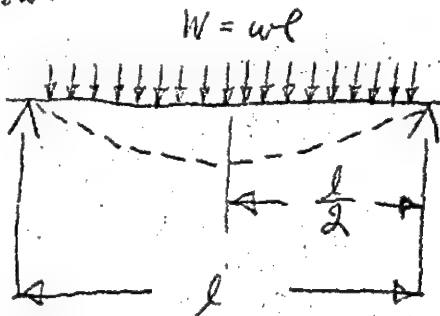
The centrifugal force acting on each slat would amount to



$$F_c = \frac{0.1902 \cdot \#}{32 \frac{\text{ft.}}{\text{sec.}^2}} \cdot (150.8)^2 \frac{\text{rad.}^2}{\text{sec.}^2} \left( \frac{13 \text{ ins.}}{12 \frac{\text{ins.}}{\text{ft.}}} \right)$$

$$= 694 \#$$

The force would be distributed as a uniform load over the entire  $l$  of the loaded beam to give a condition as schematically indicated below.



$$W = wl$$

$$EI \frac{d^2 y}{dx^2} = \frac{wx}{2} (l-x)$$

$$\frac{dy}{dx} = \frac{w}{2EI} \left( \frac{lx^2}{2} - \frac{x^3}{3} \right)$$

$$\text{Since } \frac{dy}{dx} = 0, \text{ where } x = \frac{l}{2},$$

$$0 = \frac{w}{2EI} \left( \frac{l^3}{8} - \frac{l^3}{24} \right) + C_1$$

$$C_1 = -\frac{w}{2EI} \left( \frac{l^3}{12} \right) = -\frac{wl^3}{24EI}$$

whence :-

$$\frac{dy}{dx} = \frac{w}{2EI} \left[ \frac{lx^2}{2} - \frac{x^3}{3} - \frac{l^3}{12} \right]$$

$$y = \frac{w}{2EI} \left[ \frac{lx^3}{6} - \frac{x^4}{12} - \frac{l^3 x}{12} \right] + C_2$$

Since  $y=0$ , where  $x=0$ , then  $C_2=0$ ; and,

$$y = y_{\max}$$

where  $\frac{l}{2} = x$ , so that

$$y_{\max} = \frac{w}{2EI} \left[ \frac{l^4}{48} - \frac{l^4}{192} - \frac{l^4}{24} \right]$$

$$= -\frac{w}{2EI} \left[ \frac{5l^4}{192} \right] = -\frac{5wl^4}{384EI} = -\frac{5Wl^3}{384EI}$$

Referring back to the diagram on Page 318, the dot on the y - indicates the center of gravity of the slot. The distance ( $\bar{y}$ ) of the dot from the axis of rotation would be given by :-

$$\bar{y} = \frac{r \sin 30^\circ}{\text{rad } 30^\circ} = \frac{13(0.5)}{\frac{\pi}{6}} = \frac{13(3)}{3.14} = 12.42$$

The x-sectional area of the slot is approximately

$$\frac{2\pi \times 60^\circ}{360^\circ} \cdot t = \frac{2\pi(13)}{6(16)} = \frac{26\pi}{96} = 0.852$$

and its approximate ( $I_0$ ) about its center-of-gravity is given by :-

$$0.852(13.00)^2 = I_0 + 0.852(12.42)^2$$

where  $13''$  is taken to be the radius of gyration of the slot about its x-axis thru the axis of rotation. By the equation derived on Page 31 then

$$y_{\max} = \frac{5(694)(24 \frac{1}{16})^3}{384(26)(10^6)(12.78)} = \frac{5(694)(15)(10^3)}{384(26)(10^6)(12.78)} = 0.000408 \text{ in.}$$

This is indeed a negligible deflection, but it is based on the value for ( $E$ ) — the ( $E$ ) for steel — which is in all likelihood large; but even if it were  $\frac{1}{30}$  of the indicated value, then

$$0.000408(30) = 0.01224''$$

would be the approximate magnitude of ( $y_{\max}$ ). Even such a value could be tolerated; and would evidently involve a very low stressing of the slot. If, as per Page 311, two sandwichee sheets of methacrylate were to be used, then

$$\frac{360}{60}(694)(2) = 8328\#$$

would be the total load imposed on the Outer Drum End — by the plate when the Drum is rotated.





The stress induced in the End-rings would be a low stress. In fact, a  $1\frac{1}{4} \times \frac{1}{2} \times \frac{1}{8}$  aluminum alloy is employed. The x-section of the angle offers an  $I_x$  of 0.3 in.<sup>4</sup>. This would mean that, since the load is between two Rings,

$$\frac{8328 \#}{2(0.3) \text{ in.}^4} = 13,880 \#/\text{in.}^2$$

would be the tensile stress induced. This stress lies actively beneath the elastic limit of such aluminum 515, and hence is acceptable.

#### CONCLUSIONS UP TO THIS POINT:-

- A. The 60° slats, which are the weakest of the slats in the Outer Drum, will not suffer any undue flexion due to centrifugal loading during the running of the Drum Assembly. If this is true of slats in the Outer Drum, it certainly means that slats in the Inner Drum are equally "safe".
- B. The Outer Drum Rings, which were originally specified at  $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{16}$  4s, but which in practice were brought to  $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{8}$  4s, are certainly safe. For the Inner Drum End-Rings which are  $1\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$  4s, and which have a cross-sectional area of 0.13 in.<sup>2</sup>

$$\frac{8,328}{2(0.13)} = 31,600 \#/\text{in.}^2$$

would be the induced stress, which is still beneath elastic limit for a 515 aluminum. Consequently, the Inner Drum Rings are also "safe". If the modulus of elasticity of the 515 is taken at  $3.7(10^6)$  lbs./in.<sup>2</sup>,

$$E = \frac{S}{\epsilon} = \frac{31,600}{\epsilon} = 3.7(10^6)$$

$$\epsilon = \frac{31,600}{3.7(10^6)} = 0.00854$$

which is to say that

$$2\pi(13)(0.00854) = \text{peripheral stretch}$$

the rim = 0.696"

during rotations in the case of the Inner Drum E.  
If the increase in the circumference,  $(\Delta c)$ , is 0.696  
then

$$\frac{0.696}{6.28} = 0.11"$$

would be the increment in the radius of the wheel.  
The moment we were to drop the restraining influence  
spokes from consideration. Continuing the check,  
clear that @ a hoop stress of 13,800 #/in.<sup>2</sup>

$$\frac{13,800}{31,600} (0.11) = 0.0481"$$

would be the radial stretch in the Outer Drum.  
Correcting the 0.696 circumferential stretch for the  $\pi$   
of the Inner Drum Ring, which is  $25\frac{1}{2}"$  instead of 2.  
find

$$\frac{25.5}{26} (0.696) = 0.684" = \Delta c$$

and

$$\frac{0.684}{2\pi} = \Delta r = 0.1088"$$

the Ring radius would go from 12.75"

$$12.75 + 0.1088 = 12.8588"$$

for the case of the Inner Rings, while the Outer R.  
would go from 12.9375" to

$$12.9375 + 0.0481 = 12.9856"$$

the gap between the Rings of

$$12.9856 - 12.8588 = 0.1268"$$

any as opposed to the static gap  
calculations are enough to indicate  
of the radial stretch in the me



Outer-

The stress in the Rings due to their rotation is given by

$$T = \frac{W}{g} v^2 \quad (\#/ft.^3)$$

where:-  $w$  = the density of the ring-material;  $T$  = tensile stress, and,  $g$  = gravitational acceleration,  $ft./sec.^2$ . Where the sp. g. of is 2.7, then

$$\begin{aligned} T &= \frac{2.7(62.5)}{32} \cdot \left[ (24 \text{ rps}) (2\pi \text{ rads/rev}) \left( \frac{13 \text{ in}}{12 \frac{\text{in}}{\text{ft}}} \right) \right]^2 \\ &= 140,000 \text{ \#/ft.}^2 \\ &= \frac{140,000 \frac{\text{\#}}{\text{ft.}^2}}{144 \frac{\text{in.}^2}{\text{ft.}^2}} = 973 \frac{\text{\#}}{\text{in.}^2} \end{aligned}$$

The combined <sup>tension</sup> stress in the Outer Rings due to their rotation and due to the imposed load from the slats would be

$$13,880 + 973 = 14,853 \frac{\text{\#}}{\text{in.}^2}$$

which would mean a radial stretch of

$$\frac{14,853}{3.7(10^6)} \times 13 = 0.523 \text{ "}$$

which are approximately 12" in length, a unit elongation of

$$\frac{0.523}{12} = 0.0436$$

$$3.7(10^6)(5.96)(10^{-3}) = 16,080 \text{ \#/in.}^2$$

the stretch of the spokes would take place over a distance of this stretch, for the four spokes are pulled on the rim. Between

the uniform loading of a spoke, for the  $1\frac{1}{4} \times 1\frac{1}{4} \times 0.5 \text{ in.}$ , a stress

a stress of 14,853 lbs./in.<sup>2</sup> means a load of

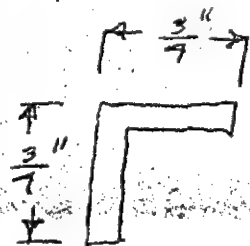
$$14,853(0.3) = 4455.9 \text{ \#/ring}$$

Per spoke, this would mean

$$\frac{4456}{4} = 1114 \text{ \#}$$

or a stress of

$$\frac{1114}{\frac{11}{64}} = 6500 \text{ psi}$$



$$\frac{5}{8} \times \frac{1}{8} = \frac{5}{64} \text{ in.}^2$$

$$\frac{6}{8} \times \frac{1}{8} = \frac{6}{64} \text{ in.}^2$$

$$\frac{11}{64} \text{ in.}^2$$

and, for a spoke length of approx. 12" the area to

$$\frac{6500}{3.7(10^6)} \cdot 12 = 0.0211 \text{ in.}^2 = A_L$$

For a uniformly-loaded beam with fixed ends, ( $y_{\max}$ ) [not shown here] would be given by:-

$$y_{\max} = \frac{wL^3}{384EI}$$

( $l$ ) may be taken to be  $\frac{1}{4}$  x the circumference, whence

$$\frac{13(2\pi)}{4} = 20.4 \text{ in.} = l$$

and, since  $I$ , for  $1\frac{1}{4} \text{ in.} \times 1\frac{1}{4} \text{ in.} \times \frac{1}{8} \text{ in.}$  is 0.04 in.<sup>4</sup>, then

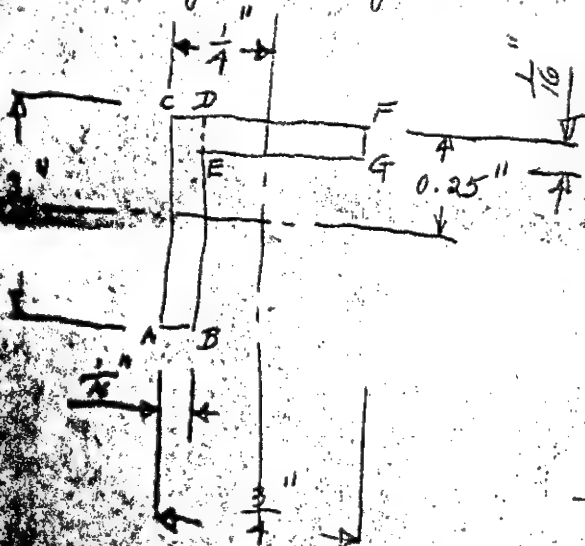
$$y_{\max} = \frac{1114(20.4)^3}{384(3.7)(10^6)(0.04)} = 0.2335 \text{ in.}$$

This indicates that a doubling of the number of spokes already specified would be required to hold the between-spokes deflection of the rim to tolerable limits. Such a doubling of the no. of spokes used would halve the load per span, and halve the span — the combined effect of which would be to cut the between-spokes deflection to  $\frac{1}{16}$  of the value computed above.

$$\frac{0.2335}{16} = 0.0146 \text{ in.}$$



In the case of the inner kerge, only part of the solution to the problem of preventing a large between-spokes deflection lies in doubling no. of spokes, for the moment of inertia of the angle section is



The moment of inertia of ABCD about its own neutral fibre would be :-

$$\frac{1}{12} \cdot \frac{1}{16} \cdot \left(\frac{3}{4}\right)^3 = \frac{0.92}{19.2} = 0.00219$$

About the indicated X-axis the moment of inertia of this section would be

$$\begin{aligned} I_x &= 0.00219 + \frac{1}{16} \cdot \frac{3}{4} \cdot \frac{1}{8} \\ &= 0.00219 + 0.000073 \\ &= 0.002263 \\ &= 0.00226 \text{ in.}^4 \end{aligned}$$

The moment of inertia of EFG about its neutral fibre would

$$\frac{1}{12} \cdot \frac{3}{4} \cdot \frac{1}{16}^3 = \frac{3}{48(4100)} = 0.00001523 \text{ in.}^4$$

About the indicated X-axis would be approximately

$$\begin{aligned} I_x &= 0.00001523 + \frac{3}{4} \cdot \frac{1}{16} \cdot \frac{1}{4}^2 \\ &= 0.00001523 + 0.00293 \\ &= 0.002945 \text{ in.}^4 \end{aligned}$$

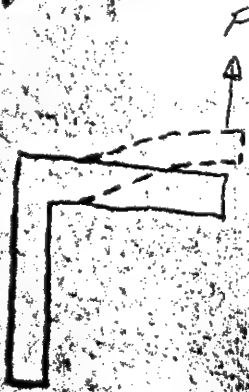
Total ( $I_x$ ) of approximately 0.00587 in. <sup>4</sup>

The moment of inertia of the angle section would increase by a factor of 7 in flexure. Roughly it would amount to

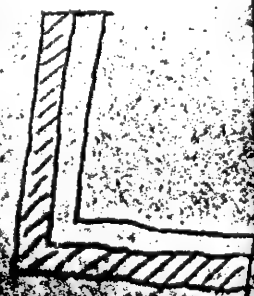
$$0.00587 \times 7 = 0.04109 \text{ in.}^4$$

$$\frac{2.6555}{16} = 0.091"$$

for an 8-spoke wheel. Before passing the "8-spoke" for  
to a conclusion, and before proposing a solution for the "between-spokes" flexure of the Inner Drum End-Rings, it  
pay to give attention to the problem which arises because of the  
loading of the centrifugal force acting on the plate to one  
of the 4 rims. A situation such as is indicated below

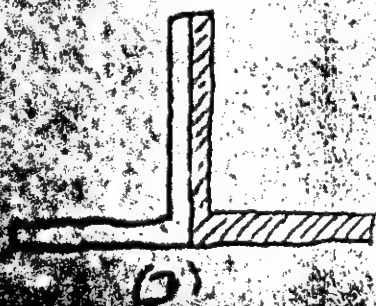


In other words, a tendency would exist  
loaded leg to flare out due to a result  
of the loading. This would be most noticed  
the case of the Outer Drum L.H. End-Ring  
then, in the next instance, in the case of  
Outer Drum R.H. End-Ring. It would  
applicable to the Inner Drum End-Rings, if  
the load involved is such that if it con-  
over any single portion of a  $1\frac{1}{4}" \times 1\frac{1}{4}" \times \frac{1}{8}"$   
will produce an excessive deformation of the concentrated-  
part. Since tension stresses are concerned, there is but  
one way to solve this, and that is to increase the area of the  
part. This is indicated some of the ways in which it  
can be accomplished:-



(C)





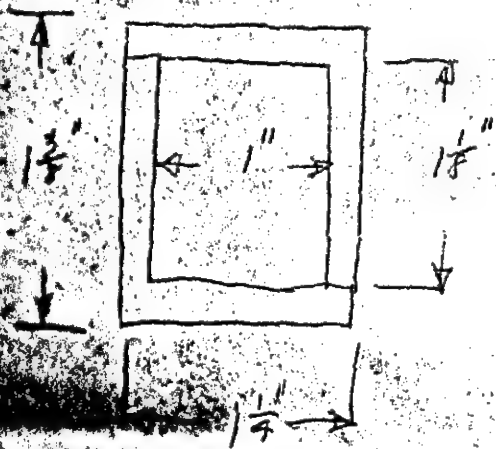
\* \* \* \* \*

(In each case, the x-hatched member is the presently-specified 7-in.)

\* \* \* \* \*

From purely structural considerations, (A) and (D) provide the soundest means of "beefing up" the stressed section. From a cost standpoint, (B) and (C), and particularly (B), stand better. (B) and (C) involve the greatest re-design of the lathe mechanism — in that for the given stroke of the "Positioners" plunger, any increase in the metal thickness of the leg through which the plunger goes means a decrease in the displacement of the lathe pawl can be pushed. Though it would seem that this is true for (A) as well, certain accommodations can be made with (A) which are not so easily made with the others.

In pushing towards a final solution of the problems involved, we have pinned ourselves on (A), and for the moment we have decided on the plate connecting of a sandwich type of construction. A section of 1/2" per inch of area of 0.6". The (I) for this sec.



would be :-

$$I = \frac{1.25(1.375)^3 - 1(1)^3}{12} = \frac{3.25 - 1.42}{12} = 0.1525 \text{ in}^4$$

Accordingly, the deflection of 0.0146" on Page 324 would now assume a value of

$$\frac{0.0146(0.04)}{0.1525} = 0.00363 \text{ inches}$$

The (I) value for a similarly treated Inner Drum End Ring would be

$$I = \frac{\frac{3}{4}\left(\frac{13}{16}\right)^3 - \frac{5}{8}\left(\frac{11}{16}\right)^3}{12} = \frac{\frac{3}{4}(0.532) - \frac{5}{8}(0.323)}{12} = \frac{0.399 - 0.202}{12} = 0.0164 \text{ in}^4$$

and, similar to the case of the Outer Drum End Ring, the deflection of 0.091" given on Page 326 would now be

$$\frac{0.091(0.006)}{0.0164} = 0.0333 \text{ inches}$$

which ring is 4455.9 #/ring.

The following table

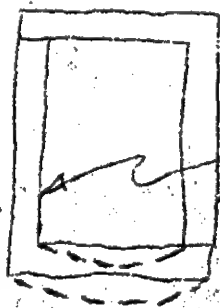
shows the



$$y_{max} = \frac{59.5 \left(\frac{1}{8}\right)^3 (12)}{192 (3.7) (10^6) \left(\frac{1}{16}\right)^3} =$$

$$\frac{59.5 (0.293) (12)}{192 (3.7) (10^6) (2.43) (10^{-6})} = 0.000922$$

be the probable order of the deflection of the loaded side of the box for the case of the box formed by the two  $\frac{3}{4}'' \times \frac{3}{4}'' \times \frac{1}{16}''$  &s, the beam formed by the bottom is held to have an  $(h) = \frac{1}{8}''$ ; and the so-formed beam is held to be one having its ends fixed. even the order of the flexure due to the slats in motion, or even if it several multiples of the indicated value, then the danger of a condition such as is indicated below:-



A SEVERE DEFLECTION OF  
BOTTOM PANEL OF THE BOX  
MEAN A DRAWING IN OF  
SIDE(S) TO WHICH THE ARR.  
POINTS

developing until a collapsing of the beam occurs is indeed possible.

Thus, it is possible to sum up the major aspects of this section by stating that the structural stability of the Drum under dynamic conditions demands that:-

- 1) the  $1\frac{1}{4}'' \times 1\frac{1}{4}'' \times \frac{1}{8}''$  & rims be converted from an angle section of the indicated dimensions to a box-section with an  $h = 1\frac{3}{8}''$  and a  $b = 1\frac{1}{4}''$  by properly joining two &s of the indicated specifications
- 2) the  $\frac{3}{4}'' \times \frac{3}{4}'' \times \frac{1}{16}''$  & rims be converted from an angle section of the indicated dimensions to a box-section with an  $h = \frac{13}{16}''$  and a  $b = \frac{3}{4}''$  by properly joining two &s of the indicated specifications

and,

- 3) each End-Ring should be converted from a 4-spoke ring to an 8-spoke ring

Having thus assured ourselves of the structural correctness & stability of the Drum Assembly as such, we may now pass to a consideration of the associated mechanisms.

Firstly, let us obtain an approximation of the weights of the two Outer Drum End-Rings and the two Inner Drum End-Rings:-

A steel  $\frac{3}{4} \times 1\frac{1}{4} \times \frac{1}{8}$  would weigh 1.01 #/ft. The of iron is 7.87, and that of aluminum 2.7. This means, on a basis of a 13" O.D. box-section, a weight of

$$\frac{2(1.01)2\pi(13)(2.7)}{7.87(12)} = \frac{566}{12} = 4.71 \#$$

for each of the Outer Drum End-Rings. The x-sectional area of a  $\frac{3}{4} \times \frac{3}{4} \times \frac{1}{16}$   $\pi$  is (Page 321) 0.13 in.<sup>2</sup> as compared a 0.3 in.<sup>2</sup> for a  $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{8}$   $\pi$ . Thus, the box section formed as per above from the  $\frac{3}{4} \times \frac{3}{4} \times \frac{1}{16}$   $\pi$ s would weigh approximately

$$\frac{0.13}{0.3} (4.71) = 2.04 \#$$

for each of the Inner Drum Rings. This would give a total of wt. of

$$2(4.71) + 2(2.04) = 9.42 + 4.08 = 13.5 \#$$

for the end-ring assemblies. To include the mechanisms which are hung onto the various End-Rings, it would be a fair estimate add on another 2.5 #, raising the total weight to 16 #.

Having ourselves on a sandwich formation for the slats 2 sheets of  $\frac{1}{16}$ " thk. polyethylene sheet holding between them



the filter sheet), it is clear by Page 318 that if one 60° s. weighs 0.902# for one 1/16" thick sheet, then the weight of methacrylate on each Drum would be of the order of

$$\frac{0.902(360)(2)}{60} = 10.824 \#$$

giving a total of 21.648# for both Drums. Approximating the weight of the Ribs and the plates to act from a 13" radius, then

$$\left[ \frac{21.65 + 16}{32} \right] \left( \frac{13}{12} \right)^2 = \sum m_i r_i^2 = 1382 \# \cdot \text{in}^2$$

Consider all of the spokes to be 13" lg., and fabricated from 3/4" x 3/4" x 1/8" angle. There are 8 spokes per wheel, and 4 wheels to take into this means

$$\frac{32(13)}{12} = 34.6'$$

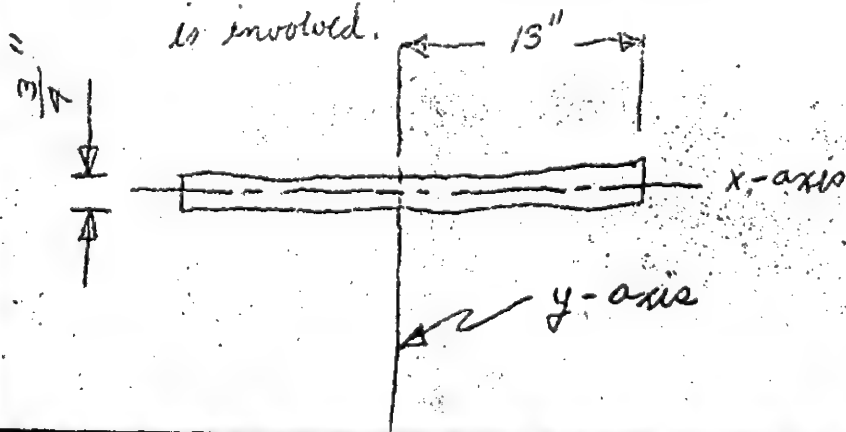
of 3/4" x 3/4" x 1/8" angle is involved. If, as per Page 321, a 3/4" x 3/4" angle has a x-sectional area of 0.13 in.<sup>2</sup>, then a 3/4" x 3/4" angle would have approximately 0.26 in.<sup>2</sup> of x-sectional area which would mean

$$\frac{34.6(0.26)}{1.74} = 0.0625 \text{ ft.}^3 \text{ of aluminum}$$

is involved. This would mean a weight of

$$0.0625(62.5)(2.7) = 10.55 \#$$

is involved.



Consider this 10.55# weight to be concentrated at a single bar, 21" lg. and 3/4" wide, about the origin of indicated set of axes.

The ( $m r^2$ ) about the x-axis would be

$$\frac{10.55}{32(12)} \left( \frac{26}{12} \right)^2 = \frac{10.55}{32(12)} \cdot 3.9(10^{-1}) =$$

$$1.08 \times 10^{-5} \text{ lbs. - ft. - sec.}^2$$

The ( $m r^2$ ) about the y-axis would be :-

$$\frac{10.55}{32(12)} \cdot \left( \frac{26}{12} \right)^2 = \frac{10.55(4.7)}{32(12)} =$$

$$1.29(10^{-1}) \text{ lbs. - ft. - sec.}^2$$

Since

$$I_p = I_x + I_y$$

$$= 1.08 \times 10^{-5} + 1.29(10^{-1})$$

$$\approx 1.29(10^{-1}) \text{ lbs. - ft. - sec.}^2$$

Thus, the Drum Assembly would have a total inertia of

$$1.382 + 1.29(10^{-1}) = 1.511 \text{ lb. - ft. - sec.}^2$$

Then, the energy that must be assigned to the Drum in getting it up to a speed of 150.8 rads./sec. would be

$$\frac{1}{2} \cdot 1.511 (150.8)^2 = \frac{1.511(22700)}{2} = 17,200 \text{ ft. - lbs.}$$

which, if done in 60 secs., would amount to :-

$$\frac{17,200}{60} = 284.4 \text{ ft. - lbs./sec.}$$

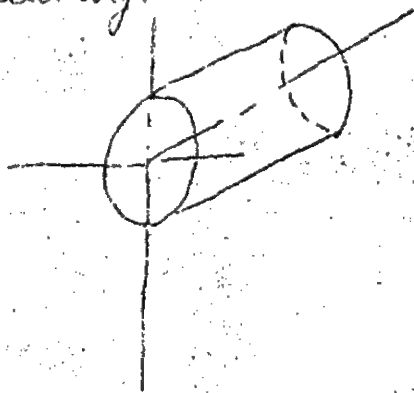
Start-up in 60 secs. would then demand a

$$\frac{284.4}{550} = 0.518 \text{ HP motor driver}$$

This size of motor demanded here for start-up alone raises the question of a reconsideration of the sandwich formation of the plates to reduce the weight involved.



But before we consider a change in the design of the plate, we enter into the question of the power demand of the against the air fluid that fills the cabinet. The prime power load is due to the centrifugal fan action of the Drum assembly.



The fan action would occur prior at the <sup>ends</sup> faces of the rotor, where cylindrical portion of the Drum a comparatively small contribution fan action. By a derivation indicated here, the fan torque of the end-faces would vary as the 5th power of the of the rotor, while the influence rotor length would be as the 6 of Drum length.

By the writer's understanding, a 22" diameter rotor, <sup>to</sup> called for a  $\frac{1}{10}$  HP motor driver. Then,

$$0.05 \left[ \frac{26}{22} \right]^5 \left( \frac{24}{16} \right)^{0.3} = 0.05 (2.3) (384) \\ = 0.05 (2.31) (5.95) = 0.688 \text{ HP}$$

would be the size of unit required to power the instant & if we assume that the  $\frac{1}{10}$  HP motor was 75% loaded, then

$$0.75 (0.688) = 0.516 \text{ HP}$$

would be the actual power-demand here. It would then be a  $\frac{3}{4}$  HP motor would be required.

Next, the question of braking the mechanism arises. If of the Drum assembly is 1.571 lb.-ft.-secs. and the Drum is brought to rest in about 6 secs, a negative deceleration

$$\frac{150.8(2)}{60} = 5 \text{ rads./sec.}^2$$

is needed, and this would require an applied torque of

$$1.511(5) = 7.555 \text{ ft-lbs.}$$

Basing ourselves on the Eddy Current Brake already described, the designed Brake at its feed of 25 milliamperes would exert a torque of

$$0.1772(25)(1) = 4.44 \text{ ft-lbs.}$$

at the peak velocity of the Drum; and, at  $(\frac{1}{25})$  of the starting running velocity of the Drum would exert

$$0.1772(1) = 0.1772 \text{ ft-lbs.}$$

Thus between an angular velocity of 150.8 rads./sec. and

$$\frac{150.8}{25} = 6.03 \text{ rads./sec.}$$

the designed Eddy Current Brake would exert an average torque of

$$\frac{4.44 + 0.1772}{2} = 2.31 \text{ ft-lbs.}$$

which means that

$$\frac{2.31}{1.511} = 1.528 \text{ rads./sec.}^2 = \text{the yielded}$$

negative acceleration, and

$$\frac{150.8 - 6.03}{1.528} = 94.4 \text{ secs.}$$

of braking-time would be required to go from 150.8 rads./sec. to 6 rads./sec. Thus, a slight re-design of the Eddy Current Brake to provide for a higher permissible current feed-rate might bring the speed-control Brake at its over-excited condition into effective use as the Brake for slowing down the drum in switching to black-and-white viewing.

One important question in viewing the braking problem, toward attaining a speed suitable for Plunger "A" to "go home" is the question of how much energy the plunger-member of Position "A" can absorb.

$$y_{\max} = \frac{WL^3}{3EI}$$



defines ( $y_{max}$ ) for a cantilever beam, which is what the plunger [item # 45, DWG. A1] is:-

$$y_{max} = \frac{Wl^3}{3EI} = \frac{(Wl)l^2}{3EI} = \frac{Ml^2}{3EI} = \frac{5El^2}{3EI}$$

$$= \frac{5l^2}{3Ec} = y_{max} = \frac{25l^2}{3Ed}$$

since  $l = 1.5$ ", if we specify a limiting stress of 20,000 psi,

$$y_{max} = \frac{2(20,000)(1.5)^2}{3(26)(10^6)(\frac{\pi}{16})}$$

$$= \frac{2(20,000)(2.25)(16)}{3(26)(10^6)5} = 0.0037$$

and now by

$$y_{max} = \frac{Wl^3}{3EI}$$

$$0.0037 = \frac{W(1.5)^3}{3(26)(10^6)\frac{\pi}{64}(\frac{5}{16})^4}$$

$$\frac{0.0037(3)(26)(10^6)(\pi)(0.0095)}{3.37} = W = 2560\#$$

which is to say that since the stored elastic energy would be given

$$E_e = W \frac{y}{2}$$

then

$$2560(0.0037) = 9.46 \text{ in-lbs.}$$

would be the energy which safely be stored in the plunger-me Positioner "A". Thus, the maximum speed from which the pos could act would be

$$\frac{9.46}{12} = \frac{1.511 W^2}{2}$$

$$\left[ \frac{2(9.46)}{12(1.511)} \right]^{1/2} = W = 1.04 \text{ rad/sec}$$

Actually, the above calculation, despite its optimistic reflections on the problem, yields a deceptive result. The force between the drill-hole knot "A" and the plunger of Positioner "A" which would be involved is impractical. We will return to a consideration of this point.

If we measure the use of a  $\frac{1}{4}$  HP motor and assume it is under <sup>constant</sup> operating conditions, it will give 25%, on the average, its full-load output torque, then

$$\frac{0.75(63025)}{1725} = 27.4 \text{ in.-lbs.}$$

or

$$\frac{27.4}{12} = 2.28 \text{ ft.-lbs.}$$

would be applied to the acceleration of the drum. Then

$$\frac{2.28}{1.511} = 1.508 \text{ rads./sec.}^2$$

would be the initial acceleration. To travel one full revolution then requires, starting from rest,

$$2\pi = \frac{1}{2}(1.508)t^2$$

$$\left[\frac{4\pi}{1.508}\right]^{1/2} = t = 2.88 \text{ secs.}$$

at which time the Drum Assembly would be moving with a

$$\text{velocity of } \frac{1}{2}(2.88)(1.508) = 2.17 \text{ rads./sec.}$$

At this velocity as indicated above and which Positioner "A" is to go home at the rate, it will clearly be seen that when the Drum itself is driven by the Drive motor in its alignment, the load imposed on the latched-pawl in locking will be substantial. This calls for a re-evaluation of the system to be used operating Positioner "A" and in



Regarding:-

1. The synchronization system:- Conditions now make it doubtful if I will have to leave the detailing of the scheme outlined in "Drive Motor Arrangements" to you. I believe that the ideas were outlined with a sufficient clarity to enable a competent servo-engineer to proceed with this. The calculations in "Drive Motor Arrangements" in view of the comments on motor size below hold on as an outline. All indications are that the same magnetic structures that operate the mechanism will be temporarily over-excited when braking for the black-and-white realignment of the Drums. This would eliminate the brute solution which the solenoid-operated brake provides. The calculations on Page 316 thru 336 indicate that a "shorting out" of the tube which normally feeds the magnetic structures in synchronization control, and a substitution of a source capable of feeding possibly 50 millionamps would provide braking in a reasonable time (estimated 1 minute).

torque control

2. The Drive Motor:- The calculations on Pages 316 thru 336 indicate that the motor size was sharply underestimated in the original calculations, and that a motor of  $\frac{3}{4}$  H size is required. The loading factor here is the "fan load" on the motor, rather than start-up energy. In computing the "fan load" the basic relationships I have used are correct (except as the influence of rotor diameter and cylinder length on the power required), but the estimate that a  $\frac{1}{2}$  H motor is 75% loaded with a 22" disc of  $\frac{1}{8}$ " thickness is just an estimate. Therefore the

Page (EE)  
Section marked  
IMPORTANT

Therefore the size of the Drive Motor should be checked against the more precise information you must have. It is possible a substantially smaller motor would suffice.

The gearing - The recent change in the gearing that drove the Main Drive shaft was in accommodation to the newly-conceived synchronization method. This will be seen from Page 6 of "Drive Motor Arrangements" and based on a 1725 rpm full-load motor speed. It is assumed that constant speed service for the motor would be established around the 1725 rpm full-load speed. The details here in this matter are left up to you. One thing is for sure must be lived up to here in connection with the gear and that is the use of an Oil Reservoir or Oil Bath. Right-angle transmission. Helical gearing is to be used. General, in all right angle gear transmissions, a great deal of rubbing action between the gear teeth is involved, and the proposed partially-filled Oil Bath (with one gear within the oil layer) provides for the long-life of the gears involved.

The functioning of Positioner "A" and realignment operation. The calculations on Pages 318 thru 336 indicate that during Positioner "A" entry action at speeds more than just a few rpm would be to impose such loads on the pin or plunger portion of the Positioner as would press the pin and the rim of the drill hole of the Positioner into each other, leading to a considerable friction between them. Moreover, it would seem that the rim of the Positioner would be driving the inner portion of the Positioner up to speeds in realignment operation. This would subject the Positioner to shock loads on the latch as well as the Positioner itself. Therefore, my suggestion



(C)

would be to: - a) bring the Drum Assembly to rest by positioning the Drum Assembly as a whole thru Positioner and, (b) in starting the Drum Assembly again preparatory to operating Positioner "A", to start the motor thru a High resistance that would reduce the applied voltage to the motor to a very low level - a level such that the motor would or weakly move the Drum. The same practice as regards the application of less than full voltage to the motor would apply to all realignment operations in which the Inner Drum is moved by itself. Some changes in the Control Circuit would be necessary by this scheme, and taking these in combination with those of using a temporarily over-excited Eddy Current Brake as the braking unit in black-and-white going to black-and-white alignment from color operation, would produce the following suggestion: -

the operating coil of

Positioner "A" should be activated as per the recent Control Circuit using the same signal that energizes the operating coil of C8.

and;  
As a whole, the functional pattern of the Control Circuit changes only in that Positioner "A" is actuated after the Drum Assembly has been brought to rest.

2) During the check version of the Ellinco D.C. Kene tachometer it would be possible to get a "rest signal" from the Drum Assembly, the signal be in the form of the absence of a blocking signal to tube operating a plate circuit relay. Such a relay would substitute the Tachometer Relay C3. The energizing of the plate circuit relay could relay signal from the black-and-white position of the selector switch C2 to the timing relay now from the application of the motor phase signal to the motor via C9, and by another set of contacts in the plate circuit relay, power supply from the black-and-white position of C2 to a conventional relay controlling a shunt out of the tube normally feeding the motor and use of the auxiliary power source for over current protection could be eliminated. Thus the starting of the motor Drive from "rest" to its positioner Positioner "A" would begin immediately after the Drum Assembly has been brought to rest and the Brake has been energized.

b) The feeding of the power signal to the motor from the indicated contacts in C9, C10, and C12 should in each of these coils pass thru the same resistance units to control the applied voltage and output torque from the Drive Motor, while in the case of C10, power supply for the regular motor running operation of the motor would be applied directly to the motor to get a full voltage energizing of the motor.

c) The information of the plate; - Page 310 comments on the fabrication of the plate, and suggests a sandwich structure in which two sheets of polycarbonate form an outer layer supporting a filter film. If such a structure can be obtained from a single sheet of polycarbonate, it can be applied, it should be the standpoint of many considerations to face.



IMPORTANT

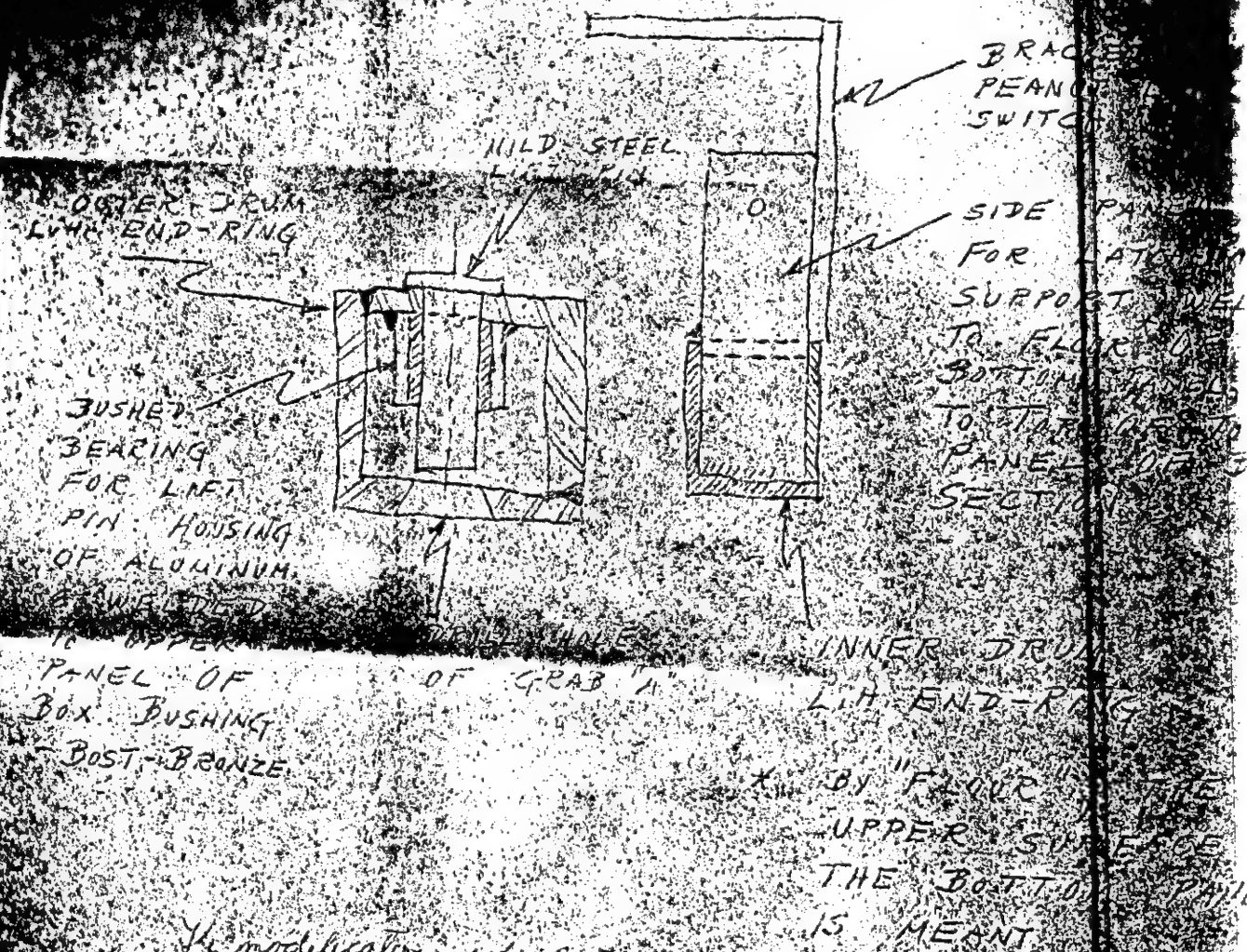
any method of obtaining adequate filter action by the use of a single methacrylate sheet for each slot should be used. But regardless of the slot formation method used,

1. The polymethacrylate sheet dimensions should be kept as now indicated.

2. The number of filter areas within each slot should be doubled to give what fundamentally amounts to a 12-color (4 sets of three) rather than a 6-color (2 sets of three) which would enable a halving of the drum speed and a saving in power from you. The use of clear methacrylate sheet as the base of the slot structure makes such a move possible since the filter sections are merely applied media to a clear sheet. <sup>Since the present</sup> as the cube of the drum speed, a cutting of the power requirement to one-eighth of the present computed level would be made possible as regards the minimum power requirements of the drum assembly. The start-up energy requirements for the same starting time would be cut to one-fourth of the present requirement. Thus it would be possible to use a  $\frac{1}{4}$  HP Drive Motor.

6. The End Rings - In conclusion of the calculations Page 315 to 316 it is that the outer drum end rings should be modified with a complementary  $\frac{1}{4}$  of the same dimensions as the present specified  $\frac{1}{4}$  to form a box-section ring with a base of  $1\frac{1}{4}$  and a height of  $1\frac{1}{8}$ , while the inner rings should be similarly modified to a height of  $\frac{1}{4}$  and a height of  $\frac{1}{8}$ . In conclusion that all dimensions from this point & apply.

for cor. & - spoke construction



The modifications which the box construction involves in the mounting of the lateral jaw, grab, and support mechanism are typified above. The lift-jaw construction between the jaw or plunger member of the positioner and the side support member of the lateral jaw. The same lift-jaw construction appears in connection with the side support member mounted on the top panel of the positioner. The side support member of the inner surface of the X-bar. The side support member of the lateral jaw are extended through the side support member and are welded to the side support member. On the other side of the positioner, the side support member is extended through the side support member.



... and "B" ... of the solenoid of ... energy in ... the recoil spring ... (b) the ... and "B" return to their ... distribution of the lift-force ... 50% of the lift force acts to ... the lateral recoil springs, and 10% acts to ... balanced would be adequate. In the case of the ... of Position ... the ball being against the scolded end of the ... 75% of the solenoid's lift-force, this spring should yield just enough for the ball to move clear of the ... the pin tube and roll in its ... back the ball up.

8. The framework - more important to the ... the unit is general ... into a stable and ... (and rigid) structure ... not been loaded on to the calculations. ... You ... the 4 members ... can be ... that members now specified ... become  $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{8}$ , while those specified as  $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{8}$  ...  $1\frac{1}{4} \times \frac{1}{4} \times \frac{1}{8}$ . The foot-pads ... the cabinet, and ... with ... certain amount of rigidity from the





BULKY EXHIBIT

Date received 2/20/52

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent J. M. Collins

Source from which obtained See Serial 768

Address \_\_\_\_\_

Purpose for which acquired Investigation

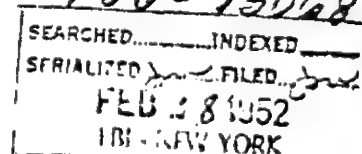
Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retained

List of contents:

154. Photostatic copy of the letter written by Brothman to the Reverend B.B. Nielsen, 4th Avenue, and 46th Street, Brooklyn, N.Y. whom Brothman classified as a friend.



NUMBER 71644  
NAME ABRAHAM BROTHMAN  
If written for one inmate by another enter name  
and number of the actual writer in space below:  
WRITTEN BY \_\_\_\_\_  
NUMBER \_\_\_\_\_  
Inmate's name and number must be signed at the  
bottom of this letter and correspond with that on  
this coupon.  
NOTE: Do not write on reverse side of this coupon.

Letter sent to Following Address:  
NAME REV. J. E. McLEEN  
Street and Number 7 AVE. 4  
City NEW YORK State N.Y.  
Relationship FRIEND  
**DO NOT WRITE BELOW THIS LINE**  
Last Letter to Same Address \_\_\_\_\_  
Total Number to Same Address \_\_\_\_\_  
FPI-LK-11-2-50-1,100M-7605

From ABRAHAM BROTHMAN  
PMB 71644, PENITENTIARY, PA.  
To REV. J. E. McLEEN  
(Name)

DEC. 27, 1952  
(Date)  
7 AVE. 4  
(Address)

Dear Bjorn,

I have your letters of Dec. 25 and Jan. 1, and as always these letters have brought the warmth, the loving kindness, and in general the wonderful spirit that I have found with you. And nothing comes more welcome to me than these good and human qualities. [and human] and not just 'good' alone, because something has then these qualities in it, more than 'human', something more that is associated with the lower species. I

I'm reminded of what the word 'human' has always meant to me whenever in the past as happened tonight, a sheet of paper entitled "Notice of Action of Parole Board" came to me. It happened, as you might surmise, in a single word: - "Denied", but, as is so often the case, what the high and the mighty would determine with a single word, it never quite gets that easily. For every contemporaneous verdict, it must be borne in mind, there will be a later and later decision, and that later decision belongs to history; and I'm confident that history will be with me.

But it nevertheless never fails, when I look at <sup>that</sup> presumptuous "Denied", to evoke a whole train of thought for it is no light matter to be told that your freedom is "Denied". I cherish freedom, but, as you and I might find out a little more than a year ago, I place it <sup>it</sup> cheaper than my <sup>written</sup> legal history. My application to the Parole Board and what I had to say in my personal appearance before the Parole Judge made this clear, for as accurately as I can recall both my written and my spoken words, I stated that one of my <sup>main</sup> reasons for my <sup>present</sup> application was for the earliest termination of a manifest injustice. And then I went on to say that the only possible motive for the alleged crime had to be a guilty association with espionage, and nothing could be more ludicrous than such an accusation for neither the Brothman that people knew in person nor the one they knew thru his writings could conceivably have been a trafficker in "secrets". On the contrary, I insisted, mine had been a record of a ruthless opposition to the penetration of magic and wizardry into science; and, moreover, I argued, I had always felt that the scientist to make his work publicly known stands on a higher calling than any other group.



7  
think of, having none. No person required by such a Opoint, and I offered more than a  
reprints of published articles to substantiate my claim to this viewpoint, could possibly have  
in "stock and dagger" newspapers to publish "secrets", nor could he have become the exemplar  
who found in such endeavor a satisfaction which outweighed their judgment or the knowledge

to "Denial" is the verdict on my request to serve at the earliest possible moment the  
dication of my lineage! "Denial" is the verdict on my open-<sup>and</sup> avowed intention of a monthly  
series! "Denial" is the verdict on my assertion that my return to society in at least one  
with the best interests of society as they <sup>found</sup> the applications of Japanese and German war criminals  
be! And "Denial" is the verdict on my children's oft-repeated request that their father  
come!

There is no more - now and then - in the slanders of downy and downy and downy and downy  
of crocodile tears for the support of a series of other people - I repeat of and downy and downy  
with the verdict; and I do nothing for - now and then - in the slanders of downy and downy and downy  
ing the fact of a denial of a series of other people - I repeat of and downy and downy and downy  
to "Denial" which consists of a series of other people - I repeat of and downy and downy and downy  
as a possible part of a record by a series of other people - I repeat of and downy and downy and downy  
which they have handed me is their certificate of illegitimacy to the name of history and downy  
oppression, the one which will be a series of other people - I repeat of and downy and downy and downy  
to the people - now and then - in the slanders of downy and downy and downy and downy

I know that their "Denial" will be a series of other people - I repeat of and downy and downy and downy  
to the people - now and then - in the slanders of downy and downy and downy and downy  
will be a series of other people - I repeat of and downy and downy and downy and downy  
to the people - now and then - in the slanders of downy and downy and downy and downy  
will be a series of other people - I repeat of and downy and downy and downy and downy  
to the people - now and then - in the slanders of downy and downy and downy and downy  
will be a series of other people - I repeat of and downy and downy and downy and downy  
to the people - now and then - in the slanders of downy and downy and downy and downy

The day when I will again be able to sit down with the people and downy and downy and downy  
discussions for downy and downy and downy and downy and downy and downy and downy  
the that day when I will again be able to sit down with the people and downy and downy and downy  
I look forward to the day when I will again be able to sit down with the people and downy and downy and downy

I look forward to the day when I will again be able to sit down with the people and downy and downy and downy

BULKY EXHIBIT

Date received 3/10/52

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent J. M. Collins

Source from which obtained See Serial 769

Address \_\_\_\_\_

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

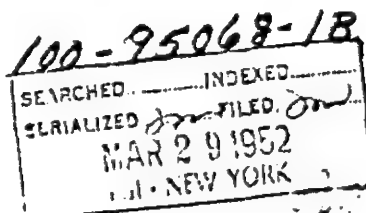
Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

155. Photostatic copy of a letter to Abraham Brothman from his wife Naomi.
156. Photostatic copy of a letter to Naomi Brothman from her husband Abraham Brothman.

(84)





Mr. Abraham Brothman #71647  
Room: Naomi Brothman, 41-08-42 St. LIC

Feb. 13th  
Wednesday

Dear Abe:

Have had no letters from you this week but what with the Holiday yesterday and the general delay this is not surprising at all. Will probably get one tomorrow.

Saw yesterday the play I wrote you before. Was greatly impressed by it this time, even more than before. I have completely forgotten what it was all about but found it even more timely now than before. I wonder if you remember it though I am sure that you do. You have such a good memory. They have changed the play somewhat but the punch is the same. By the way the part of the inquisitive boy, played formerly by our neighbor, is now played by a girl. I guess it was easier to get a girl than a boy to do this small but good part.

It has gotten very cold here again and it looks like I have caught something of a cold. In fact as soon as I finish this letter I will go home, not because I feel bad but merely as a precaution. I guess I swallowed too much cold air last night and as a result I am somewhat hoarse. However, it is nothing to worry about.

Otherwise there is very little to write about. Children are doing pretty well and behaving also pretty well. Anita still comes out with pretty funny remarks. When I reprimanded her for some or other she retorted "Well I did not turn out so well" or something to that effect. I do not know how this sounds now but it was pretty funny at the time she said that. She is a very comical character in general.

With further reference to my conversation with Joe, while this matter has not been fully settled, it is on the way and will be handled again through Goldie, as formerly.

It also seems that the Pumpkin man has written another installment of his memoirs for a big magazine. I have not read it as I would not spend a dime or whatever it is for same. You probably saw it and I understand it is quite the thing. He practically refuted the theories of science, etc. Quite a guy he turned out to be. I guess he wants to be immortal and is making sure that his opinions are recorded. Besides of course, the fee of something like 75 thousand dollars helps along. He even appeared on the radio and television.

Please excuse me for not writing more - I am going home - so again with Best Regards  
and love from the family. As ever

Naomi

Naomi Brothman

didn't qualify for an institution of higher learning, and he had to content himself with an admission to an establishment of less rigorous entrance standards, - a disappointment which sure he keenly feels! [My competence to speak for him, I'm sure you will understand, and come from that kinship between us that derives from the fact that both of us had to grow from Ivy League schools to eventually make this circuit. If indeed my residence in the halls of Columbia University taught me to forever seek the highest realms of attainment in every endeavour, I'm sure that his tenancy at Harvard, where to be sure there's a bit more of that ingenuous species <sup>(of creature)</sup> than at Columbia, must have similarly implanted in him a comparable set of standards governing his ego-expression.]

And since one thing leads to another, I see by the newspapers that that certain insurance gent is now seeking a new trial on the basis of some new evidence. Silly boy! By this time, I have learnt that facts have nothing to <sup>do with</sup> the facts! Of like Orvil Pearson, I too "predict" that will come to nothing, for the good Federal Judge who is slated to hear this thing is probably a brighter gent than the character on whose behalf the petition was filed and because of this fact dismiss the whole thing. I'm sure that this sagacious jurist, who in the first place found it in with his standards of court-entertained and court-entertainable veracity to listen the Pumpkin out, will also find that a few additional departures from the truth by that latter speaker really of small consequence; and in this judgement, I too would frankly join him, for what's about a few extra lies when the Pumpkin Man's whole story was palpably one long organism of and auditory hallucinations.

I'm afraid that the Harvard alumnus will have to complete the course for which he is enrolled; and it may be that it will do him some good, though this latest action doesn't do highly for his scholarly aptitude. He's going to have to learn to view the world in less static terms by less congealed standards. In his day and mine at school, we were taught that fiction is confined to literature and the right to tamper with even normal word-usage required a "poet's license". Well that doesn't hold anymore! In this more highly-refined culture of ours, in this of all possible civilizations, we've widened the frontiers where fiction is permitted, and when it's in court its teller, if he's on the right side, is equipped with a new kind of legal privilege, a "prosecutor's license"; and indeed it's a sorry sort of liar who doesn't make use of this new

Abraham Brothman, 71847

do even,  
He



From ABRAHAM BROTHMAN

PMB 71647, ATLANTA, GA.

To MRS. NAOMI BROTHMAN  
(Name)

THURS. EVENING

JAN. 31, 1952

(Date)

41-08 42 ST.

LONG ISLAND CITY, N.Y.  
(Address)

Dear Naomi,

Since my last writing, I've received your letters of Thurs.-Jan. 24 and Fri.-Jan. 25. In letter of Jan. 25, there came a receipt-slip for your \$20 money-order. I thank you from the my heart for this contribution to a "worthy cause"; as, as for undelined advice, to let for when the need arises, please be assured that I am affected with few if any inhibitions in the of soliciting financial assistance, and on that account you would be well-advised to be of a cessation of such solicitations. In fact, this inclination of mine to earnestly, persistently, consistently request monetary aid, believe me, is one which stands in the least need of boasting, for it, in common with my other stronger leanings, rests <sup>firmly</sup> on the on the deepest and of my intellectual convictions.

But to be serious again, Monday's letter thrilled me! I'm very happy that you enjoyed it. As I've already written, you know that I enjoyed it too. And if I haven't said this before, proud of the way you conducted yourself. I'd like to say more about the visit but I'm still too ecstatic about it to be coherent; and so, until I calm down, let me set it down. It still makes me feel good all over just to recollect it.

It's too bad that the weather was so poor while you were here. I thought in not a the Georgia Chamber of Commerce, I wouldn't be doing right by my present status as a " " permit you to go away thinking that Sunday's and Monday's weather is the usual thing it isn't; and there's a little doubt in my mind but that it was some <sup>fine</sup> weather either drifted down here by accident, or was directed here by some subversive plot to your impression of this land of sunshine and a few lesser marks of distinction. I'm sure a certain Senator had been here, that he'd join me in the latter notion and probably, <sup>some</sup> account for the whole thing. But what am I laughing at! I'd probably rank high on the names, unless there's a State Dept. official or two around. About the latter possibility, I know, for truth to tell even if there were they wouldn't reside here with me unless the <sup>former</sup> had worked them over as one State Dept. official was. And even in that one case, that

BULKY EXHIBIT

Date received 3/18/52

ABRAHAM BROTHMAN

100-95068-1 B

(Title of case)

Submitted by Special Agent J.H. Collins

Source from which obtained See Serial 770

Address \_\_\_\_\_

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 157. Photostatic copy of letter dated 1/11/52 to Abraham Brothman from Naomi Brothman.
- 158. Photostatic copy of letter dated 1/5/52 to Mrs. Naomi Brothman from Abraham Brothman.

(85)  
100-95068-1B

|                 |              |
|-----------------|--------------|
| SEARCHED.....   | INDEXED..... |
| SERIALIZED..... | FILED.....   |
| APR 29 1952     |              |
| FBI - NEW YORK  |              |

*Jim*



I have received your letter of January 3rd. I have read it very carefully and am very pleased that the work you have been doing is interesting and productive. While most of it is not very comprehensive, I can see its implications and future uses.

As far as my trip is concerned, I am somewhat at a loss to figure it out at the present time. As I have written you, I will have to travel by train - it seems that air travel now is out of question - sea conditions are bad and then I have no right to worry mother. This means a long trip by train, which will certainly not stop me. But how to spend two days in Atlanta and then another day in Washington I do not know. I was planning to take two days off - Monday and Tuesday, but this will permit me to spend two days in Atlanta. Of course, I will write for permission to the Warden but before doing this I intend to get a train schedule from Penn Station tomorrow and try and figure the connections. I am not too anxious to spend any more time in Atlanta than necessary and do not particularly feel like sight-seeing, with all due respect to Atlanta. If I could see you over the week-end twice, it would work out all right but I do not think that this will be allowed. At any rate I will have to work it out myself and will of course inform you accordingly in my next letter. Please, if it is at all possible, send out the material as soon as you can, so that if I get to Washington on Tuesday of next week, January 22nd, Mr. Bennett should have it in his possession. I will write to him for an appointment, of course.

I have been told over the phone, that there is a letter from you today addressed to Elsa. I am very pleased with that and much relieved too. While I do not wish to influence you in any way, it is very important to my way of thinking to write to the children as often as possible. I have ~~now~~ heard a few remarks from Elsa to the effect that she has written you twice but has received no reply. It is very hard to impress a child that you cannot write as often as you want to, a being quite a spirited or stubborn child cannot be confined of many things and I prefer to leave her alone, if I can at all help it. I find that too much pressure usually results in contrary results. I will write them as often as you can and always write a few lines to Anita.

I haven't spoken to Mr. Nielsen for a long time but Mr. Messing recently met him somewhere and they had a nice chat together. He mentioned that he has been getting nice letters from you. It is very hard for me to find Mr. Nielsen because I never can find him in his office. On the other hand I do not like to call him at his apartment because his wife is quite

I expect to see Goldie over the week-end and will convey to him all your recent remarks, etc. He does not get to New York too often. I will make it a point to see him this time. After all when he does come in to New York there are ~~many~~ so many ~~business~~ affairs of the sort that he has to attend to that his time is limited. I will write to you very soon and let you know of my plans, the best that I will be able to make. I will try to arrange for next week end but do not get disappointed if it will have to be the following one. You know the ~~kind~~ of nice and men. etc. So again with best regards from the family, I am

as ever

NUMBER 71647

NAME ABRAHAM BROTHMAN

If written for one inmate by another enter name and number of the actual writer in space below:

WRITTEN BY

NUMBER

Inmate's name and number must be signed at the bottom of this letter and correspond with that on this coupon.

NOTE: Do not write on reverse side of this coupon.

Letter sent to Following Address

NAME MRS. NAOMI BROTHMAN

Street and Number 71-28

City LONG ISLAND CITY, N.Y.

Relationship WIFE

DO NOT WRITE BELOW THIS LINE

Last Letter to Same Address

Total Number to Same Address

FPI-LX-11-2-50-1,100M-2-5

From ABRAHAM BROTHMAN

PHD 71647, STANZA, 40

To MRS. NAOMI BROTHMAN

(Name)

(Date)

(Address)

Dear Naomi,

Yesterday I received your letter of Wed. Dec. 2, and I trust that even as I write the Anite has already recovered from her battle with the "bug". I'm confident that this is already somehow Anite to me has always epitomized the quintessence of healthy, happy living; and it's impossible for me to conceive of any "bug" that could be evil enough to want to hurt her too much. It seems to Anite's innate charm is so great that for her to tame a most ill-intentioned "bug" into a lovely little creature would be no stupendous task, but rather a routine matter. It's just as if she had such a rough anti-itchiness; and it hurts to think of anything that would take her happy face even for a moment. By way of some compensating moments for her uncomfortable struggle with the "bug", I'll tell her that everybody here who's seen her photos - and that means just about 2000 people - has fallen in love with her. One of the quaintest things said of her was a remark by a country-boy who said that "she's got plenty of 'tickum' in her eyes". [A "tickum" is most likely a contraction of "tick" and probably connotes a coquettish quality.]

With this blend of a fervent prayer that all is now well with Libby and my confidence that you're everything under control; I turn to a request you made of me some time ago, namely that you'd like for me to comment on some of the more interesting reports appearing in the newspapers we both read. Just such an item of interest appeared in the "Times" of Sat. Dec. 30, and it concerned the conversion of the heat energy of a "nuclear reactor" to electricity. The quality which made this article so appropriate for comment by me was the noteworthiness of this achievement nor the fact that I predicted it to you some years ago, but rather as a demonstration of the art of "secretism".

A "breeder reactor" is a flamboyant name for the type of U-238 to-Plutonium-239 cycle designed for maximum neutron economy efficiency. As you may remember from my previous explanation of a breeder, it's the cycle where neutrons obtained from a controlled fission of U-235 are used to convert the non-fissionable U-238 to the man-made and fissionable element Plutonium-239. There are two factors which prompt the desirability of such a conversion: (a) the fact that the naturally found fissionable U-235 is present in very small concentrations (about 0.7% by weight) in normal uranium ore, which must be at



*[The page contains dense handwritten cursive script throughout.]*

FD-141  
(7-1-48)

BULKY EXHIBIT

Date received 6/12/52

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent J. M. Collins

Source from which obtained See Serial 774

Address \_\_\_\_\_

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit retain

List of contents:

159. Photostatic copies of letters received by subject, Brothman, at the U.S. Penitentiary, Atlanta, Georgia.

(86)

100-95068-1B

|                |         |
|----------------|---------|
| SEARCHED       | INDEXED |
| SERIALIZED     | FILED   |
| JUN 24 1952    |         |
| FBI - NEW YORK |         |

*[Signature]*



To: [illegible]  
From: [illegible]

Yesterday I received two letters from you. One to me and one to the children - this in addition to the letter of Nov. 4th. I have three letters for last week. The letter to the children is very good. Of course I will read it first to Elsie and then to Anita, depending on how she will take this. Elsie will answer this week as she is already planning a letter to you.

Your letter of Nov. 8th is kind and very appropriate. I recall I also mentioned this anniversary to you together with Anita. Life is just a succession of struggles one after another and to go on is to live and look forward to a better life.

This being "Open School Week" I visited Elsie's teacher last night and found out that she is quite pleased with Elsie. There is a lot of improvement in her work now and that she is beginning to accept school and maybe even like it. This morning I went to Anita's class and was very pleased with her behavior there. She shines among other children. Of course, I am prejudiced but I admit it. I do not particularly care for her teacher but Anita gets along with everybody. She is beginning to read and is making good advances in school.

I spoke yesterday to Clare - and she sent her love to you. She is preparing for me two sets of your articles which I will send as directed by you. She told me, among other things, that her father who is down South, visited his sister who is very well and happy and is kept very busy.

I have not heard from Goldie for a while. He is kept busy and does not come to New York too often. I will call him and find out whether there is any news there. On the other hand, you promised me to write something about your work and I have not received it as yet. Of course, it may come in one of the letters that you have written since. If not, write it if you can.

Again there is very little that I can write in addition to the above. Life I assure you is very monotonous here and there is nothing that I can complain of - absolutely none. Still there is so little of interest that I can write about in these letters. I want to assure you, however, that I appreciate your letters and the spirit in them very much. Of course I did not expect anything else but still it is very reassuring to read it. Many people feel that way too and even if one does feel that way sometimes, which is very natural, still there are many things to look forward to.

I hope that your health is good and that you are happy. I will be in New York for a while and will be in touch with you. I will be in touch with you. I will be in touch with you.

With love,  
[illegible]

Abraham Brothman  
PMB 21647, Atlanta, Ga

From Ch. H. H. 13 1951  
Hawthorne Court  
4520 4 Ave NE  
August 21, 58

Dear Abe,

I am not, this time, trying to explain how sorry  
for not meeting you before. I shall only say that  
I have been going in circles with my next move and many  
incidents and appointments. I shall talk more when  
we meet in New York.

It seems almost certain that I shall be accepting  
an appointment at Mollen Hospital. This is, to me, the  
difficult and challenging position at the time I have  
turning over my mind. It is a position for a  
year. Then, I must have to look for some  
place, again. My family has also expressed their desire  
to stay in New York, on the condition that we are able  
to find an apartment near the hospital. My daughter  
is very anxiously that she wants to see me as often  
possible as well as much as possible. As soon as  
I can find a place to live, I will resign from my  
present position. Dr. Howard Rusk as a kindly experienced  
light in having me on the staff. He seems to be  
the type of a personality I want to work with, because  
he has an intensive desire to help his patients and he  
has a healthy interpretation of the chaplain's work.

In making this decision you also came into the  
picture. I am fully aware of the fact that I have not  
been as much help to you and your family as  
much I could be while you have been away. Now



...has developed into a mutual  
...looking forward to the day when we can  
...in New York as you at the first  
...with your friends in the prison yard. Will  
...about these experiences. I have not had  
...and it has always been under some mor-  
...strain. In spite of this I have always  
...have a genuine warmth for people, and  
...I felt your deep concern for your  
...with them behind the  
...I wish to see more of you -  
...I don't wish to sound like a sentimentalist for  
...in this circle of my acquaintance  
...and feeling for  
...to see you frequent  
...it is a strong mutual  
...when you can spare  
...I think your wife said  
...is in place 212

must also add that my stay in New York will give me  
...to continue with her doctor for another year  
...baked the first cake of  
...the only cake I did not like  
...and all. She is a great comfort  
...for me. He does my  
...I hope you are able to keep up the good spirit  
...in your letters to both me and your  
...with my heartiest greeting, with best wishes  
Chaplain, 23rd St. Station, 23rd St.  
Norwegian Lutheran Hospital  
4520 4th Ave Brooklyn 20, N.Y.

To: Abraham  
From: Naomi

Friday  
May 9th

Dear Abe:

Received your letter and was very pleased to have answers to my questions even before my letter reached you. I am very glad that you are getting along in sports and otherwise. I was also glad to see that you have been making resolutions about acquired habits and that you intend to continue ~~xxx~~ to live with them in the future. These are very encouraging news as you know so strongly I feel about these things and how much I have talked and about them in the past.

I was also pleased with the promises you made to Anita and also hope that you intend to honor them in the future. I have wanted to write and to talk to you about these things before but unfortunately, when I saw you, we never had any time. I have always wanted to bring it up but somehow never did do it. As you have now plenty of time to think things over, you must recall a lot of situations and many conversations that we have had in the past about personal matters, which I believe, I was on the right track and not you. You must realize that you can rationalize and verbalize much better than I and, while you never convinced me that I was wrong, things went on the way you were shaping them. Of course I realize the cause of all but still in all certain situations will have to be changed and eliminated. Unfortunately we cannot go into this in our letters and I do hope that we will have time to discuss it next time when I see you. But in the meantime I do hope you will give it consideration as I am sure that you are well aware of what I mean. You remember the song you used to sing about "resolutions on paper". Well another dictum of yours was always about theory and practice. So I do hope that all your theoretical resolutions will have practical applications and that you are making plans along these directions. I do not want to go into this any further and have only written the above because you gave me an opening about your habits and about your intentions to live with the better ones in the future.

I saw Mr. Nielsen yesterday and have conveyed to him what we have discussed. I think that for the present it would be best that he writes first. Then this can be followed up by a visit, if necessary. What do you think about it. He will write you directly.

I spoke to Clara yesterday too. She has received a letter from you and has written you this week in reply. I am arranging to see her in the very near future that I am able - so that will take care of your request.

I know that there is a letter at home from you - probably of last Sunday - I will answer same during the week-end - probably tomorrow, I hope. Otherwise, there is nothing new to write - the children are all right and busy. Otherwise there is nothing new to write about. I am still, as always, attending to everything that is to do and will keep you posted about any new development.

So again with Best Regards and love from the Family, I am

As ever



BULKY EXHIBIT - INVENTORY OF PROPERTY ACQUIRED AS EVIDENCE

Bureau New York Field Division  
Various Date

Title and Character of Case:

ABRAHAM BROTHMAN  
100-95068-1B

Date Property Acquired: See below

Source From Which Property Acquired: See below

Location of Property or Bulky Exhibit: In Vault

Reason for Retention of Property and Efforts Made to Dispose of Same: Evidence & Information

Description of Property or Exhibit and Identity of Agent Submitting Same: See below

160. The photostat of letter from Subject to Chaplain E.B. NIELSEN, 8703 3rd Ave., Brooklyn 9, NY dated 7/10/52. - See serial 780

File #:

100-95068-1B

|                |         |
|----------------|---------|
| SEARCHED       | INDEXED |
| SERIALIZED     | FILED   |
| SEP 30 1952    |         |
| FBI - NEW YORK |         |

10/1/52

From ABRAHAM BROTHMAN  
P.M.B. 71047, ATLANTA, GA.

To CHAPLAIN B. B. NIELSEN  
(Name)

THURS. EVENING

JULY 10, 1922

8703 - 5 AVE

BROOKLYN, 7, NEW YORK  
(Address)

Dear Bjorn,

It's my guess that by the time that this letter comes, Europe will be in the grip of a hot summer. I hope that she'll have just the kind of a summer vacation that she's had in the past - so very important that a child's life is a vacation, for now and for later on.

I'm mindful as I think of Evelyn leaving off on her vacation of the two summer vacations country that I had as a child. I thrill to the recollection of those weeks today even as I did then. They stand today in a different framework of experience than they did then. What was a matter of adventure then is a matter of humor today; and what only vaguely troubled me then stands out in clear relief today.

From the cool-laden air and the nondescript greyness of a New York ghetto to the blue sky and the rich greenness of the countryside was a bigger trip than the four hours that he had told of. Only a journey thru celestial space could encompass such a change; and so unexpected for the voyage were certainly no less in scope or magnitude than those Peary had made for the Pole. All things were taken into account: - the possibility of a monstrous change in the weather; a first-aid kit to deal with bloody emergencies; and of course an ample supply of sandwiches and a thermos-jug of coffee. This was a small but a very important supply of things of the first dimension accompanied us in the baggage-car of the train. This latter 'supply dump', packed with a dozen borrowed travelling-grips and an ancient trunk that happened to belong to me, took even more account; everything that the imagination could conjure up. And the imagination of a ghetto people in a big city knows no limit!

A thousand years of adventure were crowded into approximately five hours: - a ferry-boat to a distant land known as Weclawton, New Jersey; and then an honest-to-goodness locomotive-powered train belonging to the ostentatiously-named New York, Westchester, and Connecticut Railroad. Our destination? A frontier-land in the Catskills, Ellenville by name. Even as I write of it now it seems to me that I can still feel the sweep of the wind against my face as I stood on the point on the ferry-boat's deck. A month of anticipation of this journey and the morning of



of excitement that accompanied the approach of D-L turned the hot New York August into a Arctic blast. In my vivid imagination, I steered this mighty ocean-prowling luxury into its home-port at Weehawken with bold twists in this and then in that direction of travel. In that ten-minute ride from West 42 St. to Weehawken, all of the rides I had previously taken on the top-deck of a double-decker Fifth Avenue Buses in their totality were dwarfed by this experience. Nor was a boat-ride on the main Central Park lake to be compared to this or on the vast expanse of the Hudson River! The ghetto knew a boundary, I had learned, and that horizon lay at West 42 St. in Manhattan.

In the years since this event took place, a mighty torrent of hours and pages have been in an almost never-ceasing endeavor to place the concept of the 'infinite' within an ultimate definition; but even today I've nothing but a few devices - of - mathematical convenience by which to make this momentous projection. But what has for good and sufficient reason escaped my (and all else's) intellect as a hard and fast physical concept has been known to me on an intuitive level ever since the day I boarded the country-bound train at Weehawken. An eternity, an infinite time, is still the length of time it took for that train to get started. I can't remember much that happened from then on until we arrived at Ellenville because a cruel fate, to my everlasting grief, caused <sup>me</sup> to fall asleep on the train; and, tired by the accumulated nervous strains, slumbered almost all of the trip. But Ellenville will always stand for me as my first rendezvous with extravagance, for it was at Ellenville Station that we sent a telegram to my Father assuring him that we had safely and soundly survived the rigours of our ghetto-shattering journey. The Brother - Mother, daughter, and son -, carefully worded a message to be whipped across the long line up until that moment had - so far as we knew - served <sup>only</sup> the whims of the makaregale of finance.

I was destined in the years to come to roam <sup>some goodly portion of</sup> the <sup>the</sup> skies of two hemispheres, and - in some almost all of the ghetto's chains have since been broken; but the day on which I first slipped the ghetto's fortress walls still lives on with a freshness I guess it will never lose.

A 'bon voyage' to Evelyn Horne, even though a belated one, and my very best wishes you and Mrs. Nielsen for the happiest kind of a summer! I hope that these reminiscences bored you. In an indirect way, they'll at least convey why I've always hated poverty and residence, a ghetto.

Abraham Brothman, 71647 Yours-in-friendship,  
Abc